

Machine-Level Programming II: Arithmetic & Control

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Outline

- Arithmetic operations
- Control: Condition codes
- Conditional branches
- Loops
- Switch

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Some Arithmetic Operations

- Two Operand Instructions:

| Format | Computation | |
|-----------------|--------------------|------------------|
| addl Src, Dest | Dest = Dest + Src | |
| subl Src, Dest | Dest = Dest - Src | |
| imull Src, Dest | Dest = Dest * Src | |
| sall Src, Dest | Dest = Dest << Src | Also called shll |
| sarl Src, Dest | Dest = Dest >> Src | Arithmetic |
| shrl Src, Dest | Dest = Dest >> Src | Logical |
| xorl Src, Dest | Dest = Dest ^ Src | |
| andl Src, Dest | Dest = Dest & Src | |
| orl Src, Dest | Dest = Dest Src | |

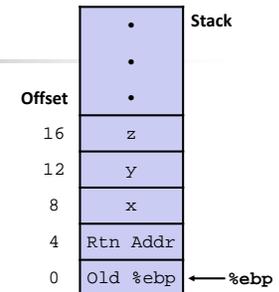
- One Operand Instructions

| | |
|-----------|-----------------|
| incl Dest | Dest = Dest + 1 |
| decl Dest | Dest = Dest - 1 |
| negl Dest | Dest = - Dest |
| notl Dest | Dest = ~Dest |

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Arithmetic Example

```
int arith(int x, int y, int z)
{
    int t1 = x+y;
    int t2 = z+t1;
    int t3 = x+4;
    int t4 = y * 48;
    int t5 = t3 + t4;
    int rval = t2 * t5;
    return rval;
}
```



```
movl 8(%ebp), %ecx # ecx = x
movl 12(%ebp), %edx # edx = y
leal (%edx,%edx,2), %eax # eax = y*3
sall $4, %eax # eax *= 16 (t4)
leal 4(%ecx,%eax), %eax # eax = t4 +x+4 (t5)
addl %ecx, %edx # edx = x+y (t1)
addl 16(%ebp), %edx # edx += z (t2)
imull %edx, %eax # eax = t2 * t5 (rval)
```

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Processor State (IA32, Partial)

- Information about currently executing program
 - Temporary data (%eax, ...)
 - Location of runtime stack (%ebp, %esp)
 - Location of current code control point (%eip, ...)
 - Status of recent tests (CF, ZF, SF, OF)

| | | | | |
|------|-----------------------------|----|----|-----------------|
| %eax | } General purpose registers | | | |
| %ecx | | | | |
| %edx | | | | |
| %ebx | | | | |
| %esi | | | | |
| %edi | | | | |
| %esp | Current stack top | | | |
| %ebp | Current stack frame | | | |
| %eip | Instruction pointer | | | |
| CF | ZF | SF | OF | Condition codes |

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Condition Codes (Arithmetic Setting)

- Single bit registers
 - CF Carry Flag (for unsigned) SF Sign Flag (for signed)
 - ZF Zero Flag OF Overflow Flag (for signed)
- Set by arithmetic operations

Example: `addl / addq Src, Dest` \leftrightarrow `t = a+b`

 - CF set if carry out from most significant bit (unsigned overflow)
 - ZF set if `t == 0`
 - SF set if `t < 0` (as signed)
 - OF set if two's-complement (signed) overflow (`a>0 && b>0 && t<0`) || (`a<0 && b<0 && t>=0`)
- Not set by `leal` instruction

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Condition Codes (Setting by Compare)

- Setting by compare instruction
 - `cmpl Src2, Src1`
 - `cmpl b, a` like computing `a-b` without setting destination
- CF set if carry out from most significant bit (used for unsigned comparisons)
- ZF set if `a == b`
- SF set if `(a-b) < 0` (as signed)
- OF set if two's-complement (signed) overflow (`a>0 && b<0 && (a-b)<0`) || (`a<0 && b>0 && (a-b)>0`)

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Condition Codes (Setting by Test)

- Setting by Test instruction
 - `testl Src2, Src1`
`testl b, a` like computing `a&b` without setting destination
 - Sets condition codes based on value of `Src1` & `Src2`
 - Useful to have one of the operands be a mask
 - ZF** set when `a&b == 0`
 - SF** set when `a&b < 0`

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Reading Condition Codes

- SetX Instructions:
 - Set single byte based on combination of condition codes
 - One of 8 addressable byte registers
 - Does not alter remaining 3 bytes
 - Typically use `movzbl` to finish job

```
int gt (int x, int y)
{
    return x > y;
}
```

```
movl 12(%ebp),%eax # eax = y
cmpl %eax,8(%ebp) # Compare x : y
setg %al          # al = x > y
movzbl %al,%eax  # Zero rest of %eax
```

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Reading Condition Codes

- SetX instructions
 - Set single byte based on combinations of condition codes

| SetX | Condition | Description |
|--------------------|----------------|---------------------------|
| <code>sete</code> | ZF | Equal / Zero |
| <code>setne</code> | ~ZF | Not Equal / Not Zero |
| <code>sets</code> | SF | Negative |
| <code>setns</code> | ~SF | Nonnegative |
| <code>setg</code> | ~(SF^OF) & ~ZF | Greater (Signed) |
| <code>setge</code> | ~(SF^OF) | Greater or Equal (Signed) |
| <code>setl</code> | (SF^OF) | Less (Signed) |
| <code>setle</code> | (SF^OF) ZF | Less or Equal (Signed) |
| <code>seta</code> | ~CF & ~ZF | Above (unsigned) |
| <code>setb</code> | CF | Below (unsigned) |

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Jumping

- jX Instructions
 - Jump to different part of code depending on condition codes

| jX | Condition | Description |
|-----|----------------|---------------------------|
| jmp | 1 | Unconditional |
| je | ZF | Equal / Zero |
| jne | ~ZF | Not Equal / Not Zero |
| js | SF | Negative |
| jns | ~SF | Nonnegative |
| jg | ~(SF^OF) & ~ZF | Greater (Signed) |
| jge | ~(SF^OF) | Greater or Equal (Signed) |
| jl | (SF^OF) | Less (Signed) |
| jle | (SF^OF) ZF | Less or Equal (Signed) |
| ja | ~CF & ~ZF | Above (unsigned) |
| jb | CF | Below (unsigned) |

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Conditional Control

- In assembly/machine code, jump is pretty much all we got
- But there are a variety of conditional control in high-level languages
 - if ... else ...
 - switch(...) {}
 - while loop
 - for loop
 -

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Conditional Branch Example

```
int absdiff(int x, int y)
{
    int result;
    if (x > y) {
        result = x-y;
    } else {
        result = y-x;
    }
    return result;
}
```

```
absdiff:
    pushl %ebp
    movl %esp, %ebp
    movl 8(%ebp), %edx
    movl 12(%ebp), %eax
    cmpl %eax, %edx
    jle .L6
    subl %eax, %edx
    movl %edx, %eax
    jmp .L7
.L6:
    subl %edx, %eax
.L7:
    popl %ebp
    ret
```

} Setup

} Body1

} Body2a

} Finish

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Conditional Branch Example (Cont.)

```
int goto_ad(int x, int y)
{
    int result;
    if (x <= y) goto Else;
    result = x-y;
    goto Exit;
Else:
    result = y-x;
Exit:
    return result;
}
```

```
absdiff:
    pushl %ebp
    movl %esp, %ebp
    movl 8(%ebp), %edx
    movl 12(%ebp), %eax
    cmpl %eax, %edx
    jle .L6
    subl %eax, %edx
    movl %edx, %eax
    jmp .L7
.L6:
    subl %edx, %eax
.L7:
    popl %ebp
    ret
```

} Setup

} Body1

} Body2a

} Body2b

} Finish

- Better resemblance to “goto”-style C code
- Bad coding style, but that’s not our concern here

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Using Conditional Moves

- Conditional move instructions
 - if (Test) Dest ← Src
- Why?
 - Branches are very disruptive to instruction flow through pipelines
 - Cond-mov require no control transfer

C Code

```
val = Test
  ? Then_Expr
  : Else_Expr;
```

Cond-mov Version

```
tval = Then_Expr;
result = Else_Expr;
t = Test;
if (t) result = tval;
return result;
```

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Loop Control

- In assembly/machine code, jump is pretty much all we got for conditional control (similar to “goto” in C)
- Convert typical loop control into goto-based C code.
 - Familiarize with assembly/machine programming
 - Understand compiler transformation
 - Able to read/comprehend assembly/machine code

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“Do-While” Loop Example

C Code

```
int pcount_do(unsigned x)
{
  int result = 0;
  do {
    result += x & 0x1;
    x >>= 1;
  } while (x);
  return result;
}
```

Goto Version

```
int pcount_do(unsigned x)
{
  int result = 0;
loop:
  result += x & 0x1;
  x >>= 1;
  if (x)
    goto loop;
  return result;
}
```

- Count number of 1’s in argument x
- Use conditional branch to either continue looping or to exit loop

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"Do-While" Loop Compilation

Goto Version

```
int pcount_do(unsigned x) {
    int result = 0;
loop:
    result += x & 0x1;
    x >>= 1;
    if (x)
        goto loop;
    return result;
}
```

Registers:
 %edx x
 %ecx result

```
movl $0, %ecx # result = 0
.L2: # loop:
movl %edx, %eax
andl $1, %eax # t = x & 1
addl %eax, %ecx # result += t
shrl %edx # x >>= 1
jne .L2 # If !0, goto loop
```

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General "Do-While" Translation

C Code

```
do
    Body
while (Test);
```

Goto Version

```
loop:
    Body
    if (Test)
        goto loop
```

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General "While" Translation

While version

```
while (Test)
    Body
```

Do-While Version

```
if (!Test)
    goto done;
do
    Body
while (Test);
done:
```

Goto Version

```
if (!Test)
    goto done;
loop:
    Body
    if (Test)
        goto loop;
done:
```

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General "For" Translation

For Version

```
for (Init; Test; Update)
    Body
```

While Version

```
Init;
while (Test) {
    Body
    Update;
}
```

Do-While Version

```
Init;
if (!Test)
    goto done;
do
    Body
    Update
while (Test);
done:
```

Goto Version

```
Init;
if (!Test)
    goto done;
loop:
    Body
    Update
    if (Test)
        goto loop;
done:
```

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“For” Loop Conversion Example

C Code

```

#define WSIZE 8*sizeof(int)
int pcount_for(unsigned x) {
    int i;
    int result = 0;
    for (i = 0; i < WSIZE; i++) {
        unsigned mask = 1 << i;
        result += (x & mask) != 0;
    }
    return result;
}
                
```

- Initial test can be optimized away

Goto Version

```

int pcount_for_gt(unsigned x) {
    int i;
    int result = 0;
    i = 0;
    if (!(i < WSIZE)) !Test
        goto done;
loop:
    {
        unsigned mask = 1 << i;
        result += (x & mask) != 0;
    }
    i++;
    if (i < WSIZE) Test
        goto loop;
done:
    return result;
}
                
```

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Switch Statement

```

long switch_eg
(long x, long y, long z)
{
    long w = 1;
    switch(x) {
    case 1:
        w = y*z;
        break;
    case 2:
        w = y/z;
        /* Fall Through */
    case 3:
        w += z;
        break;
    case 5:
    case 6:
        w -= z;
        break;
    default:
        w = 2;
    }
    return w;
}
                
```

- An example
 - Multiple case labels (5 & 6)
 - Fall through case (2)
 - Missing case (4)
- How to implement switch statement in machine code?
 - Using jumps (or “goto”)
- Jump table avoids sequencing through cases
 - constant time, rather than linear

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Jump Table Structure

Switch Form

```

switch(x) {
case val_0:
    Block 0
case val_1:
    Block 1
    . . .
case val_n-1:
    Block n-1
}
                
```

Jump Table

```

jtab: Targ0
     Targ1
     Targ2
     .
     .
     Targn-1
                
```

Jump Targets

```

Targ0: Code Block 0
Targ1: Code Block 1
Targ2: Code Block 2
.
.
Targn-1: Code Block n-1
                
```

Approximate Translation

```

target = JTab[x];
goto *target;
                
```

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Switch Statement Example (IA32)

```

long switch_eg(long x, long y, long z)
{
    long w = 1;
    switch(x) {
        . . .
    }
    return w;
}
    
```

Jump table

```

.section .rodata
.align 4
.JT:
.long .L2 # x = 0
.long .L3 # x = 1
.long .L4 # x = 2
.long .L5 # x = 3
.long .L2 # x = 4
.long .L6 # x = 5
.long .L6 # x = 6
    
```

Setup:

```

switch_eg:
    pushl %ebp          # Setup
    movl  %esp, %ebp    # Setup
    movl  8(%ebp), %eax  # eax = x
    cmpl  $6, %eax      # Compare x:6
    ja   .L2            # If unsigned > goto default
    Indirect jump → jmp *.JT(,%eax,4) # Goto *JTab[x]
    
```

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Jump Table

```

.section .rodata
.align 4
.JT:
.long .L2 # x = 0
.long .L3 # x = 1
.long .L4 # x = 2
.long .L5 # x = 3
.long .L2 # x = 4
.long .L6 # x = 5
.long .L6 # x = 6
    
```

```

switch(x) {
case 1: // .L3
    w = y*z;
    break;
case 2: // .L4
    w = y/z;
    /* Fall Through */
case 3: // .L5
    w += z;
    break;
case 5:
case 6: // .L6
    w -= z;
    break;
default: // .L2
    w = 2;
}
    
```

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Discover Jump Table in Machine Code

- First, find the address of the jump table

Disassembled Object Code

```

08048410 <switch_eg>:
. . .
8048419: 77 07          ja      8048422 <switch_eg+0x12>
804841b: ff 24 85 60 86 04 08 jmp     *0x8048660(,%eax,4)
    
```

- Then read into the jump table
- But the table doesn't show up in disassembled code
- Can inspect using GDB: `x/7xw 0x8048660`
 - Examine `Z` hexadecimal format "`w`words" (4-bytes each)
 - Use command "`help x`" to get format documentation

```

0x8048660:  0x08048422  0x08048432  0x0804843b  0x08048429
0x8048670:  0x08048422  0x0804844b  0x0804844b
    
```

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Matching Disassembled Targets

| Value | Disassembly |
|-----------|------------------------------|
| 0x8048422 | mov \$0x2,%eax |
| 0x8048427 | jmp 8048453 <switch_eg+0x43> |
| 0x8048429 | mov \$0x1,%eax |
| 0x804842e | xchg %ax,%ax |
| 0x8048430 | jmp 8048446 <switch_eg+0x36> |
| 0x8048432 | mov 0x10(%ebp),%eax |
| 0x8048435 | imul 0xc(%ebp),%eax |
| 0x8048439 | jmp 8048453 <switch_eg+0x43> |
| 0x804843b | mov 0xc(%ebp),%edx |
| 0x804843e | mov %edx,%eax |
| 0x8048440 | sar \$0x1f,%edx |
| 0x8048443 | idivl 0x10(%ebp) |
| 0x8048446 | add 0x10(%ebp),%eax |
| 0x8048449 | jmp 8048453 <switch_eg+0x43> |
| 0x804844b | mov \$0x1,%eax |
| 0x8048450 | sub 0x10(%ebp),%eax |
| 0x8048453 | pop %ebp |
| 0x8048454 | ret |

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Summary on Execution Control

- Control in high-level language
 - if-then-else
 - do-while
 - while, for
 - switch
- Control in machine code
 - Conditional jump
 - Conditional move
 - Indirect jump
 - Compiler generates code sequence to implement more complex control
- Standard techniques
 - Loops converted to go-to form
 - Large switch statements use jump tables
 - Sparse switch statements may use decision trees

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Disclaimer

These slides were adapted from the CMU course slides provided along with the textbook of "Computer Systems: A programmer's Perspective" by Bryant and O'Hallaron. The slides are intended for the sole purpose of teaching the computer organization course at the University of Rochester.

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