CSC 252 Computer Organization

The Memory Hierarchy Part III

Chen Ding Professor

Guest lecture March 28, 2019 Required reading:

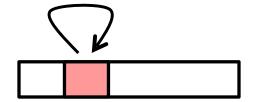
Section 6.5 – 6.7

Locality

 Principle of Locality: Programs tend to use data and instructions with addresses near or equal to those they have used recently

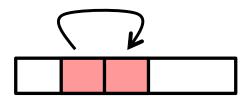
Temporal locality:

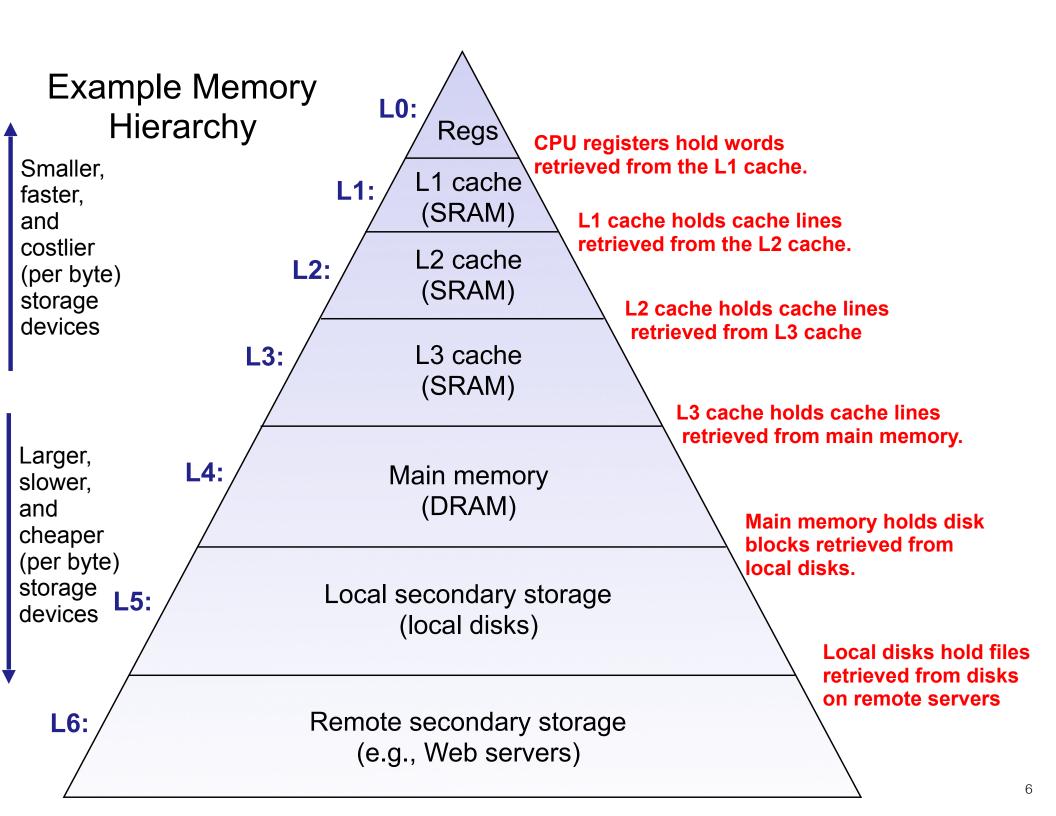
 Recently referenced items are likely to be referenced again in the near future



Spatial locality:

 Items with nearby addresses tend to be referenced close together in time

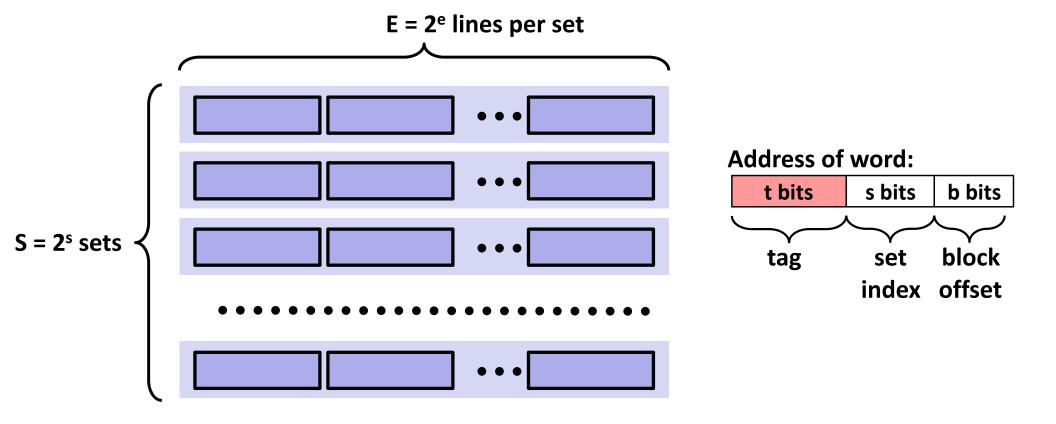




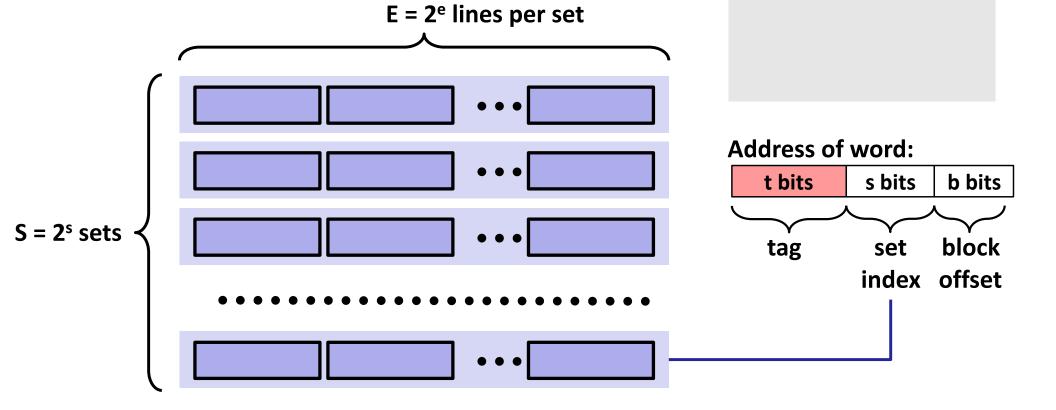
Today

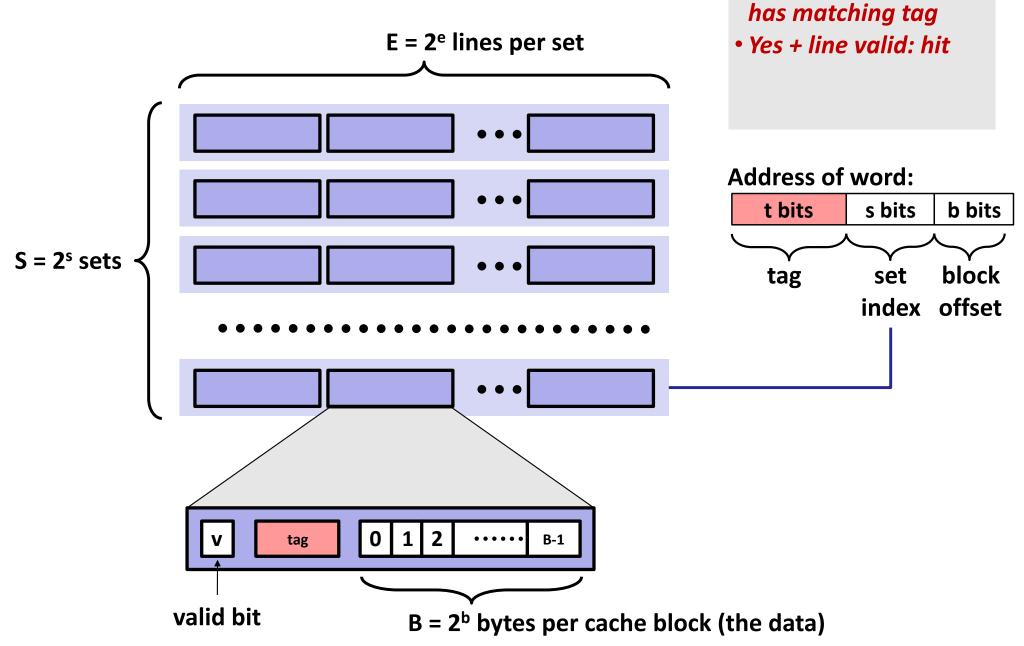
- Review: Cache memory organization and operation
- Performance impact of caches
 - Analytical Model
 - Rearranging loops to improve spatial locality
 - Using blocking to improve temporal locality

Optimizing Irregular and dynamic applications [32]



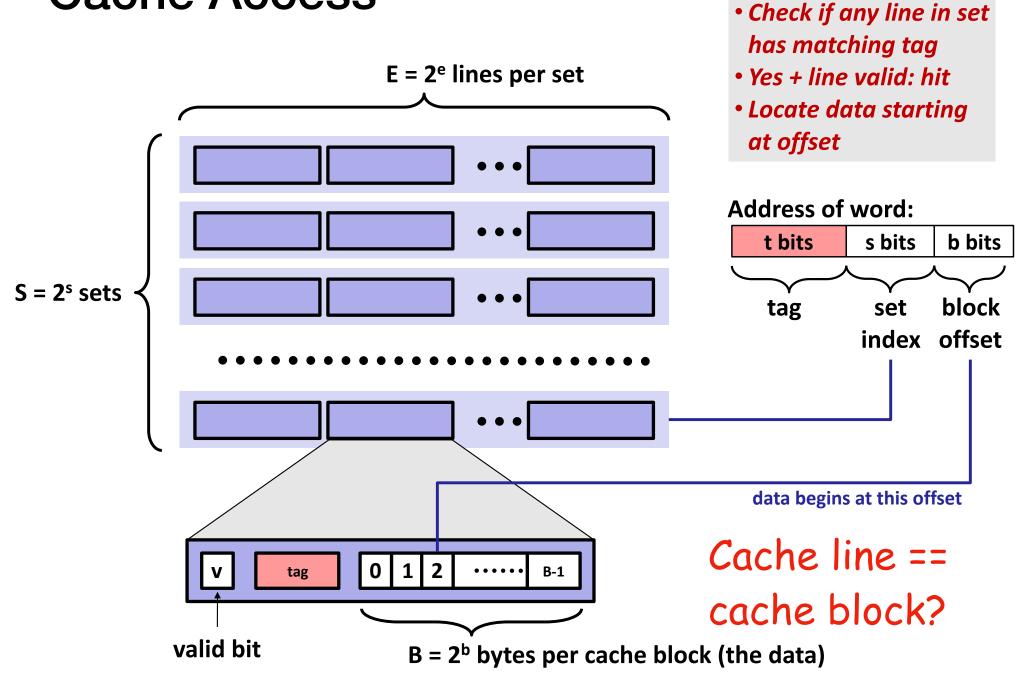
Locate set





Locate set

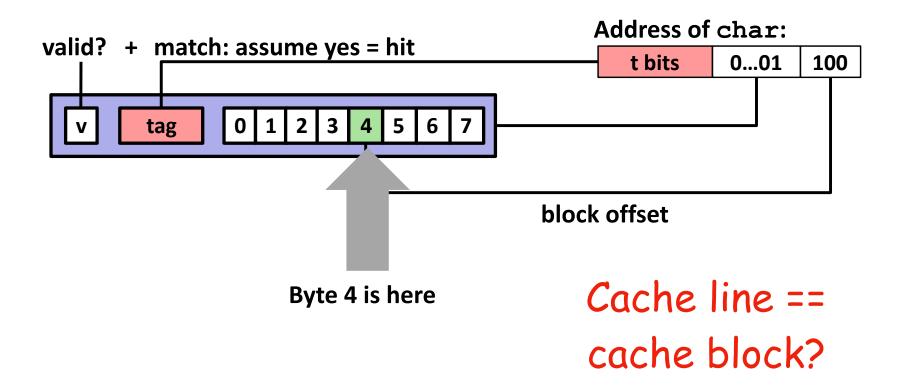
• Check if any line in set



Locate set

Example: Direct Mapped Cache

Direct mapped: One line per set Assume: cache block size 8 bytes



If tag doesn't match: old line is evicted and replaced

Direct-Mapped Cache Simulation

t=1	s=2	b=1
X	XX	Х

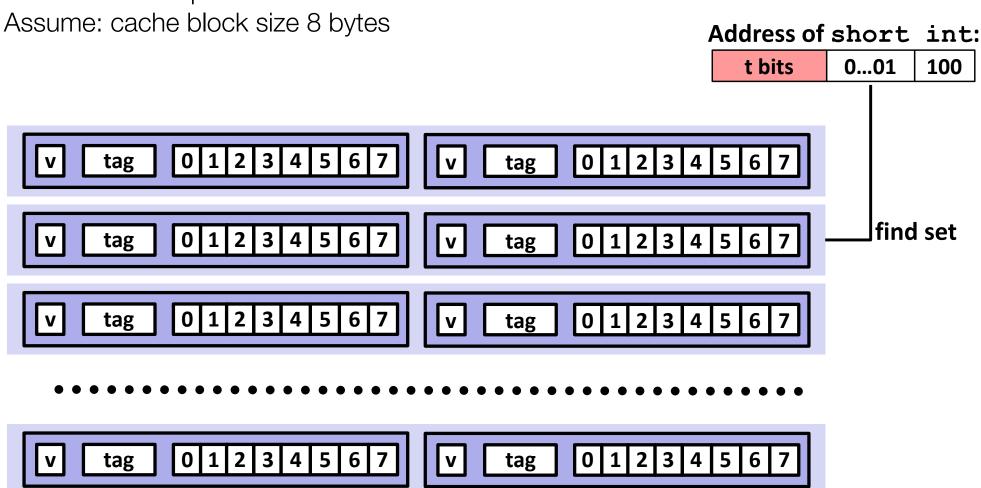
4-bit address space, i.e., Memory = 16 bytes B=2 bytes/line, S=4 sets, E=1 line/set

0	[0 <u>00</u> 0 ₂],	miss
1	[0 <u>00</u> 1 ₂],	hit
7	[0 <u>11</u> 1 ₂],	miss
8	[1 <u>00</u> 0 ₂],	miss
0	[0 <u>00</u> 0 ₂]	miss

	V	Tag	Line
Set 0	1	0	M[0-1]
Set 1			
Set 2			
Set 3	1	0	M[6-7]

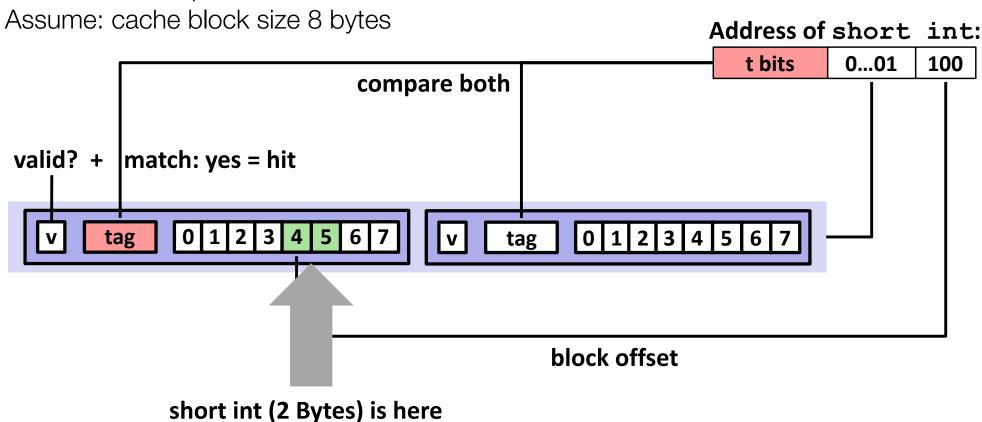
E-way Set Associative Cache (Here: E = 2)

E = 2: Two lines per set



E-way Set Associative Cache (Here: E = 2)

E = 2: Two lines per set



No match:

- One line in set is selected for eviction and replacement
- Replacement policies: random, least recently used (LRU), ...

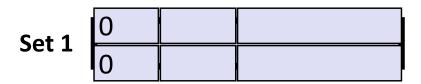
4-bit address space, i.e., Memory = 16 bytes S=2 sets, E=2 blocks/set

Block

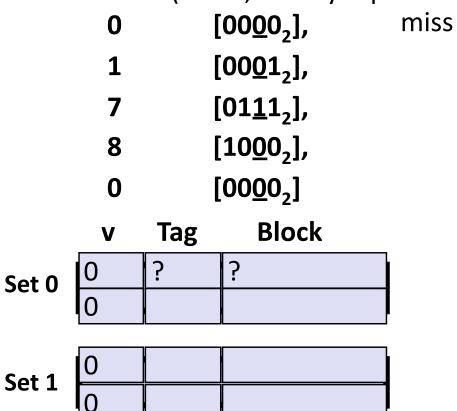
Address trace (reads, one byte per read):

 $0 \qquad [00\underline{0}0_{2}],$ $1 \qquad [00\underline{0}1_{2}],$ $7 \qquad [01\underline{1}1_{2}],$ $8 \qquad [10\underline{0}0_{2}],$ $0 \qquad [00\underline{0}0_{2}]$

	V	ıag	DIUCK
Set 0	0	?	5
	0		



4-bit address space, i.e., Memory = 16 bytes S=2 sets, E=2 blocks/set



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	8		[10 <u>0</u> 0 ₂],	
	0		[00 <u>0</u> 0 ₂]	
	V	Tag	Block	
Set 0	1	00	M[0-1]	
	0			
Set 1	0			
Set 1	0			

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	7		[01 <u>1</u> 1 ₂],	
	8		[10 <u>0</u> 0 ₂],	
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	V	Tag	Block	
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500	0			
	0			
Set 1	U			
	0			

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	8		[10 <u>0</u> 0 ₂],	
	0		[00 <u>0</u> 0 ₂]	
	V	Tag	Block	
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	0			
	0			
Set 1	0			

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	0				
	1	01	M[6-7]		
Set 1					
	10				

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				_
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- Review: Cache memory organization and operation
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Optimizing Irregular and dynamic applications [32]

Cache Performance Metrics

Miss Rate

- Fraction of memory references not found in cache (misses / accesses)
 - = 1 hit rate
- Typical numbers (in percentages):
 - 3-10% for L1
 - can be quite small (e.g., < 1%) for L2, depending on size, etc.

Cache Performance Metrics

Hit Time

- Time to deliver a line in the cache to the processor
 - includes time to determine whether the line is in the cache
- Typical numbers:
 - 1~4 clock cycle for L1
 - 5~10 clock cycles for L2

Cache Performance Metrics

- Miss Penalty
 - Additional time required because of a miss
 - Typically 50-200 cycles for main memory
 - Trend: increasing!

Let's think about those numbers

- Huge difference between a hit and a miss
 - Could be 100x, if just L1 and main memory
- Compare 97% hit rate with 99% hit rate
 - Assume: cache hit time of 1 cycle miss penalty of 100 cycles
 - Average access time:

```
97% hit rate: 1 cycle + 0.03 * 100 cycles = 4 cycles
99% hit rate: 1 cycle + 0.01 * 100 cycles = 2 cycles
```

- Think of it as reducing the miss rate from 3% to 1% (3X improvement) rather than improving hit rate
- Improving hit rate by even a little bit helps overall speed a lot

Writing Cache Friendly Code

- Make the common case go fast
 - Inner loops get executed most often. So focus on those
- Minimize the misses in the inner loops
 - Repeated references to variables are good (temporal locality)
 - Stride-1 reference patterns are good (spatial locality)

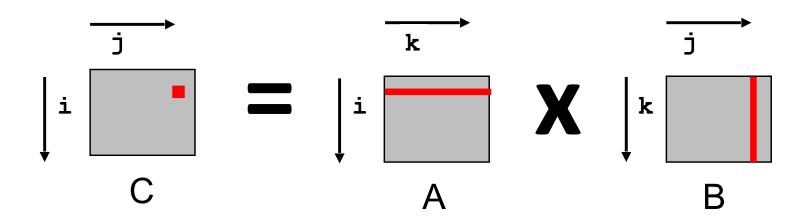
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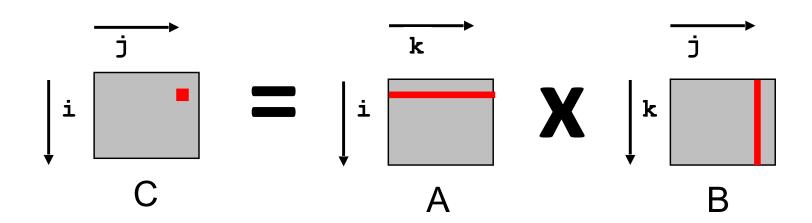
Matrix Multiplication Example

- Multiply N x N matrices
- Matrix elements are doubles (8 bytes)
- O(N³) total operations



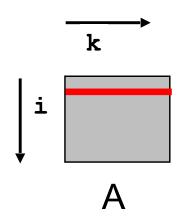
Miss Rate Analysis for Matrix Multiply

- Assume:
 - Block size = 32B (big enough for four doubles)
 - Matrix dimension (N) is very large
 - Approximate 1/N as 0.0
 - Cache is not even big enough to hold multiple rows
- Analysis Method:
 - Look at access pattern of inner loop



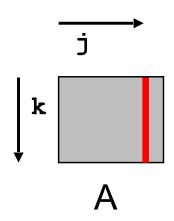
Layout of C Arrays in Memory (review)

- C arrays allocated in row-major order
 - each row in contiguous memory locations
- Stepping through columns in one row:
 - for (i = 0; i < N; i++)
 sum += a[0][i];
 - accesses successive elements
 - cache line size (32) > size of an element (8 bytes), exploiting spatial locality!
 - miss rate = 8 / 32 = 25%



Layout of C Arrays in Memory (review)

- C arrays allocated in row-major order
 - each row in contiguous memory locations
- Stepping through rows in one column:
 - for (i = 0; j < n; j++)
 sum += a[i][0];
 - accesses distant elements
 - no spatial locality!
 - miss rate = 1 (i.e. 100%)

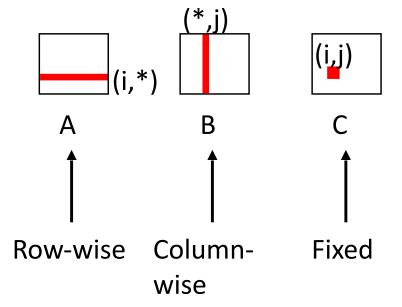


Matrix Multiplication (ijk)

```
/* ijk */
for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    sum = 0.0;
    for (k=0; k<n; k++)
        sum += a[i][k] * b[k][j];
    c[i][j] = sum;
  }
}

matmult/mm.c</pre>
```

Inner loop:



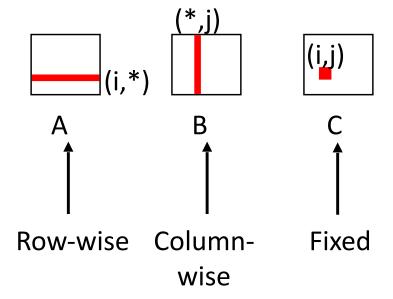
Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.25	1.0	0.0

Matrix Multiplication (jik)

```
/* jik */
for (j=0; j<n; j++) {
  for (i=0; i<n; i++) {
    sum = 0.0;
    for (k=0; k<n; k++)
        sum += a[i][k] * b[k][j];
    c[i][j] = sum
  }
}
</pre>
```

Inner loop:

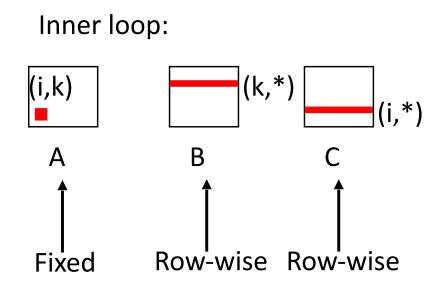


Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
0.25	1.0	0.0

Matrix Multiplication (kij)

```
/* kij */
for (k=0; k<n; k++) {
  for (i=0; i<n; i++) {
    r = a[i][k];
    for (j=0; j<n; j++)
        c[i][j] += r * b[k][j];
  }
}
matmult/mm.c</pre>
```



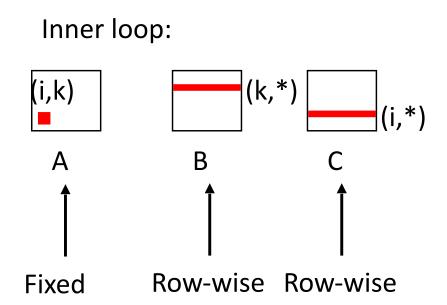
Misses per inner loop iteration:

<u>A</u> <u>B</u> <u>C</u> 0.0 0.25 0.25

Matrix Multiplication (ikj)

```
/* ikj */
for (i=0; i<n; i++) {
  for (k=0; k<n; k++) {
    r = a[i][k];
  for (j=0; j<n; j++)
    c[i][j] += r * b[k][j];
}

matmult/mm.c</pre>
```



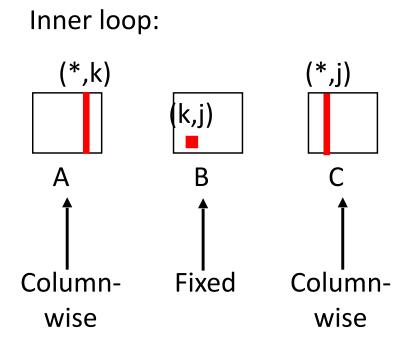
Misses per inner loop iteration:

<u>A</u> <u>B</u> <u>C</u> 0.0 0.25 0.25

Matrix Multiplication (jki)

```
/* jki */
for (j=0; j<n; j++) {
  for (k=0; k<n; k++) {
    r = b[k][j];
    for (i=0; i<n; i++)
        c[i][j] += a[i][k] * r;
  }
}

matmult/mm.c</pre>
```



Misses per inner loop iteration:

<u>A</u> <u>B</u> <u>C</u> 1.0 0.0 1.0

Matrix Multiplication (kji)

```
/* kji */
for (k=0; k<n; k++) {
  for (j=0; j<n; j++) {
    r = b[k][j];
  for (i=0; i<n; i++)
    c[i][j] += a[i][k] * r;
  }
}
matmult/mm.c</pre>
```

(*,k) A B C Columnwise (*,j) Columnwise (*,j) Columnwise

Inner loop:

Misses per inner loop iteration:

<u>A</u>	<u>B</u>	<u>C</u>
1.0	0.0	1.0

Summary of Matrix Multiplication

```
for (i=0; i<n; i++) {
  for (j=0; j<n; j++) {
    sum = 0.0;
  for (k=0; k<n; k++)
    sum += a[i][k] * b[k][j];
  c[i][j] = sum;
}
}</pre>
```

```
for (k=0; k<n; k++) {
  for (i=0; i<n; i++) {
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}</pre>
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```
for (j=0; j<n; j++) {
  for (k=0; k<n; k++) {
    r = b[k][j];
  for (i=0; i<n; i++)
    c[i][j] += a[i][k] * r;
}</pre>
```

ijk (& jik):

- 2 loads, 0 stores
- misses/iter = **1.25**

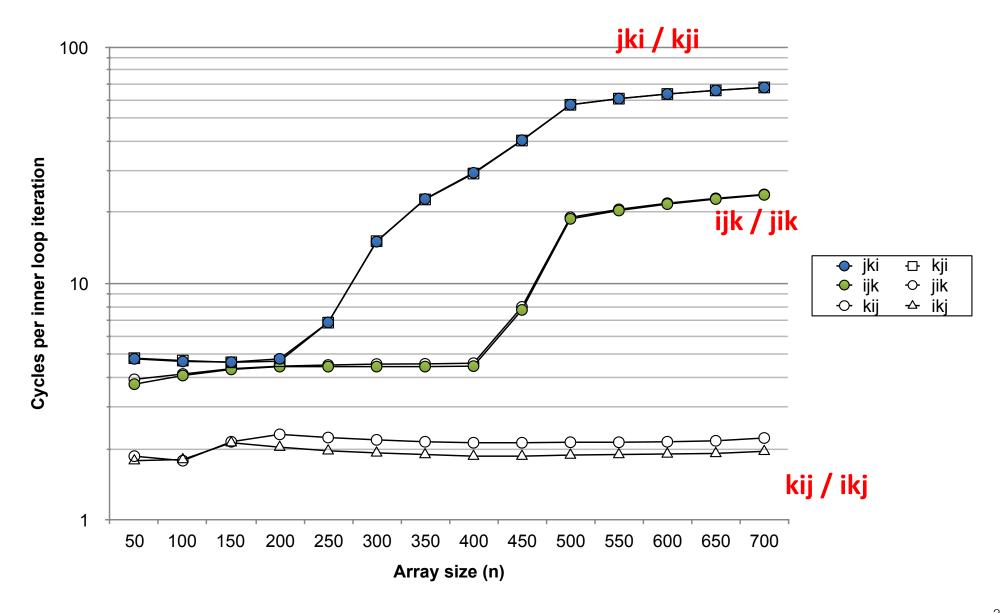
kij (& ikj):

- 2 loads, 1 store
- misses/iter = **0.5**

jki (& kji):

- 2 loads, 1 store
- misses/iter = **2.0**

Core i7 Matrix Multiply Performance



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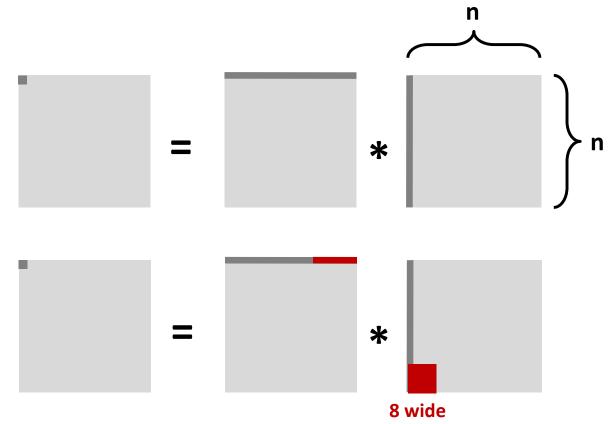
Optimizing Irregular and dynamic applications [32]

Example: Matrix Multiplication

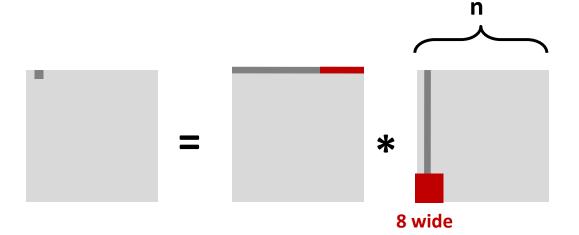


- Assume:
 - Matrix elements are doubles
 - Cache block = 8 doubles
 - Cache size C << n (much smaller than n)
- First iteration:

• n/8 + n = 9n/8 misses

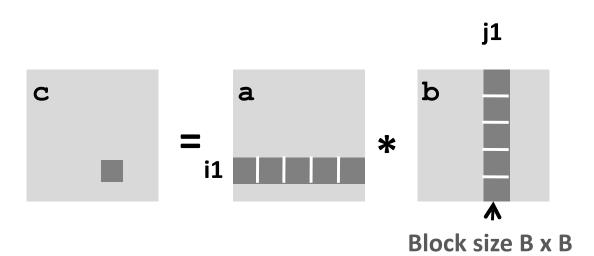


- Assume:
 - Matrix elements are doubles
 - Cache block = 8 doubles
 - Cache size C << n (much smaller than n)
- Second iteration:
 - Again: n/8 + n = 9n/8 misses

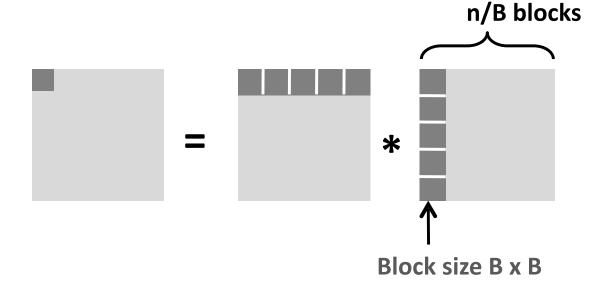


- Total misses:
 - $9n/8 * n^2 = (9/8) * n^3$

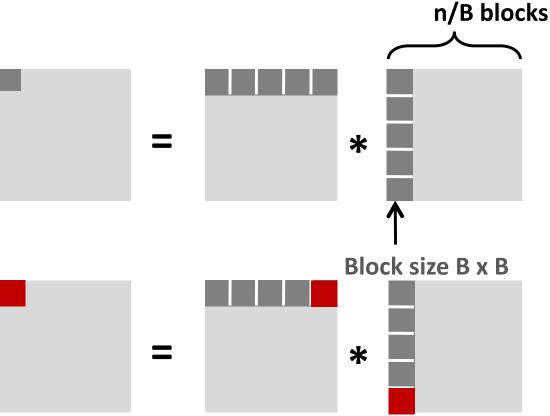
Blocked Matrix Multiplication



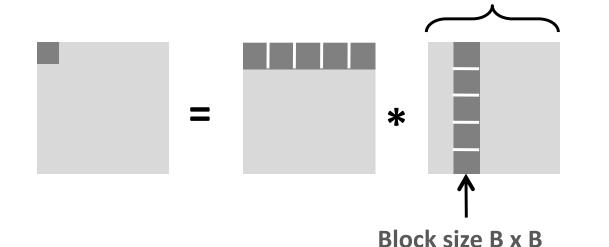
- Assume:
 - Cache block = 8 doubles
 - Cache size C << n (much smaller than n)
 - Three blocks fit into cache: 3B² < C
- First (block) iteration:



- Assume:
 - Cache block = 8 doubles
 - Cache size C << n (much smaller than n)
 - Three blocks fit into cache: 3B² < C
- First (block) iteration:
 - B²/8 misses for each block
 - $2n/B * B^2/8 = nB/4$



- Assume:
 - Cache block = 8 doubles
 - Cache size C << n (much smaller than n)
 - Three blocks fit into cache: 3B² < C
- Second (block) iteration:
 - Same as first iteration
 - $2n/B * B^2/8 = nB/4$



- Total misses:
 - $nB/4 * (n/B)^2 = n^3/(4B)$

n/B blocks

Blocking Summary

- No blocking: (9/8) * n³
- Blocking: 1/(4B) * n³
- Suggest largest possible block size B, but limit $3B^2 < C!$
- Reason for dramatic difference:
 - Matrix multiplication has inherent temporal locality:
 - Input data: 3n², computation 2n³
 - Every array elements used O(n) times!
 - But program has to be written properly

Cache Summary

- Cache memories can have significant performance impact
- You can write your programs to exploit this!
 - Focus on the inner loops, where bulk of computations and memory accesses occur.
 - Try to maximize spatial locality by reading data objects with sequentially with stride 1.
 - Try to maximize temporal locality by using a data object as often as possible once it's read from memory.

Dynamic Optimizations [PLDI'99, with Ken Kennedy]

Unknown Access

"Every problem can be solved by adding one more level of indirection."

- Irregular and dynamic applications
 - Irregular data structures are unknown until run time
 - Data and their uses may change during the computation
- For example
 - Molecular dynamics
 - Sparse matrix
- Problems
 - How to optimize at run time?
 - How to automate?

Example packing original f[1] f[2] f[3] array data f[8], f[800], f[8], f[2], access *'transformed'* f[800] f[8] f[2] array Software remapping: $f[t[i]] \rightarrow f[remap[t[i]]] \rightarrow f[t'[i]]$ $f[i] \rightarrow f[remap[i]] \rightarrow f[i]$

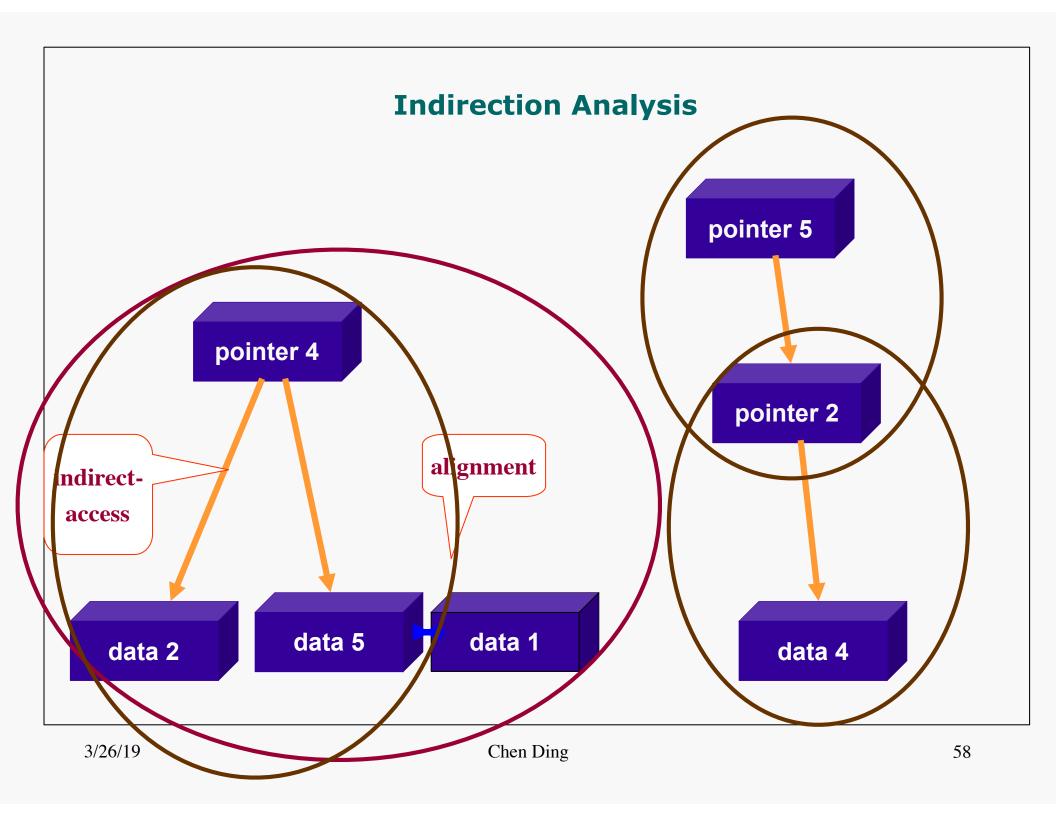
Dynamic Optimizations

- · Locality grouping & Dynamic packing
 - run-time versions of computation fusion & data grouping
 - linear time and space cost
- Compiler support
 - analyze data indirections
 - find all optimization candidates
 - use run-time maps to guarantee correctness
 - remove unnecessary remappings
 - pointer update
 - · array alignment
- The first set of compiler-generated run-time transformations

```
packing Directive: apply packing using interactions
for each pair (i,j) in interactions
   compute_force( force[i], force[j] )
end for

for each object i
   update_location( location[i], force[i] )
end for
```

```
apply packing(interactions[*],force[*],
              inter map[*], update map[*])
update indirection array(interactions[*],
                         update map[*])
transform data array(location[*], update map[*])
for each pair (i,j) in interactions
   compute force( force[i], force[j] )
end for
for each object i
  update location( location[i], force[i] )
end for
```



DoD/Magi

A real application from DoD Philips Lab

- particle hydrodynamics
- almost 10,000 lines of code
- user supplied input of 28K particles
- 22 arrays in major phases, split into 26

Optimizations

- grouped into 6 arrays
- inserted 1114 indirections to guarantee correctness
- optimization reorganized 19 more arrays
- removed 379 indirections in loops
- reorganized 45 arrays 4 times during execution

