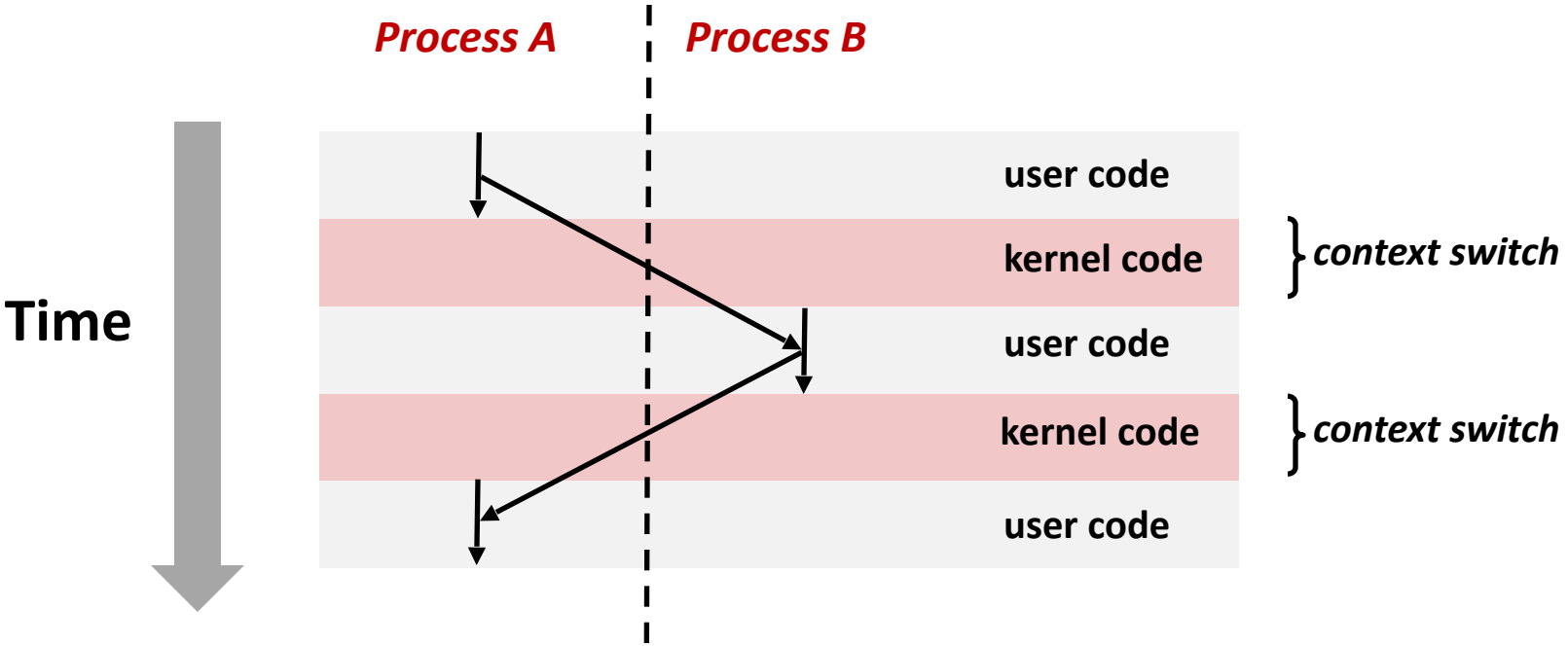
CSC 252/452: Computer Organization
Fall 2025: Lecture 18

Instructor: Yanan Guo

Department of Computer Science
University of Rochester

Context Switching

- Processes are managed by a shared chunk of memory-resident OS code called the *kernel*
  - Important: the kernel is not a separate process, but rather runs as part of some existing process.
- Control flow passes from one process to another via a *context switch*



Creating Processes

- Parent process creates a new child process by calling `fork`
- Child get an identical (but separate) copy of the parent's (virtual) address space (i.e., same stack copies, code, etc.)
- `int fork(void)`
  - Returns **0** to the child process
  - Returns **child's PID** to the parent process

`fork` Example

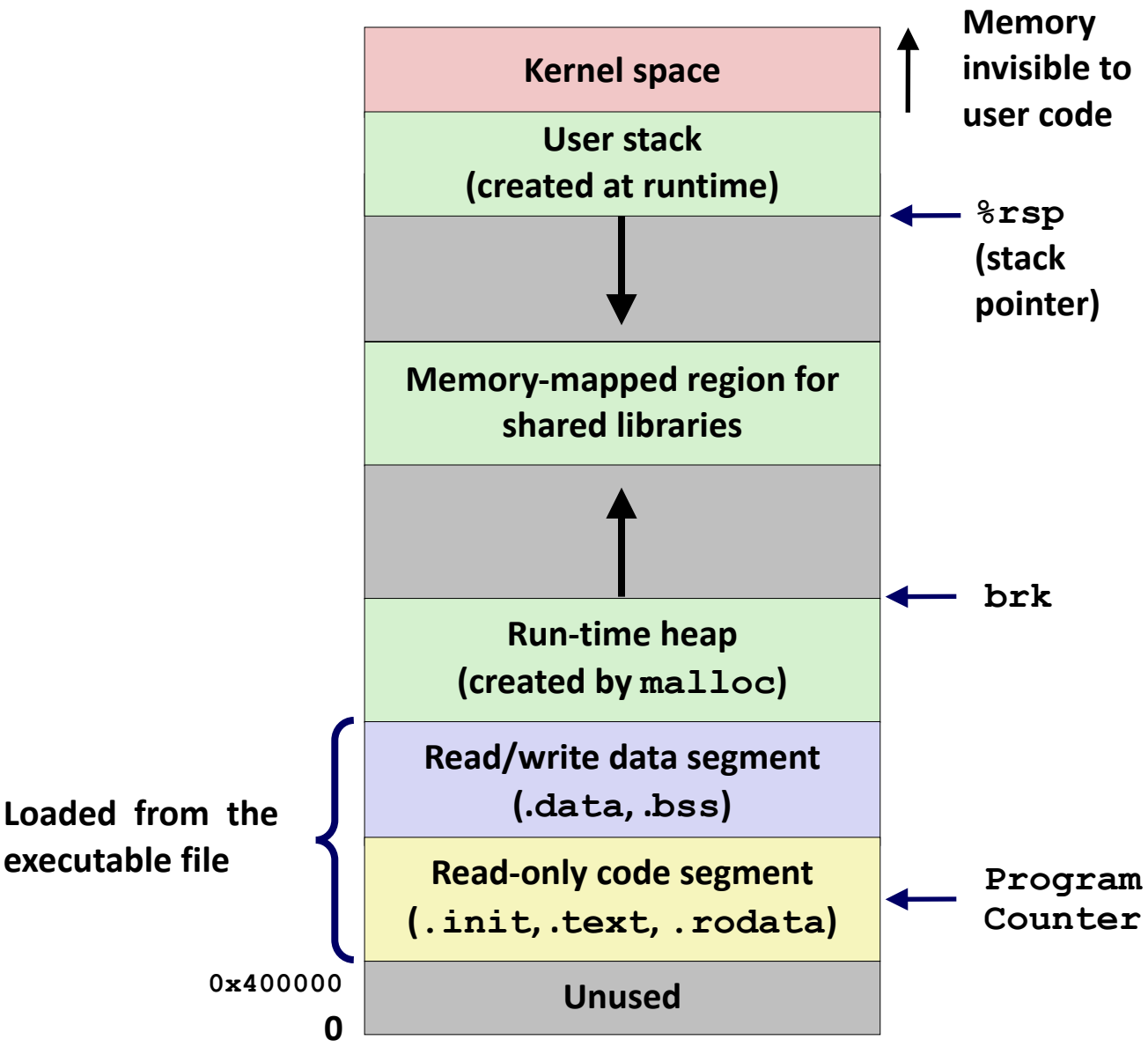
```c
int main()
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) {  /* Child */
        printf("child : x=%d\n", ++x);
        exit(0);
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    exit(0);
}
```

fork.c

```
linux> ./fork
parent: x=0
child : x=2
```

- Call once, return twice
- Concurrent execution
  - Can't predict execution order of parent and child
- Duplicate but separate address space
  - x has a value of 1 when fork returns in parent and child
  - Subsequent changes to x are independent
- Shared open files
  - stdout is the same in both parent and child

Process Address Space



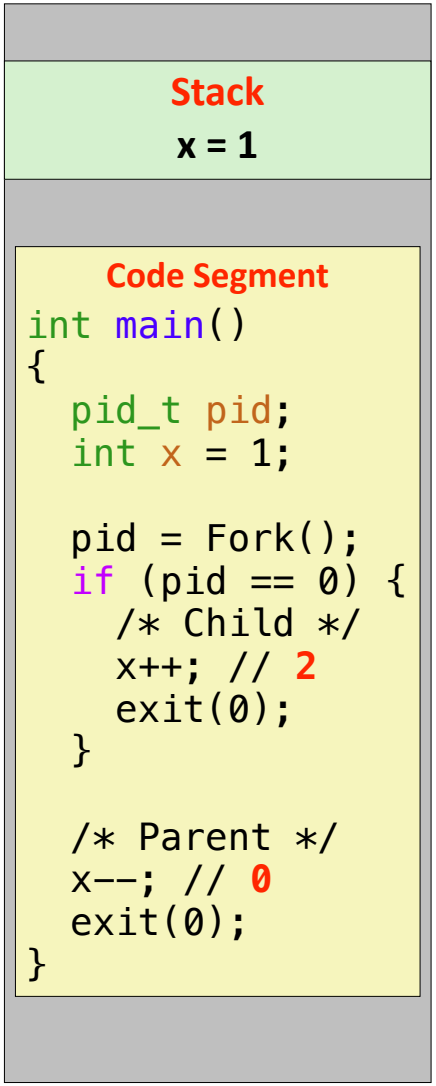
What Happens at `fork()`?

Code Segment

```
int main()
{
  pid_t pid;
  int x = 1;

  pid = Fork();
  if (pid == 0) {
    /* Child */
    x++; // 2
    exit(0);
  }

  /* Parent */
  x--; // 0
  exit(0);
}
```

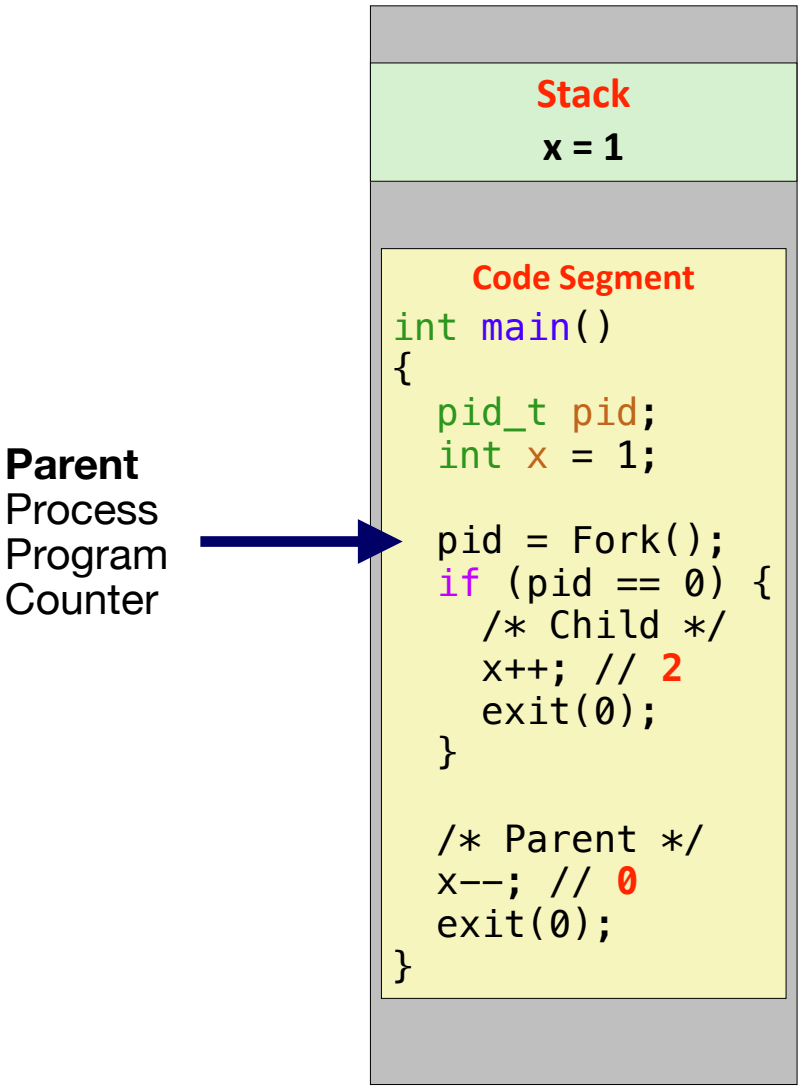
What Happens at `fork()`?

Parent Address Space

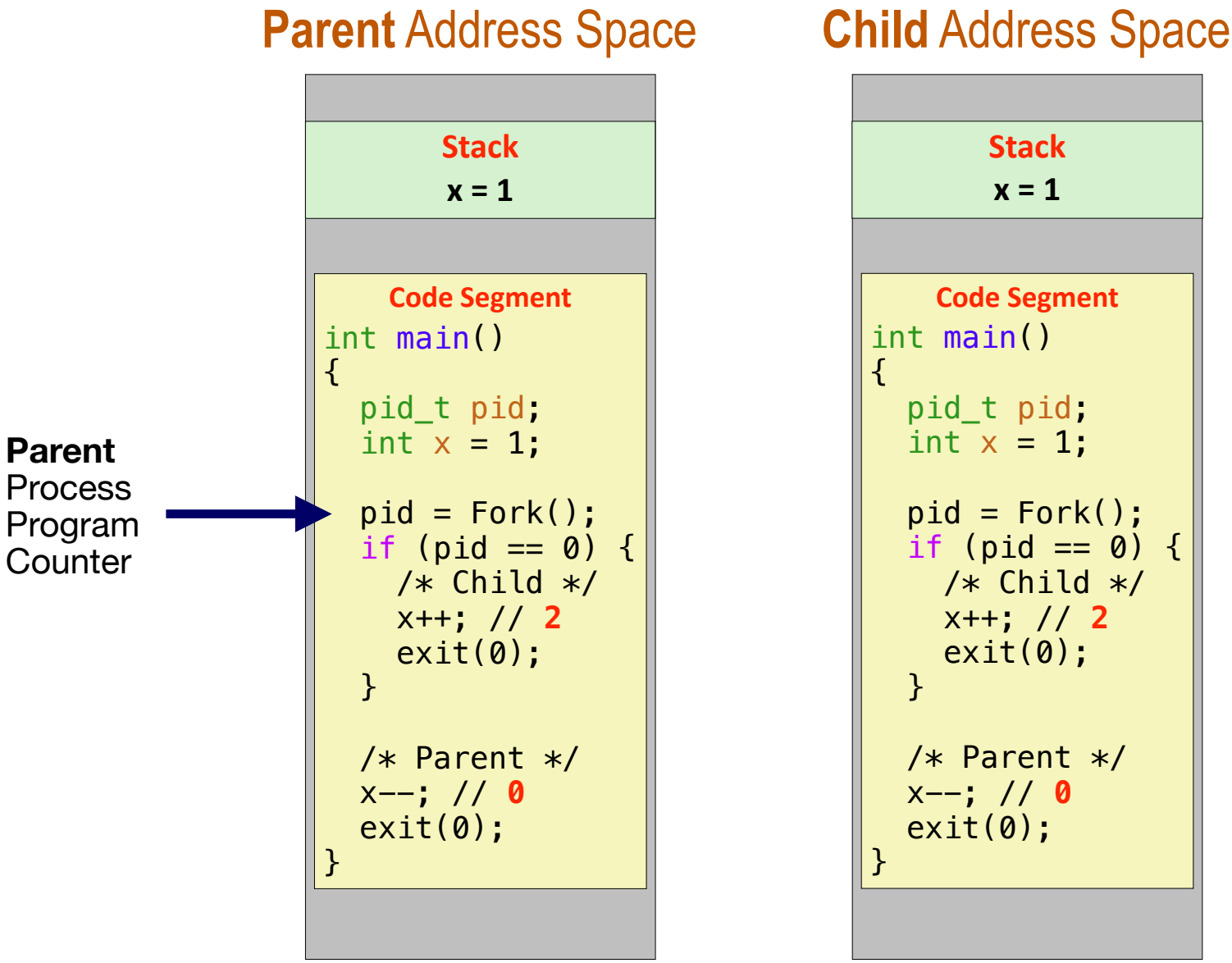


What Happens at `fork()`?

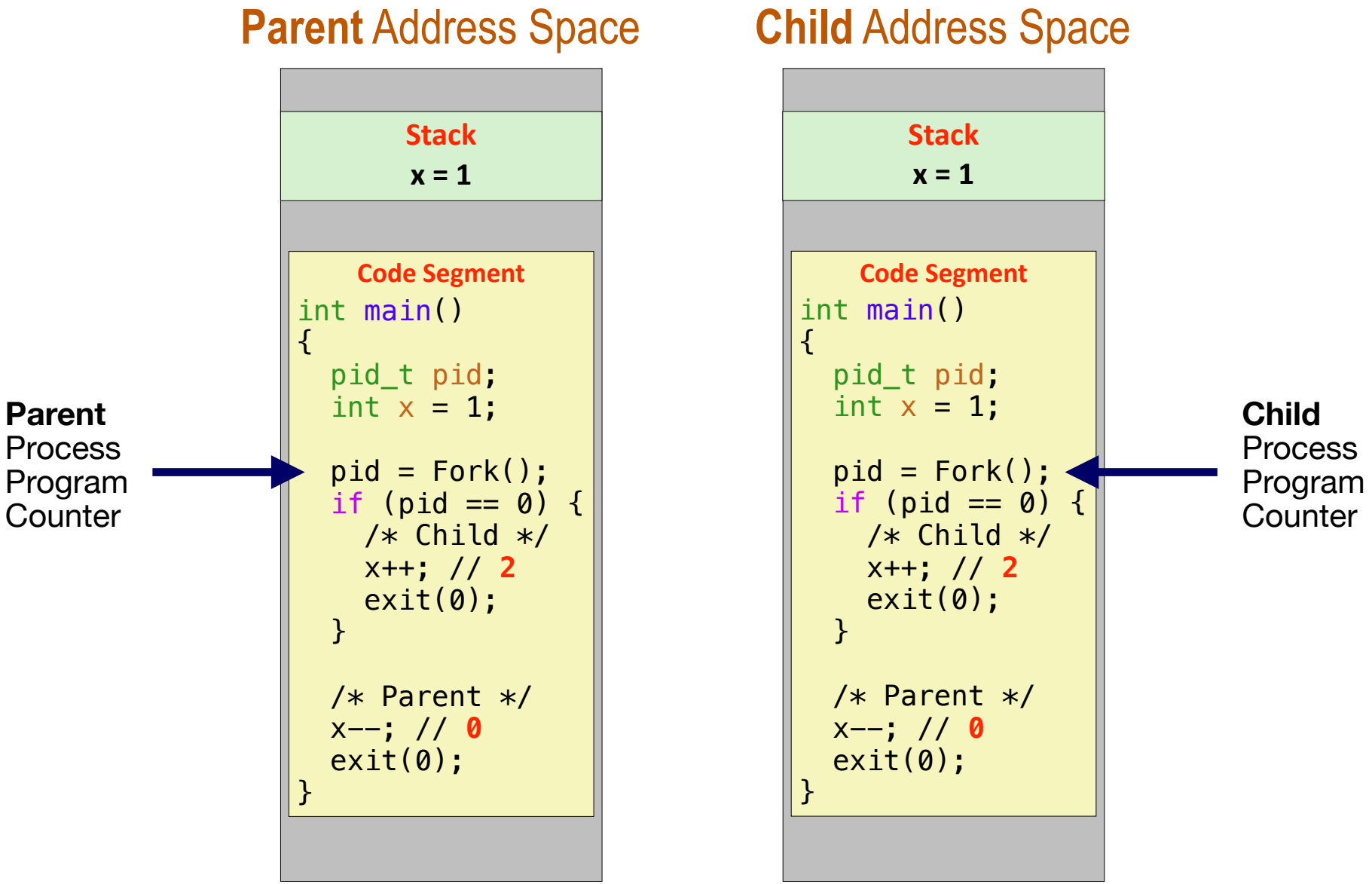
Parent Address Space



What Happens at `fork()`?



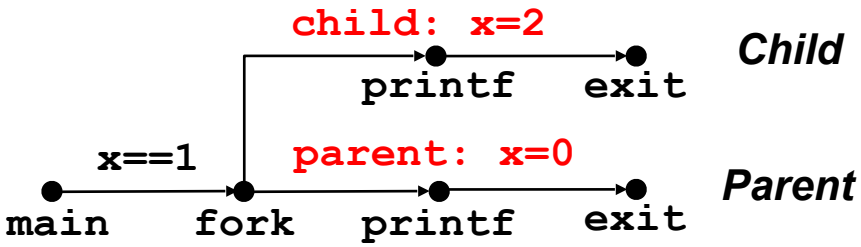
What Happens at `fork()`?



Process Graph Example

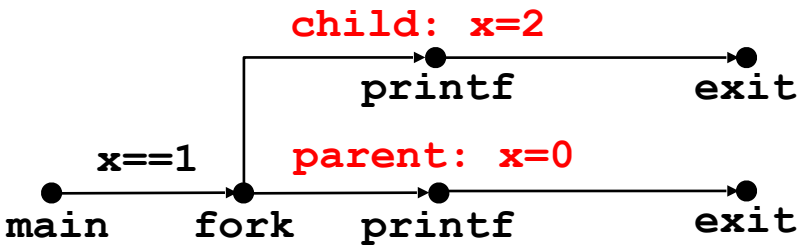
```c
int main()
{
    pid_t pid;
    int x = 1;

    pid = Fork();
    if (pid == 0) {  /* Child */
        printf("child : x=%d\n", ++x);
        exit(0);
    }

    /* Parent */
    printf("parent: x=%d\n", --x);
    exit(0);
}
```

fork.c

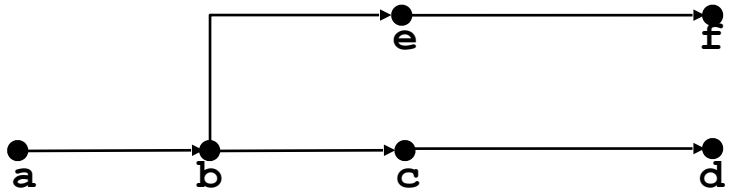


Interpreting Process Graphs

- Original graph:

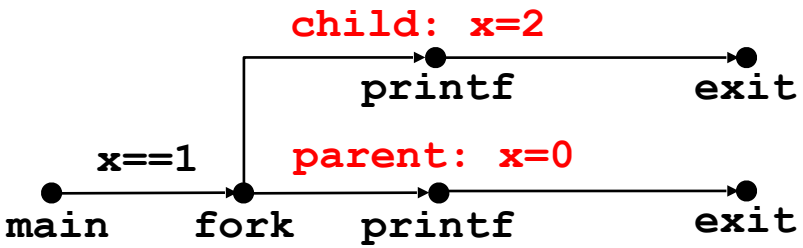


- Abstracted graph:

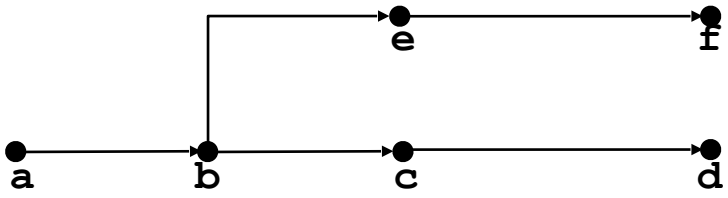


Interpreting Process Graphs

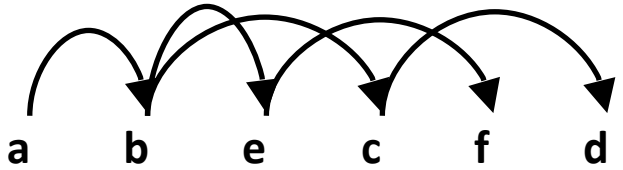
- Original graph:



- Abstracted graph:

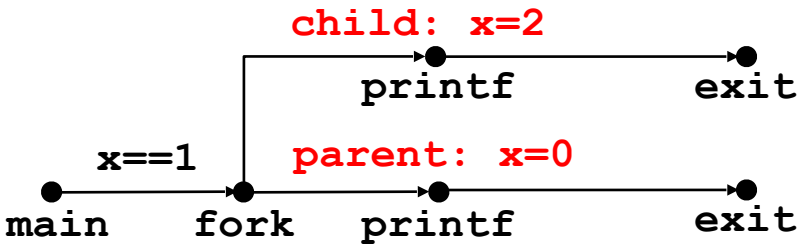


Feasible execution ordering:

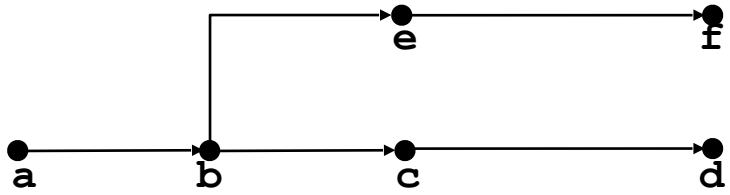


Interpreting Process Graphs

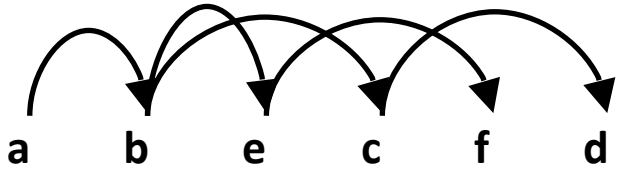
- Original graph:



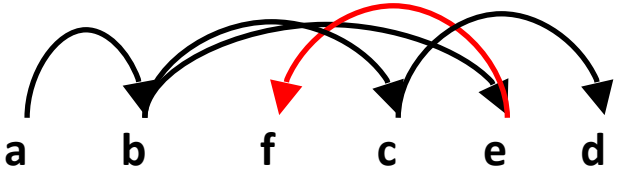
- Abstracted graph:



Feasible execution ordering:



Infeasible execution ordering:



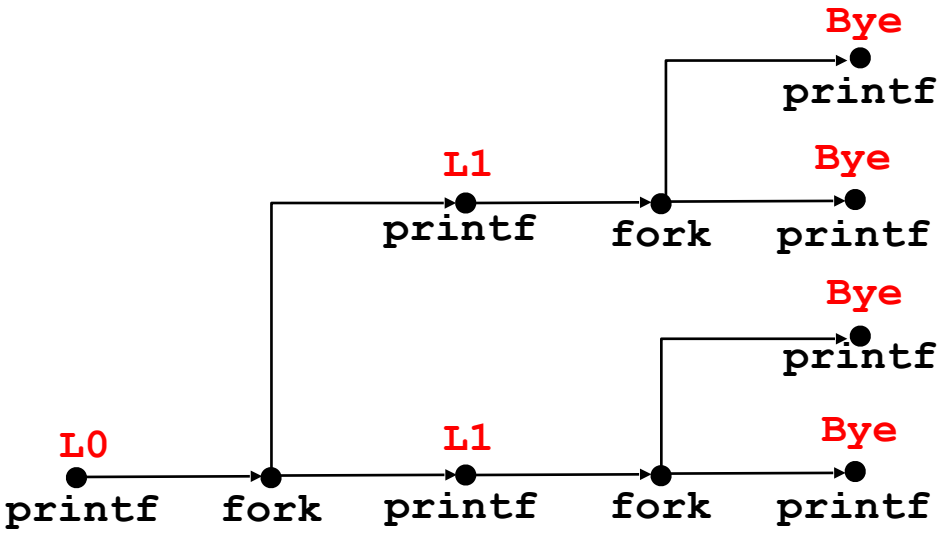
`fork` Example: Two consecutive `fork`s

```
void fork2()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```

forks.c

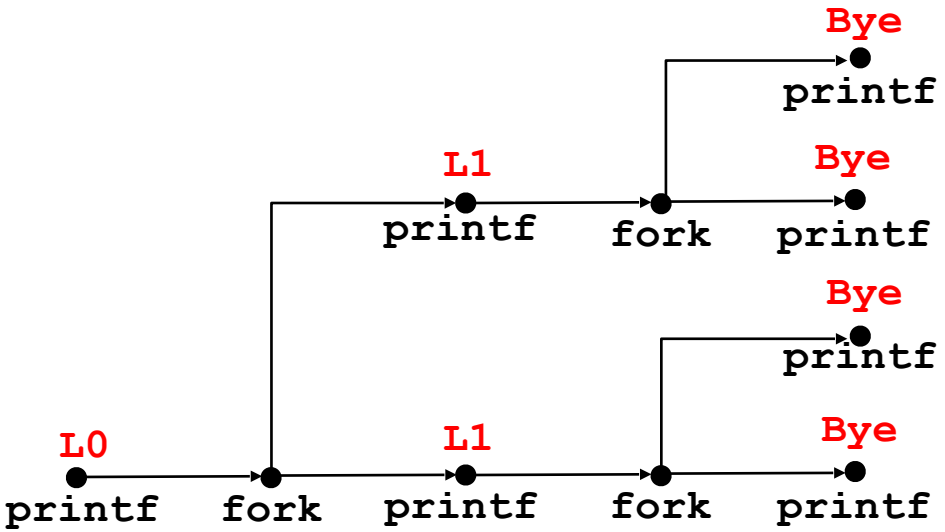
`fork` Example: Two consecutive `fork`s

```
void fork2()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```
forks.c



`fork` Example: Two consecutive `fork`s

```
void fork2()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```
forks.c

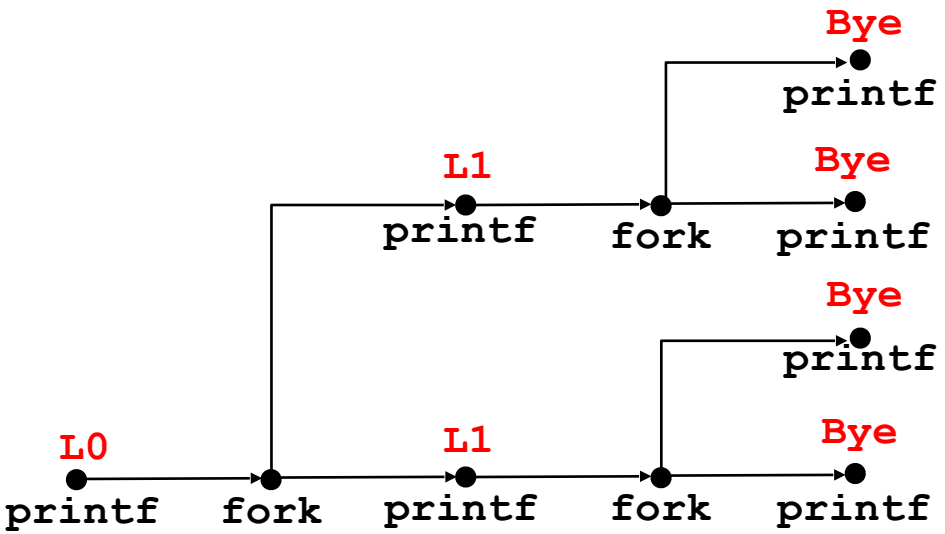


Feasible output:

L0
L1
Bye
Bye
L1
Bye
Bye

`fork` Example: Two consecutive `fork`s

```
void fork2()
{
    printf("L0\n");
    fork();
    printf("L1\n");
    fork();
    printf("Bye\n");
}
```
forks.c



Feasible output:

L0
L1
Bye
Bye
L1
Bye
Bye

Infeasible output:

L0
Bye
L1
Bye
L1
Bye
Bye

`fork` Example: Nested `fork`s in parent

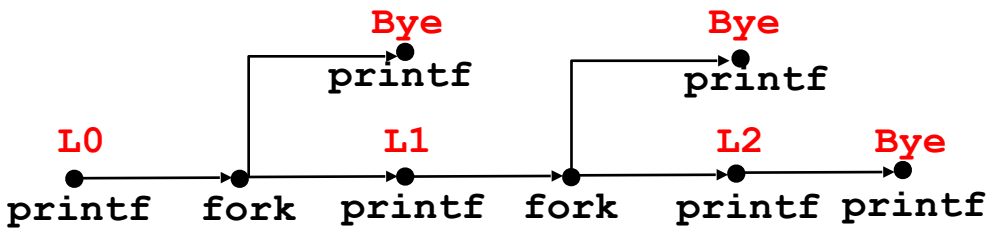
```
void fork4()
{
    printf("L0\n");
    if (fork() != 0) {
       printf("L1\n");
       if (fork() != 0) {
           printf("L2\n");
       }
    }
    printf("Bye\n");
}
```

forks.c

`fork` Example: Nested `fork`s in parent

```
void fork4()
{
    printf("L0\n");
    if (fork() != 0) {
       printf("L1\n");
       if (fork() != 0) {
           printf("L2\n");
       }
    }
    printf("Bye\n");
}
```

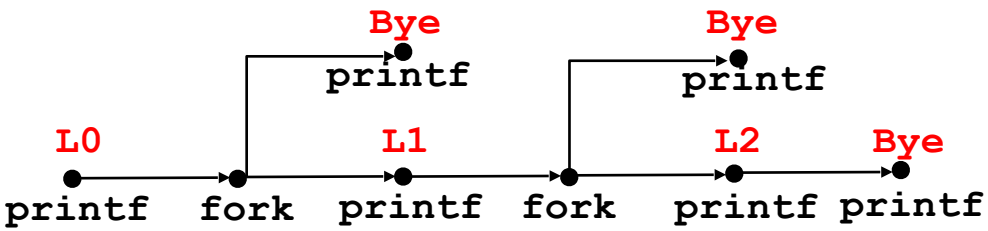
forks.c



`fork` Example: Nested `fork`s in parent

```
void fork4()
{
    printf("L0\n");
    if (fork() != 0) {
       printf("L1\n");
       if (fork() != 0) {
           printf("L2\n");
       }
    }
    printf("Bye\n");
}
```

forks.c



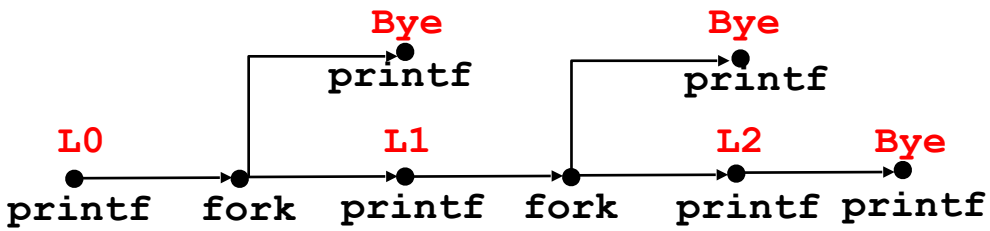
Feasible output:

L0
L1
Bye
Bye
L2
Bye

`fork` Example: Nested `fork`s in parent

```
void fork4()
{
    printf("L0\n");
    if (fork() != 0) {
       printf("L1\n");
       if (fork() != 0) {
           printf("L2\n");
       }
    }
    printf("Bye\n");
}
```

forks.c



Feasible output:

L0
L1
Bye
Bye
L2
Bye

Infeasible output:

L0
Bye
L1
Bye
Bye
L2

`fork` Example: Nested `fork`s in children

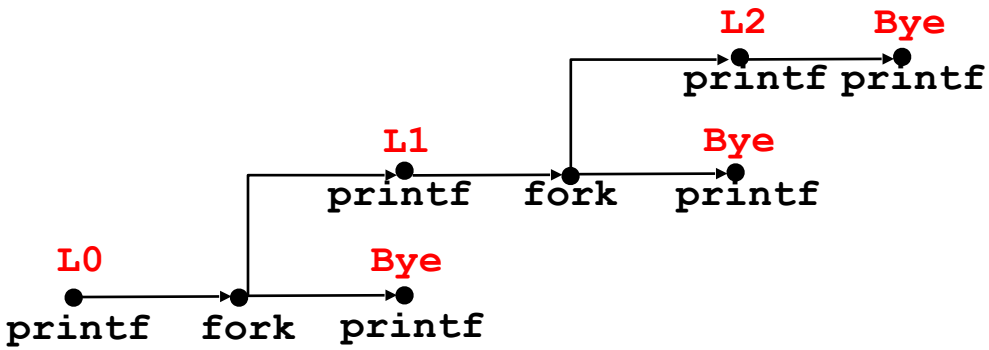
```
void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

forks.c

`fork` Example: Nested `fork`s in children

```
void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

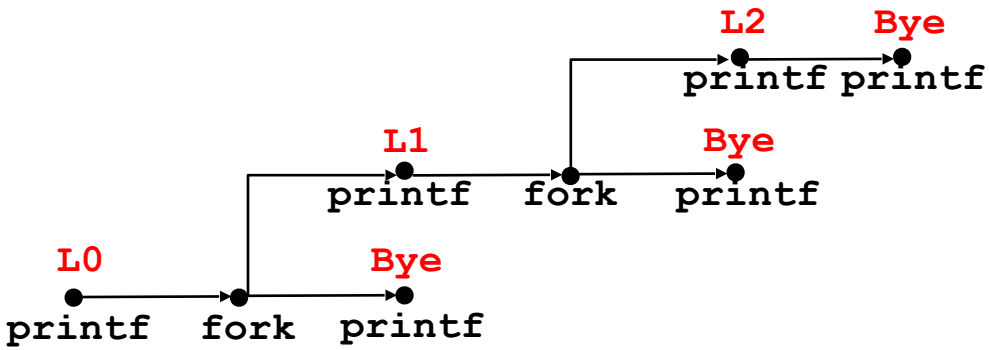
forks.c



`fork` Example: Nested `fork`s in children

```
void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

forks.c



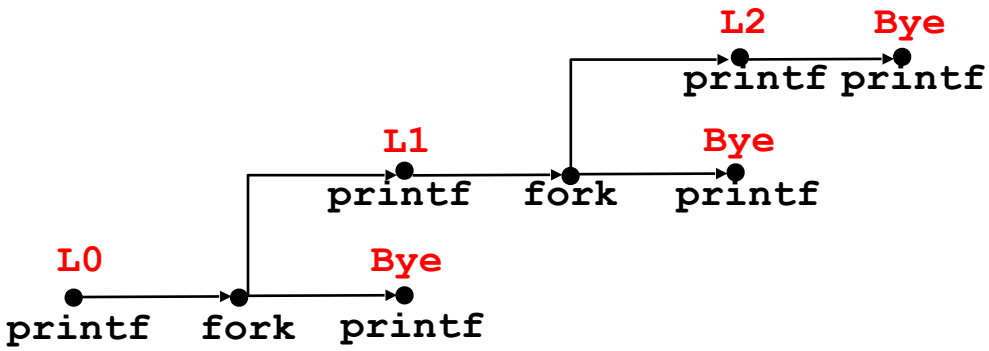
Feasible output:

L0
Bye
L1
L2
Bye
Bye

`fork` Example: Nested `fork`s in children

```
void fork5()
{
    printf("L0\n");
    if (fork() == 0) {
        printf("L1\n");
        if (fork() == 0) {
            printf("L2\n");
        }
    }
    printf("Bye\n");
}
```

forks.c



Feasible output:

L0
Bye
L1
L2
Bye
Bye

Infeasible output:

L0
Bye
L1
Bye
Bye
L2

Reaping Child Processes

- When process terminates, it still consumes system resources
  - Examples: Exit status, various OS tables
  - Called a “zombie”: Living corpse, half alive and half dead
- Reaping
  - Performed by parent on terminated child (using `wait` or `waitpid`)

Reaping Child Processes

- When process terminates, it still consumes system resources
  - Examples: Exit status, various OS tables
  - Called a “zombie”: Living corpse, half alive and half dead
- Reaping
  - Performed by parent on terminated child (using `wait` or `waitpid`)
  - Parent is given exit status information
  - Kernel then deletes zombie child process
- What if parent doesn’t reap?
  - If any parent terminates without reaping a child, then the orphaned child will be reaped by **`init`** process (pid == 1)

```c
void fork7() {
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

forks.c

```c
void fork7() {
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

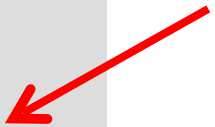
forks.c

```
linux> ./forks 7 &
[1] 6639
Running Parent, PID = 6639
Terminating Child, PID = 6640
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6639 ttyp9    00:00:03 forks
 6640 ttyp9    00:00:00 forks <defunct>
 6641 ttyp9    00:00:00 ps
linux> kill 6639
[1]    Terminated
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6642 ttyp9    00:00:00 ps
```

```c
void fork7() {
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

forks.c

```
linux> ./forks 7 &
[1] 6639
Running Parent, PID = 6639
Terminating Child, PID = 6640
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6639 ttyp9    00:00:03 forks
 6640 ttyp9    00:00:00 forks <defunct>
 6641 ttyp9    00:00:00 ps
linux> kill 6639
[1]    Terminated
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6642 ttyp9    00:00:00 ps
```



- `ps` shows child process as "defunct" (i.e., a zombie)

```c
void fork7() {
    if (fork() == 0) {
        /* Child */
        printf("Terminating Child, PID = %d\n", getpid());
        exit(0);
    } else {
        printf("Running Parent, PID = %d\n", getpid());
        while (1)
            ; /* Infinite loop */
    }
}
```

forks.c

```
linux> ./forks 7 &
[1] 6639
Running Parent, PID = 6639
Terminating Child, PID = 6640
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6639 ttyp9    00:00:03 forks
 6640 ttyp9    00:00:00 forks <defunct>
 6641 ttyp9    00:00:00 ps
linux> kill 6639
[1]    Terminated
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6642 ttyp9    00:00:00 ps
```

- `ps` shows child process as "defunct" (i.e., a zombie)
- Killing parent allows child to be reaped by **`init`**

```c
void fork8()
{
    if (fork() == 0) {
        /* Child */
        printf("Running Child, PID = %d\n",
               getpid());
        while (1)
            ; /* Infinite loop */
    } else {
        printf("Terminating Parent, PID = %d\n",
               getpid());
        exit(0);
    }
}
```

forks.c

```c
void fork8()
{
    if (fork() == 0) {
        /* Child */
        printf("Running Child, PID = %d\n",
               getpid());
        while (1)
            ; /* Infinite loop */
    } else {
        printf("Terminating Parent, PID = %d\n",
               getpid());
        exit(0);
    }
}
```

forks.c

```
linux> ./forks 8
Terminating Parent, PID = 6675
Running Child, PID = 6676
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6676 ttyp9    00:00:06 forks
 6677 ttyp9    00:00:00 ps
linux> kill 6676
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6678 ttyp9    00:00:00 ps
```

```c
void fork8()
{
    if (fork() == 0) {
        /* Child */
        printf("Running Child, PID = %d\n",
               getpid());
        while (1)
            ; /* Infinite loop */
    } else {
        printf("Terminating Parent, PID = %d\n",
               getpid());
        exit(0);
    }
}
```

forks.c

```
linux> ./forks 8
Terminating Parent, PID = 6675
Running Child, PID = 6676
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6676 ttyp9    00:00:06 forks
 6677 ttyp9    00:00:00 ps
linux> kill 6676
linux> ps
  PID TTY          TIME CMD
 6585 ttyp9    00:00:00 tcsh
 6678 ttyp9    00:00:00 ps
```

- Child process still active even though parent has terminated. Can't be reaped since it's still running!
- Must kill child explicitly, or else will keep running indefinitely

`wait`: Synchronizing with Children

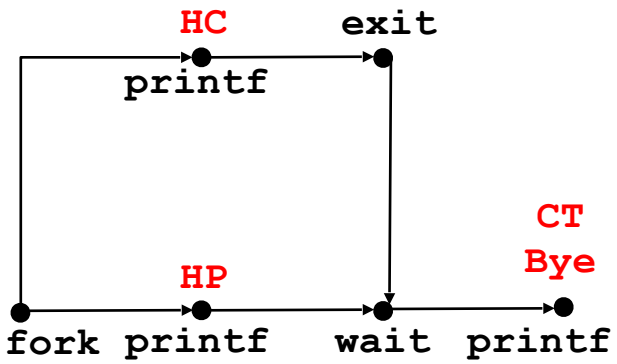
```
void fork9() {
    int child_status;

    if (fork() == 0) {
        printf("HC: hello from child\n");
       exit(0);
    } else {
        printf("HP: hello from parent\n");
        wait(&child_status);
        printf("CT: child has terminated\n");
    }
    printf("Bye\n");
}
```

forks.c

`wait`: Synchronizing with Children

```
void fork9() {
    int child_status;

    if (fork() == 0) {
        printf("HC: hello from child\n");
        exit(0);
    } else {
        printf("HP: hello from parent\n");
        wait(&child_status);
        printf("CT: child has terminated\n");
    }
    printf("Bye\n");
}
```

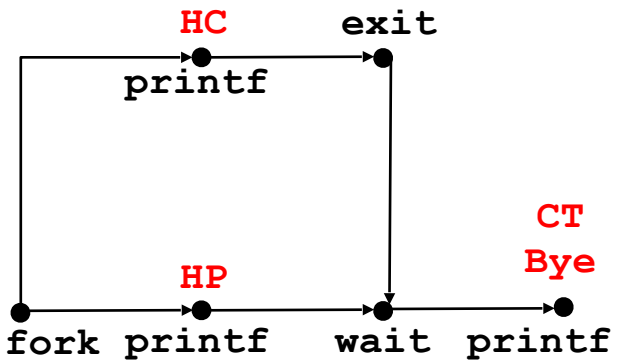
forks.c



`wait`: Synchronizing with Children

```
void fork9() {
    int child_status;

    if (fork() == 0) {
        printf("HC: hello from child\n");
        exit(0);
    } else {
        printf("HP: hello from parent\n");
        wait(&child_status);
        printf("CT: child has terminated\n");
    }
    printf("Bye\n");
}
```

forks.c



Feasible output:

HC

HP

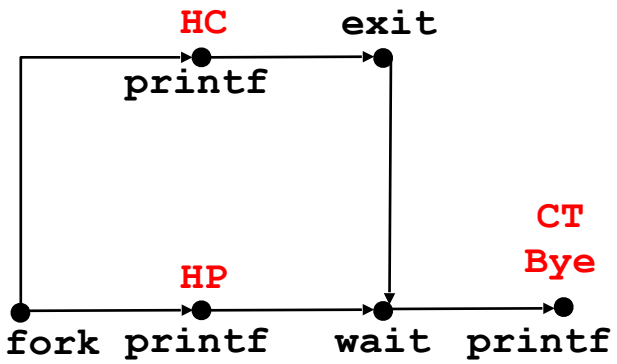
CT

Bye

`wait`: Synchronizing with Children

```
void fork9() {
    int child_status;

    if (fork() == 0) {
        printf("HC: hello from child\n");
        exit(0);
    } else {
        printf("HP: hello from parent\n");
        wait(&child_status);
        printf("CT: child has terminated\n");
    }
    printf("Bye\n");
}
```

forks.c



Feasible output:

HC
HP
CT
Bye

Infeasible output:

HP
CT
Bye
HC

`wait`: Synchronizing with Children

- Parent reaps a child by calling the `wait` function

- `int wait(int *child_status)`
  - Suspends current process until one of its children terminates
  - Return value is the **`pid`** of the child process that terminated
  - If **`child_status != NULL`**, then the integer it points to will be set to a value that indicates reason the child terminated and the exit status:
    - Checked using macros defined in `wait.h`
      - `WIFEXITED, WEXITSTATUS, WIFSIGNALED, WTERMSIG, WIFSTOPPED, WSTOPSIG, WIFCONTINUED`
      - See textbook for details

Another `wait` Example

- If multiple children completed, will take in arbitrary order
- Can use macros WIFEXITED and WEXITSTATUS to get information about exit status

```
void fork10() {
   int i, child_status;

    for (i = 0; i < N; i++)
        if (fork() == 0) {
            exit(100+i); /* Child */
        }
    for (i = 0; i < N; i++) { /* Parent */
        pid_t wpid = wait(&child_status);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n",
                   wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminate abnormally\n", wpid);
    }
}
```

forks.c

`waitpid`: Waiting for a Specific Process

- `pid_t waitpid(pid_t pid, int &status, int options)`
  - Suspends current process until specific process terminates
  - Various options (see textbook)

```c
void fork11() {
    pid_t pid[N];
    int i;
    int child_status;

    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0)
            exit(100+i); /* Child */
    for (i = N-1; i >= 0; i--) {
        pid_t wpid = waitpid(pid[i], &child_status, 0);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n",
                   wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminate abnormally\n", wpid);
    }
}
```

forks.c

`execve`: Loading and Running Programs

Executes "`/bin/ls -lt /usr/include`" in child process using current environment:

```
char *myargv[] = {"/bin/ls", "-lt", "/usr/include"};
char *environ[] = {"USER=droh", "PWD="/usr/droh"};

if ((pid = Fork()) == 0) {   /* Child runs program */
    if (execve(myargv[0], myargv, environ) < 0) {
        printf("%s: Command not found.\n", myargv[0]);
        exit(1);
    }
}
```

`execve`: Loading and Running Programs

- `int execve(char *filename, char *argv[], char *envp[])`

`execve`: Loading and Running Programs

- `int execve(char *filename, char *argv[], char *envp[])`
- Loads and runs in the current process:
  - Executable file **`filename`**
  - Argument list **`argv`**
    - By convention **`argv[0]==filename`**
  - Environment variable list **`envp`**
    - "name=value" strings (e.g., `USER=droh`)

`execve`: Loading and Running Programs

- `int execve(char *filename, char *argv[], char *envp[])`
- Loads and runs in the current process:
  - Executable file **`filename`**
  - Argument list **`argv`**
    - By convention **`argv[0]==filename`**
  - Environment variable list **`envp`**
    - "name=value" strings (e.g., `USER=droh`)
- Overwrites code, data, and stack
  - Retains PID, open files and signal context

`execve`: Loading and Running Programs

- `int execve(char *filename, char *argv[], char *envp[])`
- Loads and runs in the current process:
  - Executable file **`filename`**
  - Argument list **`argv`**
    - By convention **`argv[0]==filename`**
  - Environment variable list **`envp`**
    - "name=value" strings (e.g., `USER=droh`)
- Overwrites code, data, and stack
  - Retains PID, open files and signal context
- Called once and never returns
  - …except if there is an error

Summary

- Processes
  - At any given time, system has multiple active processes
  - Only one can execute at a time on a single core, though
  - Each process appears to have total control of processor + private memory space
- Spawning processes
  - Call `fork`
  - One call, two returns
- Process completion
  - Call `exit`
  - One call, no return
- Reaping and waiting for processes
  - Call `wait` or `waitpid`
- Loading and running programs
  - Call `execve` (or variant)
  - One call, (normally) no return

Today

- Process Control
- Signals: The Way to Communicate with Processes

Signals

- A signal is a small message that notifies a process that an event of some type has occurred in the system
  - Sent from the **OS kernel**
  - Could be requested by another process, by user, or automatically by the kernel
  - Signal type is identified by small integer ID's (1-30)

Signals

- A signal is a small message that notifies a process that an event of some type has occurred in the system
  - Sent from the **OS kernel**
  - Could be requested by another process, by user, or automatically by the kernel
  - Signal type is identified by small integer ID's (1-30)

ID	Name	Default Action	Corresponding Event
2	SIGINT	Terminate	User typed ctrl-c
9	SIGKILL	Terminate	Kill program (cannot override or ignore)
11	SIGSEGV	Terminate	Segmentation violation
14	SIGALRM	Terminate	Timer signal
17	SIGCHLD	Ignore	Child stopped or terminated

Signal Concepts: Sending a Signal

Signal Concepts: Sending a Signal

- Kernel sends (delivers) a signal to a destination process by updating some state in the context of the destination process

Signal Concepts: Sending a Signal

- Kernel sends (delivers) a signal to a destination process by updating some state in the context of the destination process
- Kernel sends a signal for one of the following reasons:
  - Kernel has detected a system event such as:
    - Exception: divide-by-zero (SIGFPE)
    - Interrupt: user pressing Ctrl + C (SIGINT)
    - The termination of a child process (SIGCHLD)
  - Another process has invoked the `kill` system call to explicitly request the kernel to send a signal to the destination process.
    - Note: `kill` doesn't mean you are going to kill the target process. It is just a system call that allows you to send signals. Of course the signal you send could be SIGKILL.

Signal Concepts: Receiving a Signal

Signal Concepts: Receiving a Signal

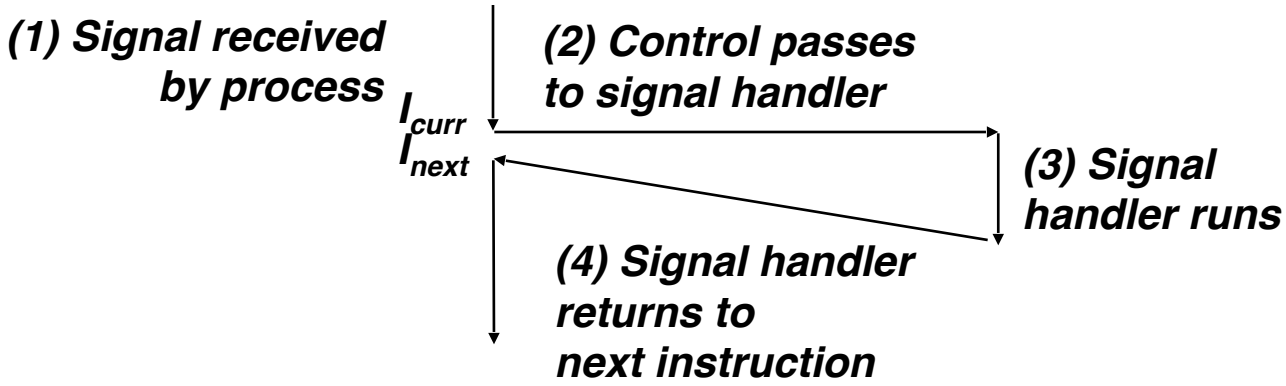
- A destination process receives a signal when it is forced by the kernel to react in some way to the delivery of the signal

Signal Concepts: Receiving a Signal

- A destination process receives a signal when it is forced by the kernel to react in some way to the delivery of the signal
- Some possible ways to react:
  - Ignore the signal (do nothing)
  - Terminate the process
  - Catch the signal by executing a user-level function called signal handler
    - Similar to a hardware exception handler being called in response to an asynchronous interrupt:

Signal Concepts: Receiving a Signal

- A destination process receives a signal when it is forced by the kernel to react in some way to the delivery of the signal
- Some possible ways to react:
  - Ignore the signal (do nothing)
  - Terminate the process
  - Catch the signal by executing a user-level function called signal handler
    - Similar to a hardware exception handler being called in response to an asynchronous interrupt:



Sending Signals with `/bin/kill` Program

- `/bin/kill` program sends arbitrary signal to a process
- Examples
  - **`/bin/kill -9 24818`**
    Send SIGKILL to process 24818
  - `/bin/kill` itself doesn't kill the process. 9 is the ID for the SIGKILL signal, which terminates the process

```
linux> ./forks 16
Child1: pid=24818 pgrp=24817
Child2: pid=24819 pgrp=24817

linux> ps
  PID TTY          TIME CMD
24788 pts/2    00:00:00 tcsh
24818 pts/2    00:00:02 forks
24819 pts/2    00:00:02 forks
24820 pts/2    00:00:00 ps
```

Sending Signals with `/bin/kill` Program

- `/bin/kill` program sends arbitrary signal to a process
- Examples
  - **`/bin/kill -9 24818`**
    Send SIGKILL to process 24818
  - `/bin/kill` itself doesn't kill the process. 9 is the ID for the SIGKILL signal, which terminates the process

```
linux> ./forks 16
Child1: pid=24818 pgrp=24817
Child2: pid=24819 pgrp=24817

linux> ps
  PID TTY          TIME CMD
24788 pts/2    00:00:00 tcsh
24818 pts/2    00:00:02 forks
24819 pts/2    00:00:02 forks
24820 pts/2    00:00:00 ps
```

Sending Signals from the Keyboard

- Typing ctrl-c causes the kernel to send a SIGINT to every process in the foreground process group.
  - SIGINT – default action is to terminate each process
- Typing ctrl-z causes the kernel to send a SIGTSTP to every job in the foreground process group.
  - SIGTSTP – default action is to stop (suspend) each process

Example of `ctrl-c` and `ctrl-z`

```
bluefish> ./forks 17
Child: pid=28108 pgrp=28107
Parent: pid=28107 pgrp=28107

<types ctrl-z>
Suspended
bluefish> ps w
  PID TTY      STAT   TIME COMMAND
27699 pts/8    Ss     0:00 -tcsh
28107 pts/8    T      0:01 ./forks 17
28108 pts/8    T      0:01 ./forks 17
28109 pts/8    R+     0:00 ps w

bluefish> fg
./forks 17
<types ctrl-c>
bluefish> ps w
  PID TTY      STAT   TIME COMMAND
27699 pts/8    Ss     0:00 -tcsh
28110 pts/8    R+     0:00 ps w
```

STAT (process state) Legend:

First letter:

S: sleeping

T: stopped

R: running

Second letter:

s: session leader

+: foreground proc group

See “man ps” for more details

Sending Signals with `kill` Function

```c
void fork12()
{
    pid_t pid[N];
    int i;
    int child_status;

    for (i = 0; i < N; i++)
        if ((pid[i] = fork()) == 0) {
            /* Child: Infinite Loop */
            while(1)
                ;
        }

    for (i = 0; i < N; i++) {
        printf("Killing process %d\n", pid[i]);
        kill(pid[i], SIGINT);
    }

    for (i = 0; i < N; i++) {
        pid_t wpid = wait(&child_status);
        if (WIFEXITED(child_status))
            printf("Child %d terminated with exit status %d\n",
                   wpid, WEXITSTATUS(child_status));
        else
            printf("Child %d terminated abnormally\n", wpid);
    }
}
```

forks.c

Default Actions to Signals

- Each signal type has a predefined default action, which is one of:
  - The process terminates
  - The process stops until restarted by a SIGCONT signal
  - The process ignores the signal

Installing Signal Handlers

Installing Signal Handlers

- The signal function modifies the default action associated with the receipt of signal signum:
  - `handler_t *signal(int signum, handler_t *handler)`

Installing Signal Handlers

- The signal function modifies the default action associated with the receipt of signal signum:
  - `handler_t *signal(int signum, handler_t *handler)`

Installing Signal Handlers

- The signal function modifies the default action associated with the receipt of signal signum:
  - `handler_t *signal(int signum, handler_t *handler)`

- Different values for handler:
  - SIG_IGN: ignore signals of type signum
  - SIG_DFL: revert to the default action on receipt of signals of type signum
  - Otherwise, handler is the address of a user-level function (signal handler)
    - Called when process receives signal of type signum
    - Referred to as "installing" the handler
    - Executing handler is called "catching" or "handling" the signal
    - When the handler executes its return statement, control passes back to instruction in the control flow of the process that was interrupted by receipt of the signal

Signal Handling Example

```c
void sigint_handler(int sig) /* SIGINT handler */
{
    printf("So you think you can stop the bomb with ctrl-c, do you?\n");
    sleep(2);
    printf("Well...");
    fflush(stdout);
    sleep(1);
    printf("OK. :-)\n");
    exit(0);
}

int main()
{
    /* Install the SIGINT handler */
    if (signal(SIGINT, sigint_handler) == SIG_ERR)
        unix_error("signal error");

    /* Wait for the receipt of a signal */
    pause();

    return 0;
}
```

sigint.c