Recap of the Last Class

- **Hardware protection**
  - kernel and user mode
- **System components**
  - process management, memory management, I/O system, file and storage, networking, ...
- **Operating system architectures**
  - monolithic architecture, microkernel
  - ...

Microkernel System Architecture

- **Microkernel architecture:**
  - Moves as much from the kernel into "user" space (still protected from normal users).
  - Communication takes place between user modules using message passing.
- **Benefits:**
  - More reliable (less code is running in kernel mode)
  - More secure (less code is running in kernel mode)
- **Disadvantage:**
  - More overhead in inter-domain communications

Layered Structure

- **Layered structure**
  - The operating system is divided into a number of layers (levels), each built on top of lower layers.
  - The bottom layer (layer 0), is the hardware.
  - The highest (layer N) is the user interface.
  - Decreased privileges for higher layers.
- **Benefits:**
  - more reliable
  - more secure
- **Disadvantage:**
  - Weak integration results in performance penalty (similar to the microkernel structure).
Outline

- **Process**
  - Process concept
  - A process's image in a computer
  - Operations on processes

- **Thread**
  - Thread concept
  - Multithreading models
  - Types of threads

Process and Its Image

- An operating system executes a variety of programs:
  - A program that browses the Web
  - A program that serves Web requests

- Process - a program in execution.

- A process’s state/image in a computer includes:
  - User-mode address space
  - Kernel data structure
  - Registers (including program counter and stack pointer)

Address space and memory protection

- Physical memory is divided into user memory and kernel memory
- Kernel memory can only be accessed when in the kernel mode
- Each process has its own exclusive address space in the user-mode memory space (sort-of)

User-mode Address Space

User-mode address space for a process:

- **Text**: program code, instructions
- **Data**: initialized global and static variables (those data whose size is known before the execution)
- **BSS** (block started by symbol): uninitialized global and static variables
- **Heap**: dynamic memory (those being malloc-ed)
- **Stack**: local variables and other stuff for function invocations

Process Control Block (PCB)

OS data structure (in kernel memory) maintaining information associated with each process:

- Process state
- Program counter
- CPU registers
- CPU scheduling information
- Memory-management information
- Accounting information
- Information about open files
- maybe kernel stack?
**Process State**

- As a process executes, it changes state:
  - **new**: The process is being created.
  - **ready**: The process is waiting to be assigned to a process.
  - **running**: Instructions are being executed.
  - **waiting**: The process is waiting for some event to occur.
  - **terminated**: The process has finished execution.

**Process Creation**

- When a process (parent) creates a new process (child):
  - Execution sequence?
  - Address space sharing?
  - Open files inheritance?
  - ... ...

- UNIX examples:
  - `fork` system call creates new process with a duplicated copy of everything.
  - `exec` system call used after a `fork` to replace the process' memory space with a new program.
  - child and parent compete CPU like two normal processes.

- **Copy-on-write**

**Process Tree on a Linux System**

- Parent process creates children processes, which, in turn create other processes, forming a tree of processes.

**CPU Switch From Process to Process**

- When can the OS switch the CPU from one process to another?
- Which one to switch to? - scheduling
Queues for PCBs

- Ready queue – set of all processes ready for execution.
- Device queues – set of processes waiting for an I/O device.
- Process migration between the various queues.

Process Termination

- Process executes last statement and gives the control to the OS (exit).
  - Notify parent if it is waiting.
  - Deallocate process’ resources.
- The OS may forcefully terminate a process.
  - Software exceptions
  - Receiving certain signals

Processes and Threads

- Thread – a program in execution; without a dedicated address space.
- OS memory protection is only applied to processes.

Why Use Threads?

- Multithreading is used for parallelism/concurrency. But why not multiple processes?
  - Memory sharing.
  - Efficient synchronization between threads
  - Less context switch overhead
User/Kernel Threads

- What is really happening when the execution of one thread switches to another?
  - save the registers (including the SP) of the old thread;
  - restore the registers of the new thread;
  - set the new PC appropriately for the new thread;

- Does this need help from the OS kernel?
- Can you do it in C/Java?
- Does process switching need help from the OS kernel?

User threads
- Thread data structure is in user-mode memory
- Scheduling/switching done at user mode

Kernel threads
- Thread data structure is in kernel memory
- Scheduling/switching done by the OS kernel

User/Kernel Threads (cont.)

- Benefits of user threads
  - lightweight - less context switching overhead
  - more efficient synchronization??
  - flexibility - allow application-controlled scheduling

- Problems of user threads
  - can’t use more than one processor
  - oblivious to kernel events, e.g., all threads in a process are put to wait when only one of them does I/O

Mixed User/Kernel Threads

- M user threads run on N kernel threads (M≥N)
  - N=1: pure user threads
  - M=N: pure kernel threads
  - M>N>1: mixed model

  \[ \text{user threads} \]

  \[ \text{kernel threads} \]

  \[ \text{CPU} \quad \text{CPU} \]

Solaris/Linux Threads

- Solaris
  - supports mixed model

- Linux
  - No standard user threads on Linux
  - Processes are treated similarly with threads (both called tasks)
  - Processes are tasks with exclusive address space
  - Tasks can also share the address space, open files, ...
Pthreads

- Different OS has its own thread package with different Application Programming Interfaces ⇒ poor portability.
- Pthreads
  - A POSIX standard API for thread management and synchronization.
  - API specifies behavior of the thread library, not the implementation.
  - Commonly supported in UNIX operating systems.

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