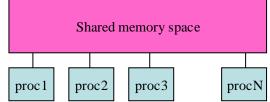
#### Shared Memory: More on Coherence and Consistency

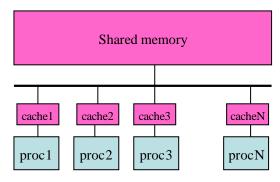
Sandhya Dwarkadas University of Rochester

# What is Shared Memory?

Shared memory: Memory that may be simultaneously accessed by two or more processing elements



### Coherent Shared Memory: A Look Underneath



# Shared Memory Implementation

- Coherence defines the behavior of reads and writes to the same memory location
  - ensuring that modifications made by a processor propagate to all copies of the data
  - Program order preserved
  - Writes to the same location by different processors serialized
- · Synchronization coordination mechanism
- Consistency defines the behavior of reads and writes with respect to access to other memory locations
  - defines when and in what order modifications are propagated to other processors

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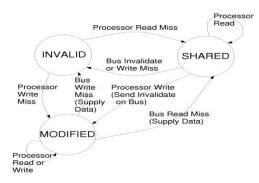
### Coherence

- A multiprocessor memory system is coherent if the results of any execution of a program are such that, for each location, it is possible to construct a hypothetical serial order of all operations to the location that is consistent with the result of the execution and ensure that
  - modifications made by a processor propagate to all copies of the data (write propagation)
  - operations by each process occur in the order in which they were issued to the memory system by the process
  - writes to the same location by all processors are serialized (write serialization) and the value returned by each read is the value written by the last write in the hypothetical order

### **Snoop-Based Coherence**

- Makes use of a shared broadcast medium to serialize events (all transactions visible to all controllers and in the same order)
  - Write update-based protocol
  - Write invalidate-based (e.g., basic MSI, MESI protocols)
- Cache controller uses a finite state machine (FSM) with a handful of stable states to track the status of each cache line
- Consists of a distributed algorithm represented by a collection of cooperating FSMs

### A Simple Invalidate-Based Protocol - State Transition Diagram



### **Correctness Requirements**

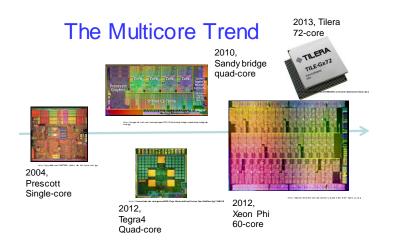
- · Need to avoid
  - Deadlock caused by a cycle of resource dependencies
  - Livelock activity without forward progress
  - Starvation extreme form of unfairness where one or more processes do not make forward progress while others do

# **Design Challenges**

- Cache controller and tag design
- Non-atomic state transitions
- Serialization
- · Cache hierarchies
- Split-transaction buses

# Multicore Processors Everywhere



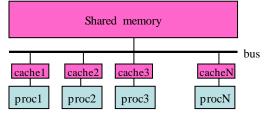


# Scaling Challenges

- Bandwidth and shared resource contention
- Non-uniform memory access
- Power/energy efficiency
- Scalable coherence implementation

# Snoop-Based or Broadcast Coherence

- Make use of a broadcast medium to manage replicas
- Benefit: Low metadata requirements
- Challenge: High bandwidth requirements



### **Directory-Based Coherence**

- Distribute memory, use point-to-point interconnect for scalability
- Need to manage coherence for each memory line – state stored in directory
  - Simple memory-based (e.g., DASH, FLASH, SGI Origin, MIT Alewife, HAL)
  - Cache-based (linked list (e.g., Sequent NUMA-Q, IEEE SCI)

#### Solution: Directory-based Cache Coherence

Directory: maintain per-core sharer information to save bandwidth

Full map: associate sharing vector with tags of shared L2

| Block A<br>tag Data<br>P0                | Bloc<br>tag<br>P                | Data                                   | Block<br>tag<br>P2                        | Data | Block C<br>tag Data<br>P3 |
|--|---------------------------------|--|---|------|---------------------------|
| Block A<br>Block B<br>Block C<br>Block D | tag<br>tag<br>tag<br>tag<br>tag | Data<br>Data<br>Data<br>Data<br>ory /S | 1000<br>0110<br>0001<br>0000<br>hared cae | che  |                           |

### Multiprocessor Interconnects

- Topology
- · Routing algorithm
- Switching strategy (circuit vs. packet)
- · Flow control mechanism

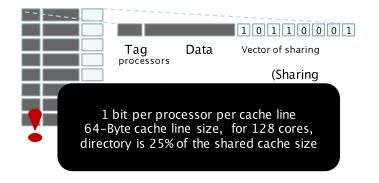
### Interconnect Topologies

- · Fully connected
  - Single large switch
  - Bus
- · Linear arrays and rings
- · Multi-dimensional meshes and tori
- Trees
- Butterflies
- Hypercube

#### Simple Memory-based Directory Coherence

- Advantage
  - Precise sharing information
- Disadvantage
  - Space/storage proportional to PxM
- · Work-around for either width or height
  - Increase cache block size
  - 2-level protocol
  - Limited pointer scheme
  - Directory cache

#### **Conventional Full Map Directory**



#### **Cache-Based Directory Coherence**

- Home main memory contains a pointer to the first sharer + state bits
- Pointers at each cache line to maintain a doubly-linked list
- Advantage reduced space overhead
- Disadvantage serialized invalidates (latency and occupancy)

### Basic Hardware Mechanisms for Synchronization

- Test-and-set atomic exchange
- Fetch-and-op (e.g., increment) returns value and atomically performs op (e.g., increments it)
- Compare-and-swap compares the contents of two locations and swaps if identical
- Load-locked/store conditional pair of instructions – deduce atomicity if second instruction returns correct value

# Memory Consistency Model

 Specifies constraints on the order in which memory operations to different locations must appear to be performed with respect to one another

### Sequential Consistency

- ``A system is sequentially consistent if the result of any execution is the same as if the operations of all the processors were executed in some sequential order, and the operations of each individual processor appear in this sequence in the order specified by its program." [Lamport 79]
  - In practice, this means that every write must be seen on all processors before any succeeding read or write can be issued

### Implications

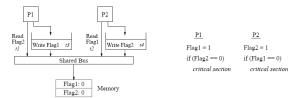
· Program order P1 P2 A = 1; while (flag == 0);flag = 1;print A; · Write atomicity P2 **P**3 P1 A = 1: while (A == 0); while (B == 0); B = 1; print A;

### Dekker's Algorithm

Can B = 0 at P1 and A = 0 at P2 at the corresponding if statements?

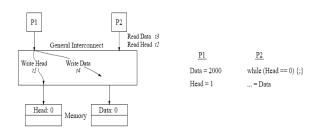
### Write Buffers [Bypassing Capability]

· Reads bypass writes, reads are blocking



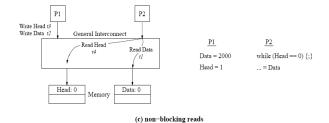
**Overlapping Write Operations** 

· Writes may bypass other writes in write buffer



#### Non-blocking Reads

Reads are allowed to bypass reads and writes



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### Drawbacks of Sequential Consistency

- SC restricts any compiler optimization that can result in reordering memory operations
  - Code motion, register allocation, common subexpression elimination, loop blocking, software pipelining
- SC restricts hardware generated memory re-orderings because of program-order and write-atomicity requirements
  - Write Buffers, OOO instruction issue, pipelining of memory operations, lock-up free caches, non-atomic memory operations
- · Potential performance penalties from the above

#### Memory Model Relaxations

- Possible relaxations
  - -Write \_\_\_ Read
  - -Write → Write
  - -Read Read, Write
  - Read other's write early
  - Read own write early
- All Models provide some Safety net (memory fence/ordering instructions or prefixes)
- All models maintain uni-processor data and control dependencies
- Write serialization is maintained by all the models except PC, RCpc, PowerPC [for most practical purposes where all processors observe all write operations in the same order (write serialization), is indistinguishable from a system where all writes are executed atomically]

#### Categorization of Relaxed Models

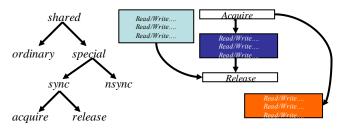
| Relaxation: | W →R<br>Order | W →W<br>Order | R →RW<br>Order | Read Others'<br>Write Early | Read Own<br>Write Early | Safety Net                      |
|-------------|---------------|---------------|----------------|-----------------------------|-------------------------|---------------------------------|
| IBM 370     | ~             |               |                |                             |                         | serialization<br>instructions   |
| TSO         | ~             |               |                |                             | ~                       | RMW                             |
| PC          | ~             |               |                | √                           | ~                       | RMW                             |
| PSO         | ~             | ~             |                |                             | ✓                       | RMW, STBAR                      |
| wo          | ~             | ~             | ~              |                             | ~                       | synchronization                 |
| RCsc        | ~             | ~             | ~              |                             | ~                       | release, acquire,<br>nsync, RMW |
| RCpc        | ~             | ~             | ~              | √                           | ~                       | release, acquire,<br>nsync, RMW |
| Alpha       | ~             | ~             | ~              |                             | ~                       | MB, WMB                         |
| RMO         | ~             | ~             | ~              |                             | ~                       | various MEMBARs                 |
| PowerPC     | √             | √             | √              | ~                           | ~                       | SYNC                            |

#### **Relaxing All Program Orders**

- Read or a Write operation may be reordered w.r.t following read or write to a different location
  - Weak Ordering Model
    - Release Consistency Model (RCsc/RCpc)
    - Digital Alpha, Sparc V9 RMO, IBM Power PC
- Except Alpha, the above models allow reordering of two reads to the same location.
- RCpc and PowerPC allow a read to return the value of another processors write early.

#### **Release Consistency**

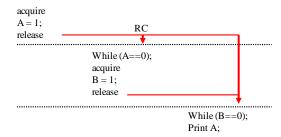
- Distinguishes between ordinary and special memory accesses
- Ordinary accesses are completely unordered with respect to each other
- · Divides synchronization into acquires and releases



#### **RC Example**

Before an ordinary access to a shared variable is performed, all previous acquires done by the process must have completed successfully

Before a release is allowed to be performed, all previous reads and writes by the process must have completed (therefore, example below should always print A=1)



### Threads cannot be implemented as a library [Boehm, PLDI'05]

#### • E.g., C/C++ with pthreads library

"Applications shall ensure that access to any memory location by more than one thread of control (threads or processes) is restricted such that no thread of control can read or modif y a memory location while another thread of control may be modifying it. Such access is restricted using functions that synchronize thread execution and also synchronize memory with respect to other threads."

- · How is this enforced?
  - Programs must use library-provided synchronization
  - Memory barrier instructions used within the library synchronization to prevent hardware memory access reordering
  - Synchronization calls treated as opaque to avoid compiler memory access reordering

# Example: Concurrent Modification

#### • Does this program contain a race?

| Initially, x=y=0                          | Compiler transformation |
|---|-------------------------|
| <sub>⊤1:</sub> if(x==1) ++y;              | ++y; if(x!=1)y;         |
| <sup>⊤</sup> <sup>2:</sup> if (y==1) ++x; | ++x; if (y!=1)x;        |

- No race in original program since no variable can become non-zero
- ... if the compiler makes the modifications on the right, there is a race!

### Summary

- Non-atomic state transitions complicate coherence implementation
- Directory protocols used to scale
  processors to large core counts
- Relaxed consistency models allow read/write reorderings
  - Implications for the hardware
  - Implications for the compiler