

CSC 252: Computer Organization

Spring 2022: Lecture 10

Instructor: Yuhao Zhu

Department of Computer Science
University of Rochester

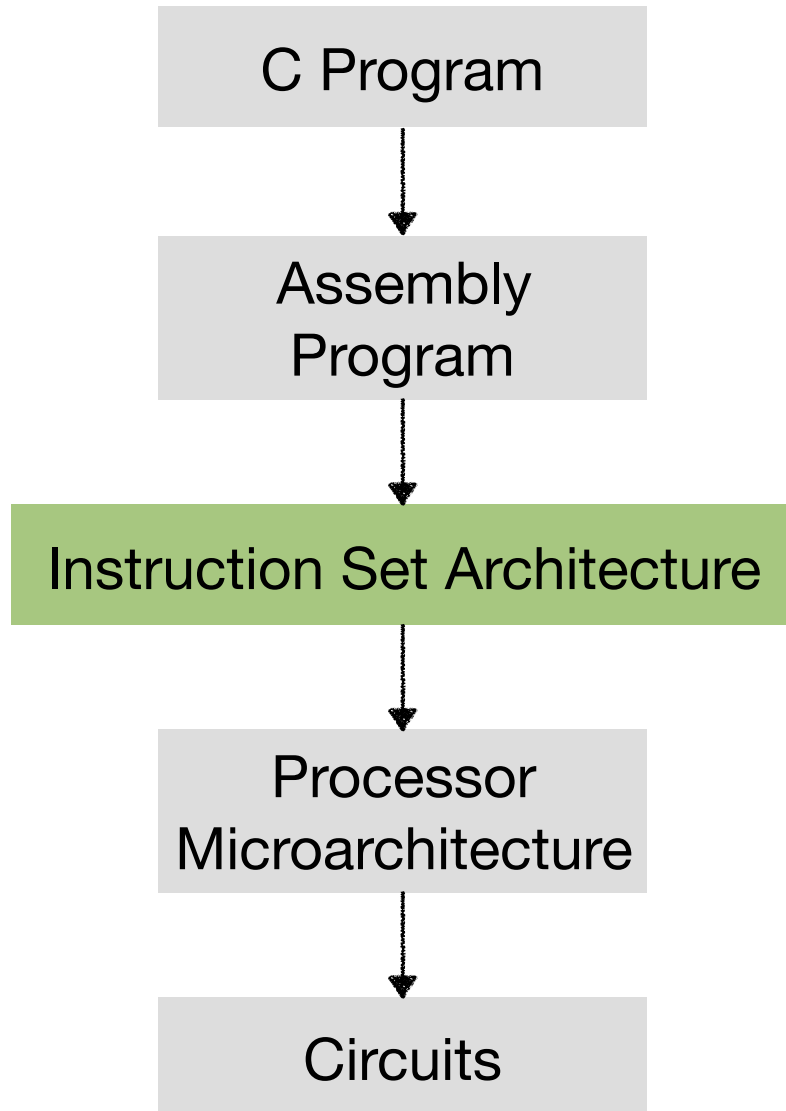
Announcement

- Programming assignment 1 grades are out.
 - If you see any issue, take a deep breath and talk to a TA. We will correct any mistakes on our part. We are your friends, not your enemies actively trying to penalize you.
- Programming assignment 2 is due midnight today.
- Programming assignment 3 will be released today.

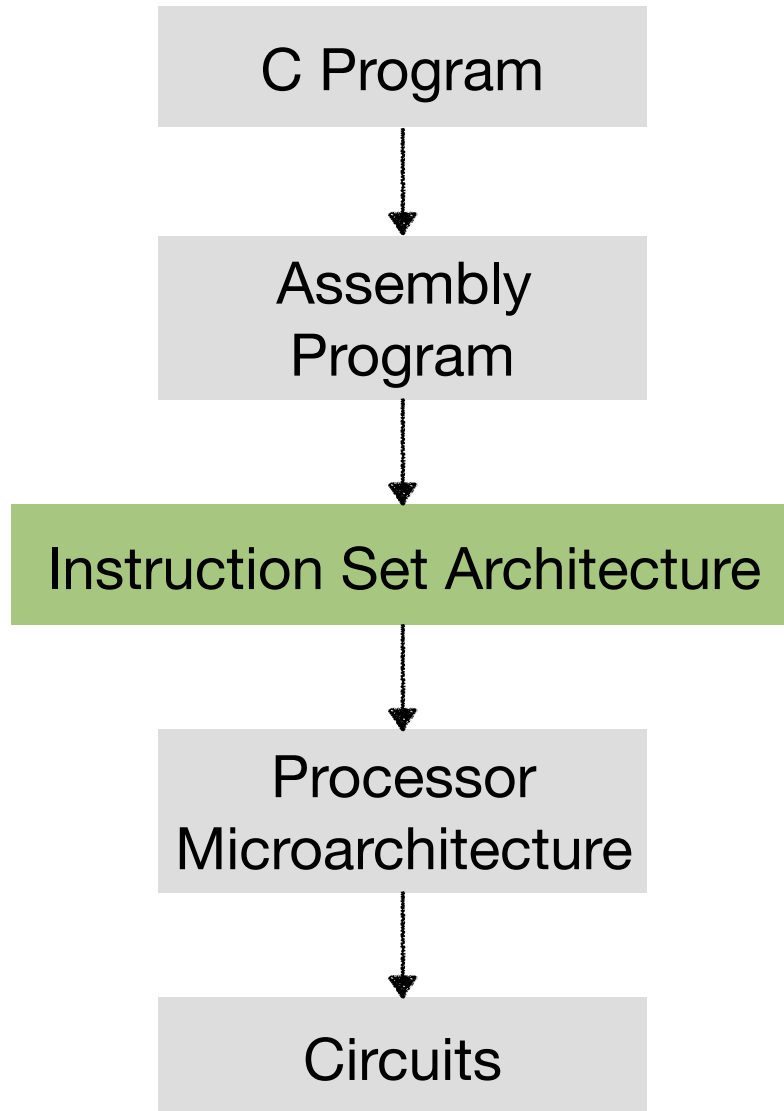
Announcement

- TAs are best positioned to answer your questions about programming assignments!!!
- Programming assignments do NOT repeat the lecture materials. They ask you to synthesize what you have learned from the lectures and work out something new.
- Problem set on arithmetics: <https://www.cs.rochester.edu/courses/252/spring2021/handouts.html>.
 - Not to be turned in.

So far in 252...

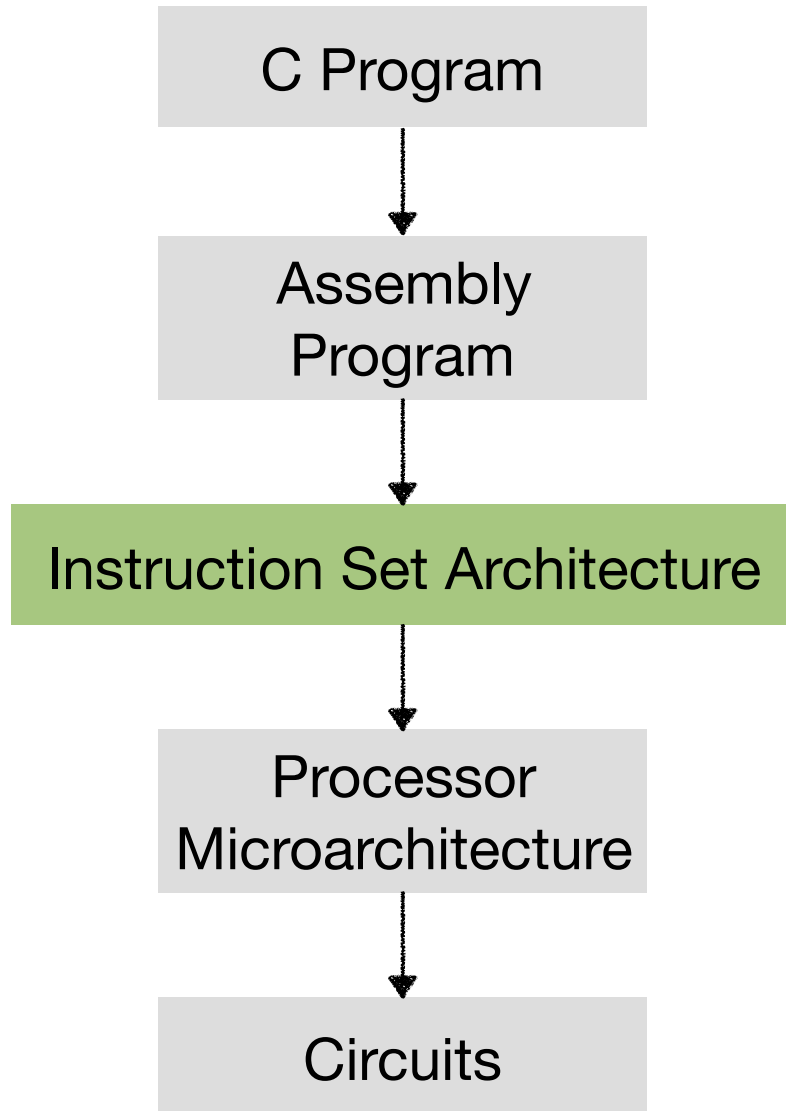


So far in 252...



`ret, call`
`movq, addq`
`jmp, jne`

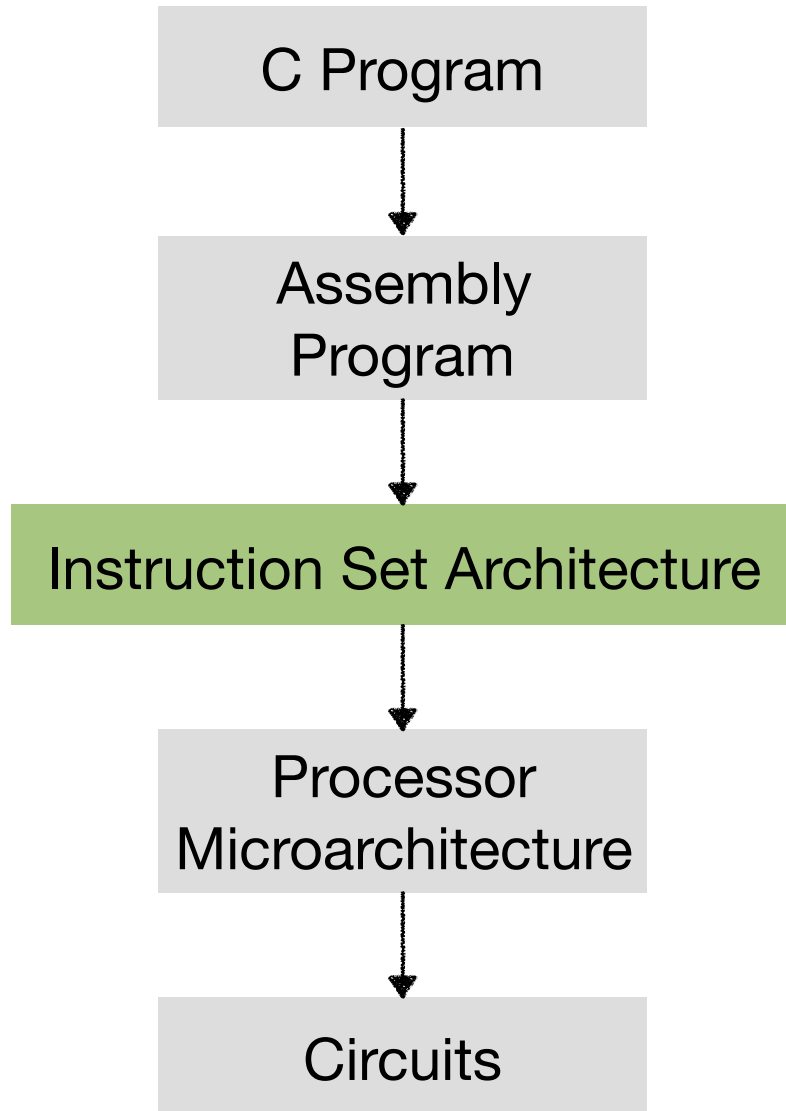
So far in 252...



```
movq    %rsi, %rax
imulq   %rdx, %rax
jmp     .done
```

```
ret, call
movq, addq
jmp, jne
```

So far in 252...

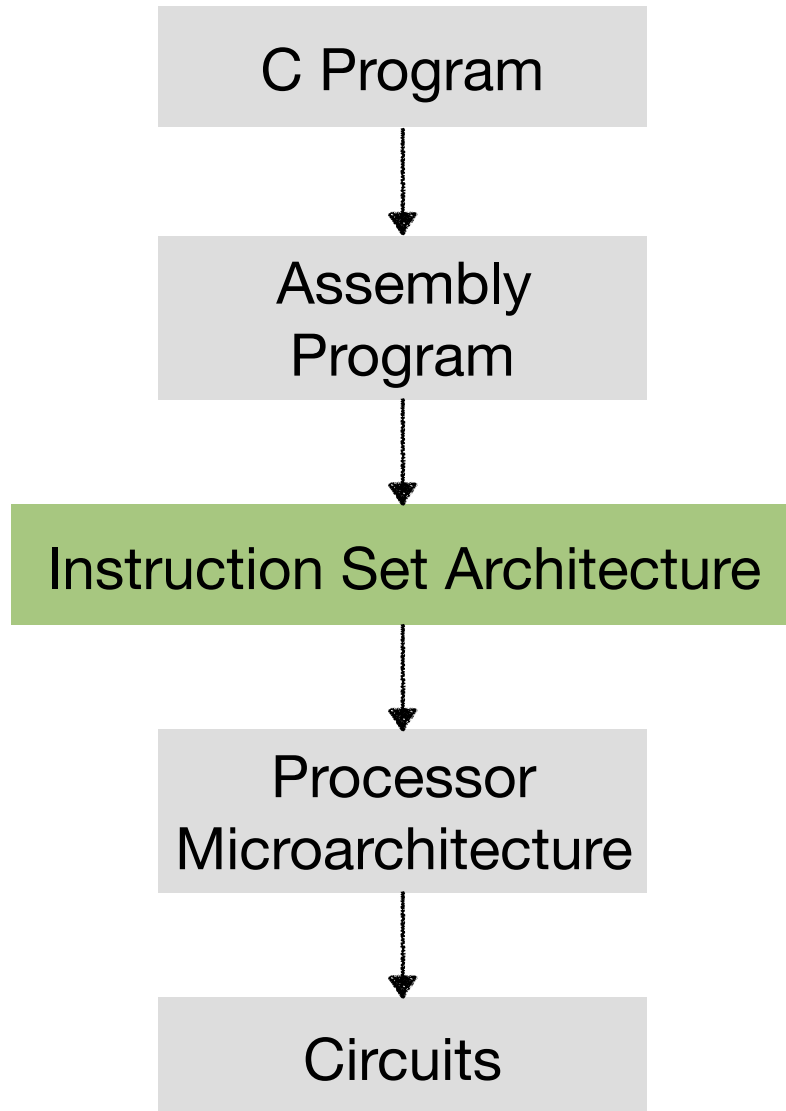


```
int, float  
if, else  
+, -, >>
```

```
movq    %rsi, %rax  
imulq   %rdx, %rax  
jmp     .done
```

```
ret, call  
movq, addq  
jmp, jne
```

So far in 252...



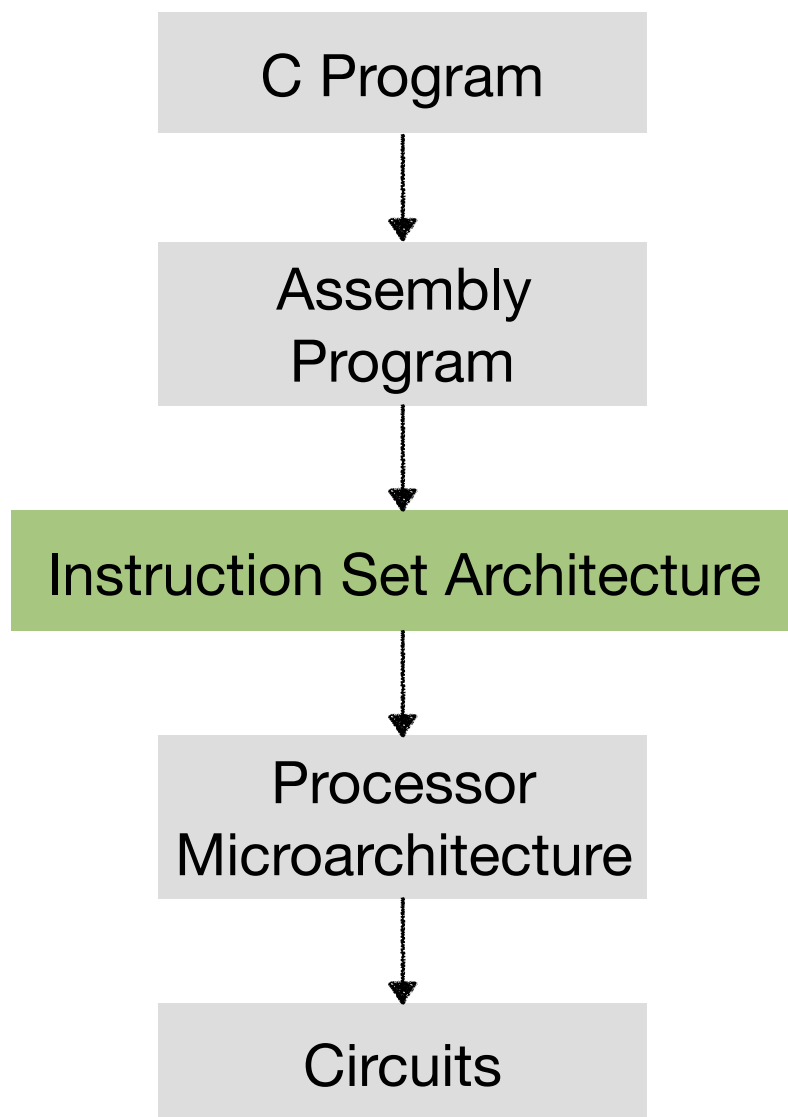
```
int, float  
if, else  
+, -, >>
```

```
movq    %rsi, %rax  
imulq   %rdx, %rax  
jmp     .done
```

```
ret, call  
movq, addq  
jmp, jne
```

Logic gates

So far in 252...



int, float
if, else
+, -, >>

```
movq    %rsi, %rax  
imulq   %rdx, %rax  
jmp     .done
```

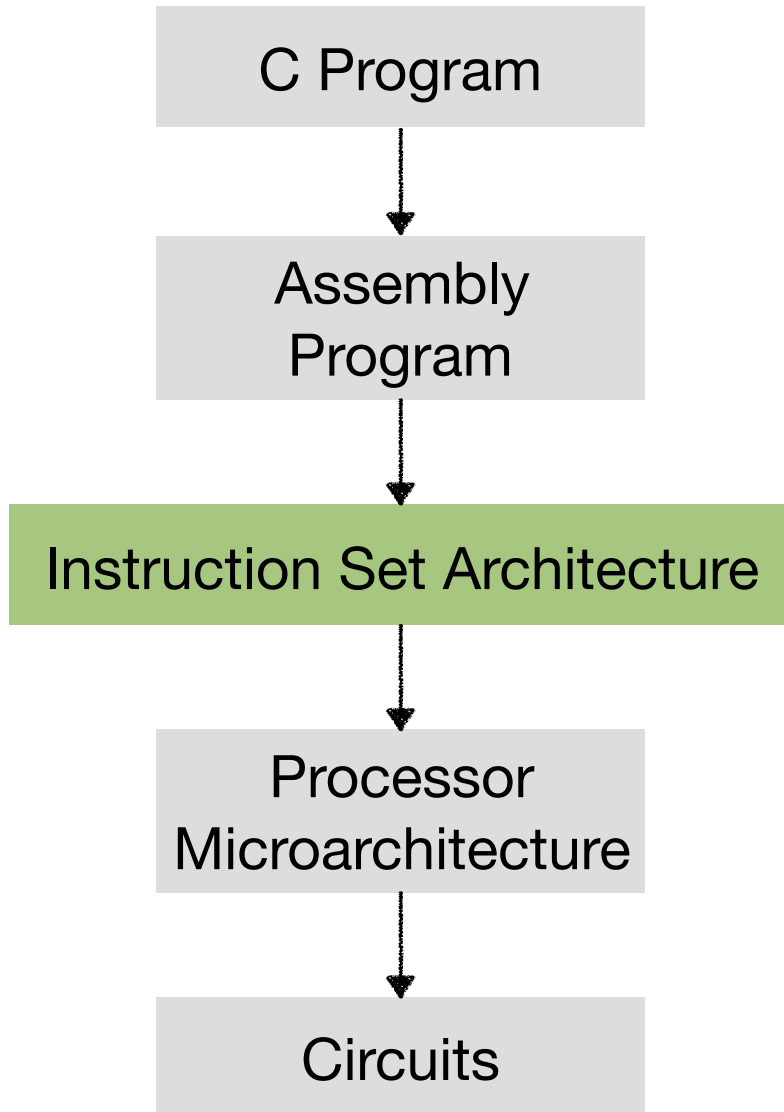
```
ret, call  
movq, addq  
jmp, jne
```

Logic gates

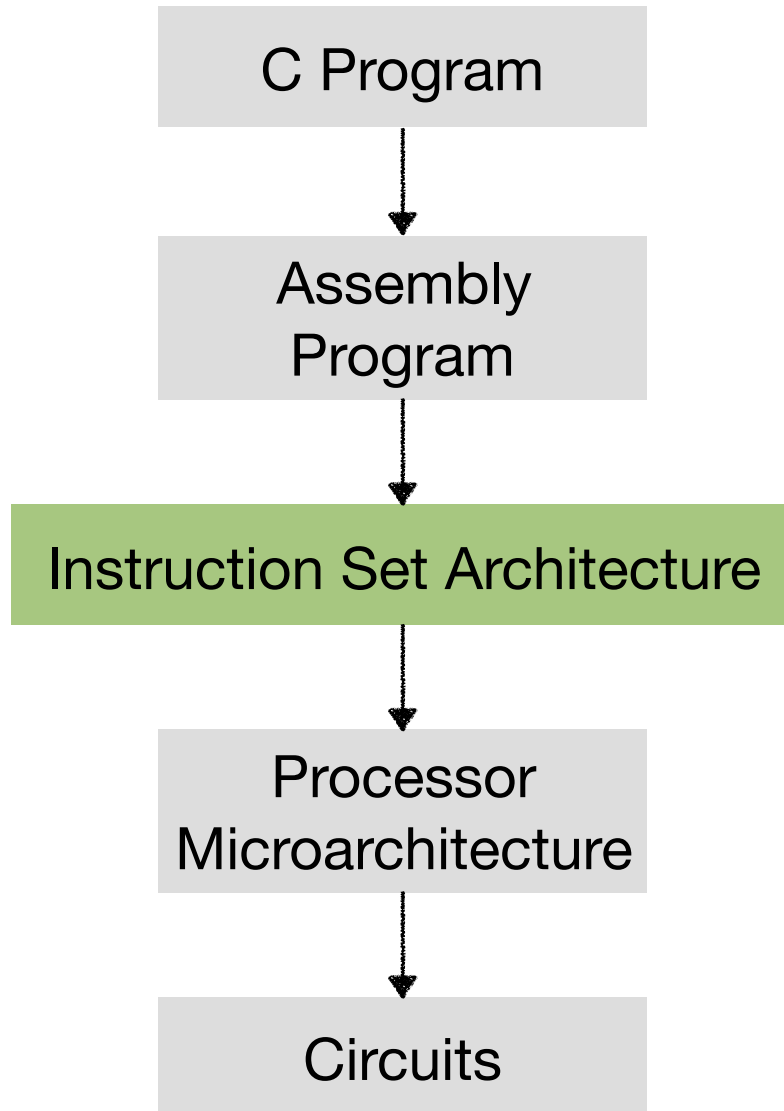
Transistors

So far in 252...

- ISA is the interface between assembly programs and microarchitecture

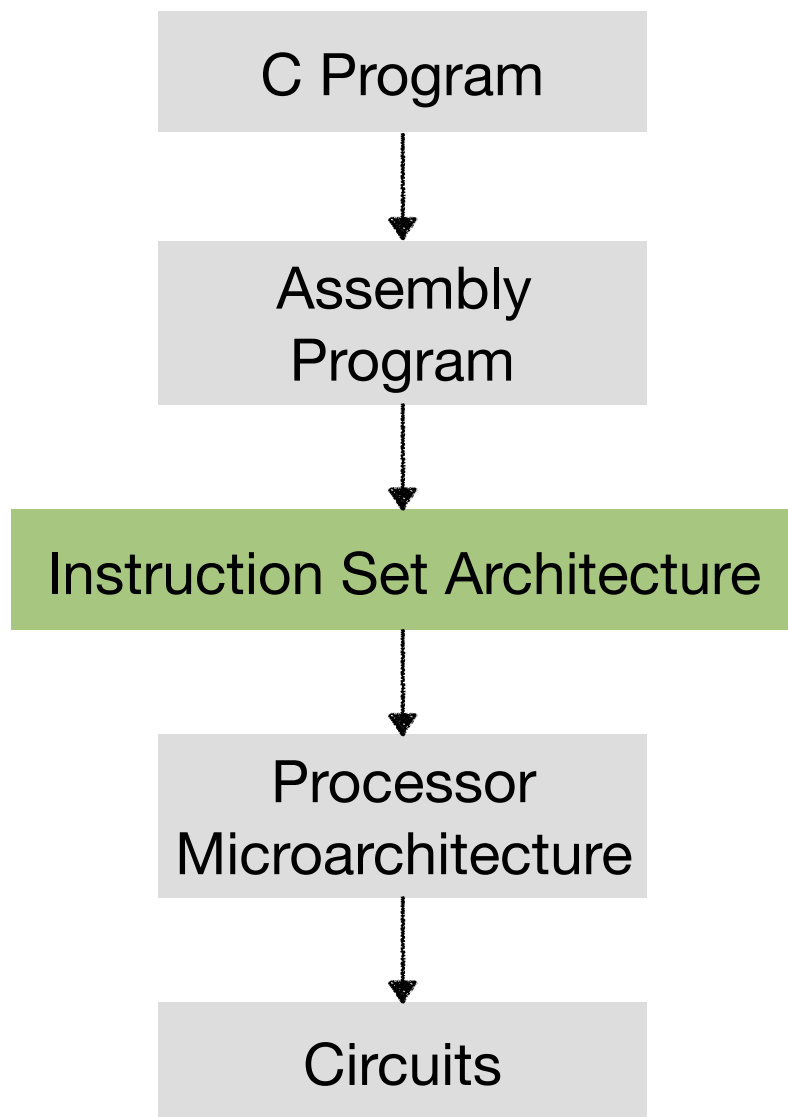


So far in 252...



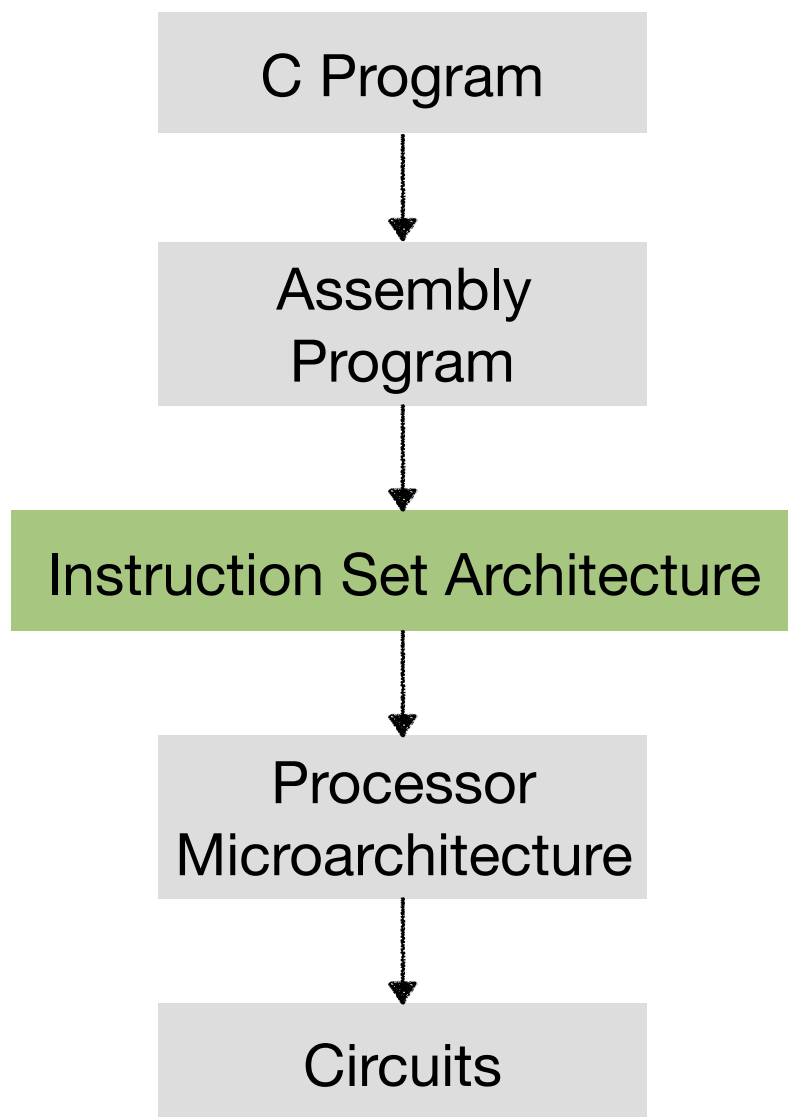
- ISA is the interface between assembly programs and microarchitecture
- Assembly view:

So far in 252...



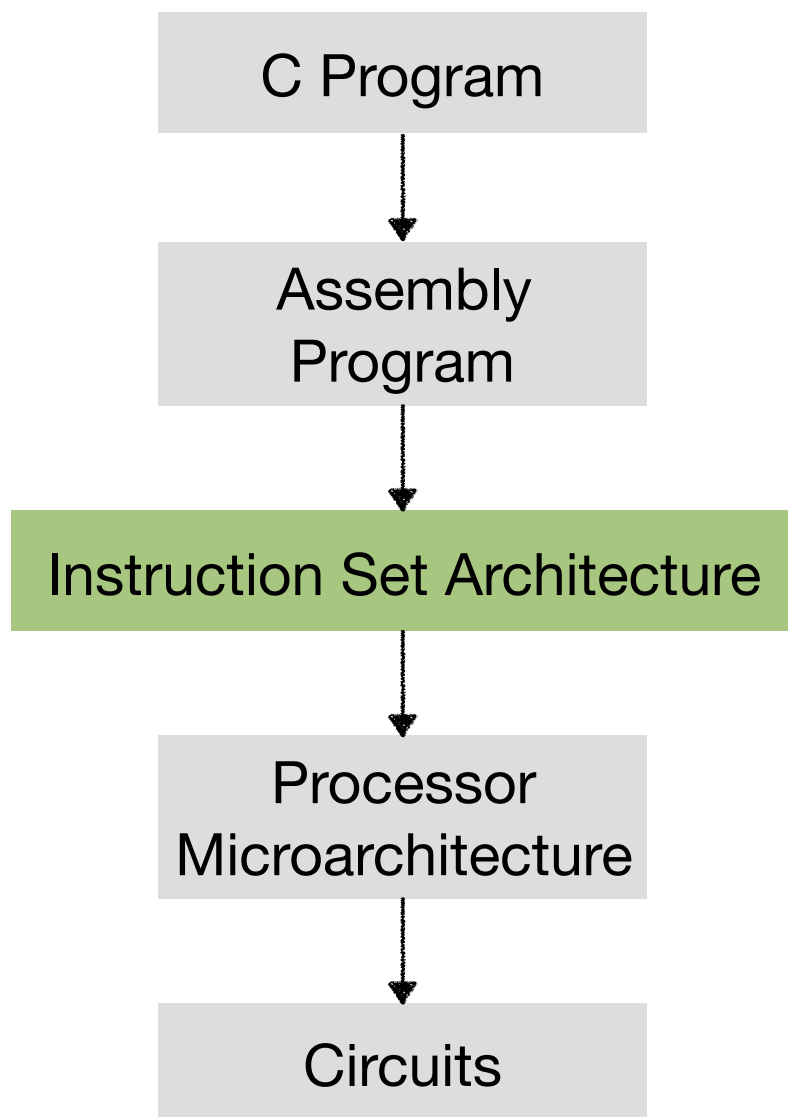
- ISA is the interface between assembly programs and microarchitecture
- Assembly view:
 - How to program the machine, based on instructions and **processor states** (registers, memory, condition codes, etc.)?

So far in 252...



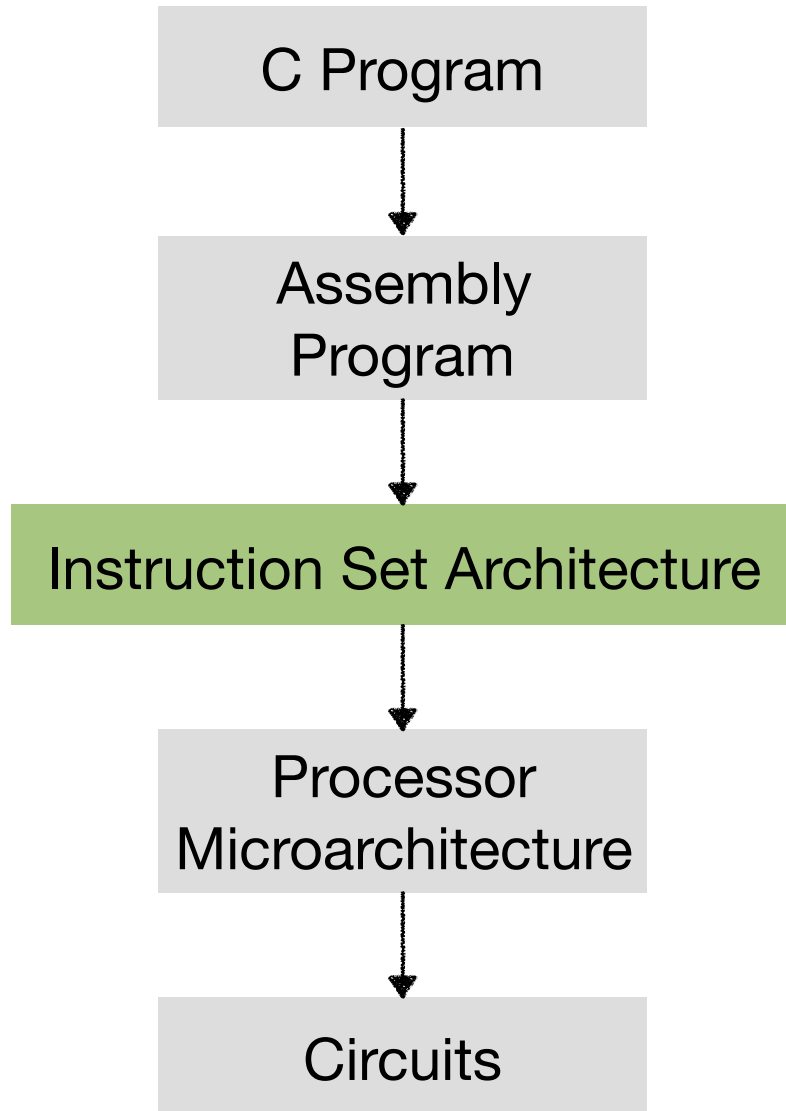
- ISA is the interface between assembly programs and microarchitecture
- Assembly view:
 - How to program the machine, based on instructions and **processor states** (registers, memory, condition codes, etc.)?
 - Instructions are executed sequentially.

So far in 252...



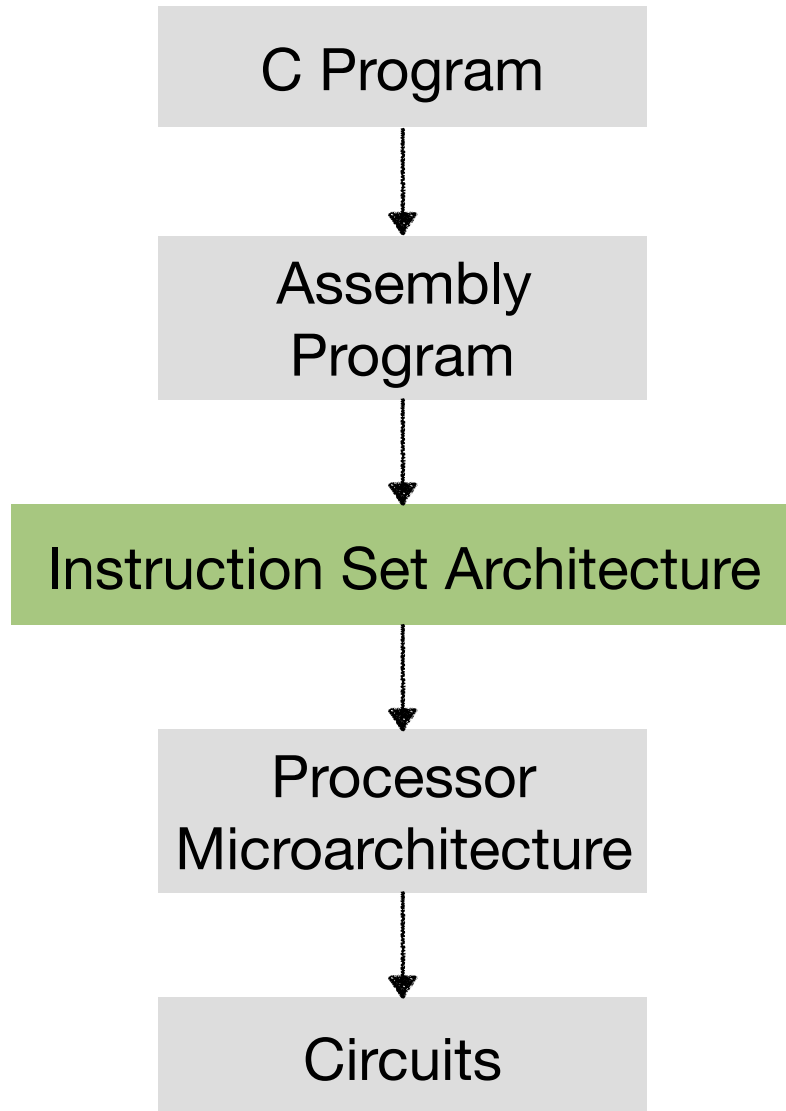
- ISA is the interface between assembly programs and microarchitecture
- Assembly view:
 - How to program the machine, based on instructions and **processor states** (registers, memory, condition codes, etc.)?
 - Instructions are executed sequentially.
- Microarchitecture view:

So far in 252...



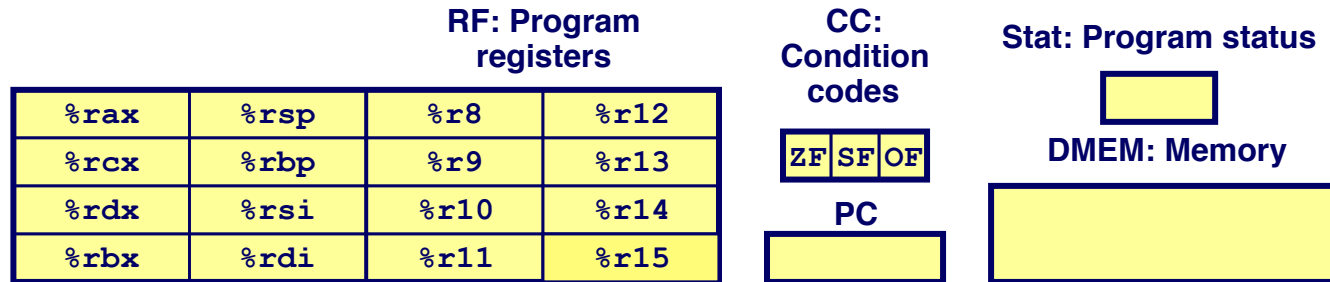
- ISA is the interface between assembly programs and microarchitecture
- Assembly view:
 - How to program the machine, based on instructions and **processor states** (registers, memory, condition codes, etc.)?
 - Instructions are executed sequentially.
- Microarchitecture view:
 - What hardware needs to be built to run assembly programs?

So far in 252...



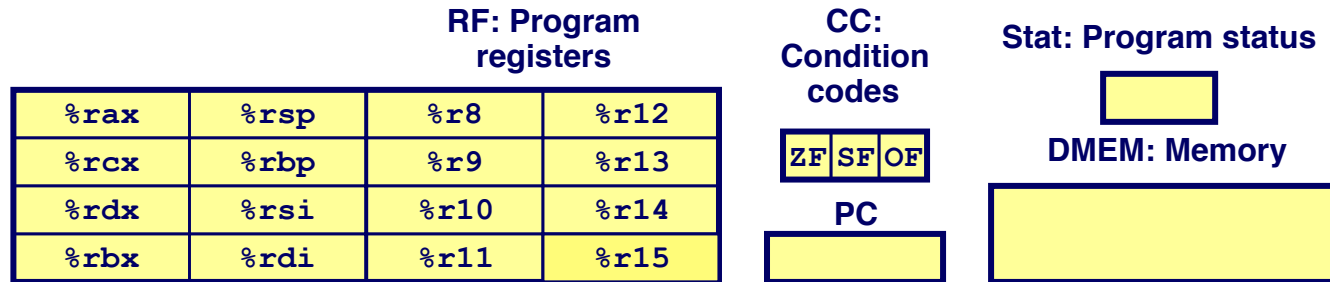
- ISA is the interface between assembly programs and microarchitecture
- Assembly view:
 - How to program the machine, based on instructions and **processor states** (registers, memory, condition codes, etc.)?
 - Instructions are executed sequentially.
- Microarchitecture view:
 - What hardware needs to be built to run assembly programs?
 - How to run programs as fast (energy-efficient) as possible?

(Simplified) x86 Processor State



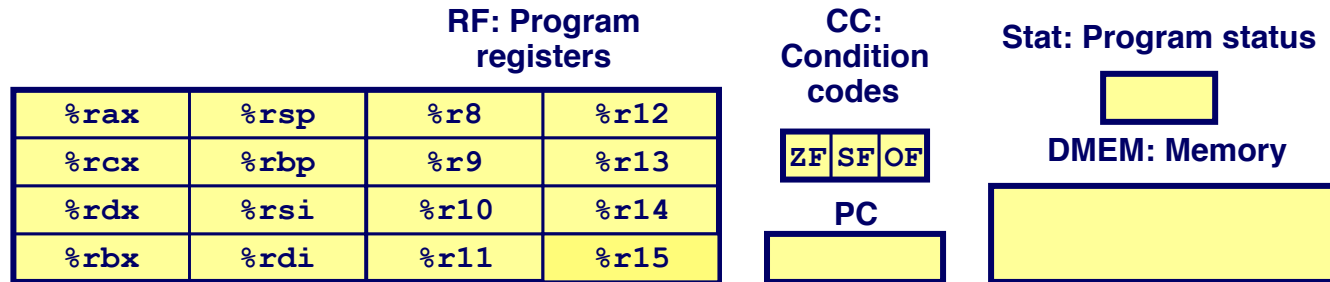
- Processor state is what's visible to assembly programs. Also known as architecture state.

(Simplified) x86 Processor State



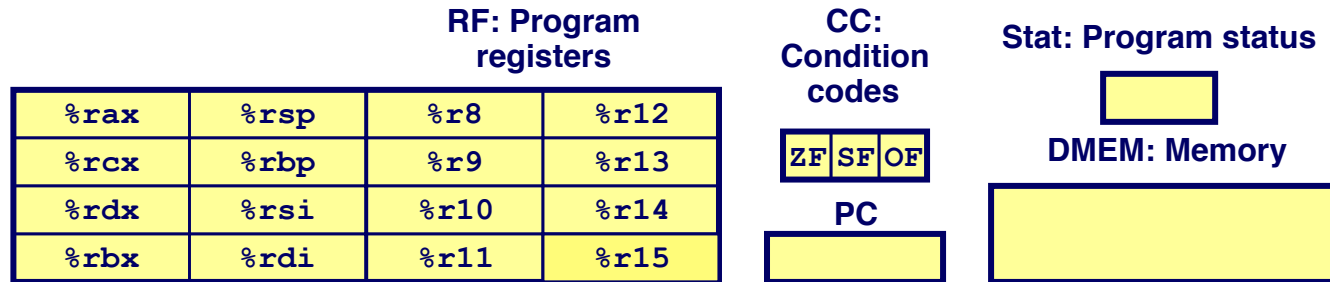
- Processor state is what's visible to assembly programs. Also known as architecture state.
- Program Registers: 16 registers.

(Simplified) x86 Processor State



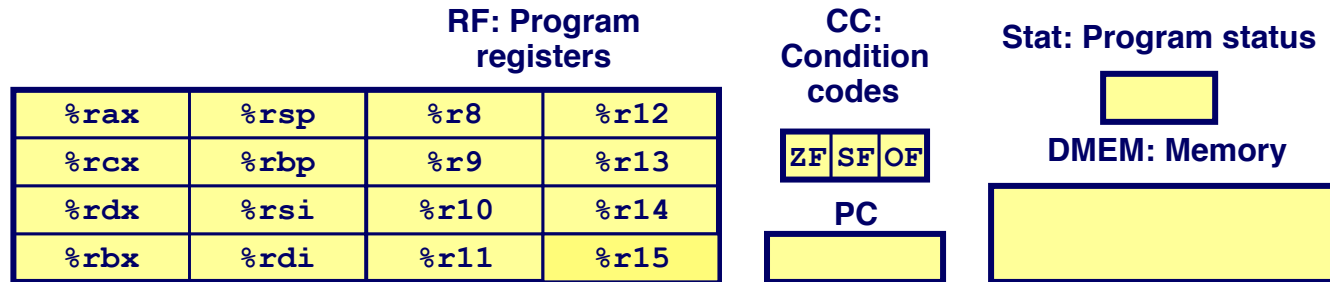
- Processor state is what's visible to assembly programs. Also known as architecture state.
- Program Registers: 16 registers.
- Condition Codes: Single-bit flags set by arithmetic or logical instructions (ZF, SF, OF)

(Simplified) x86 Processor State



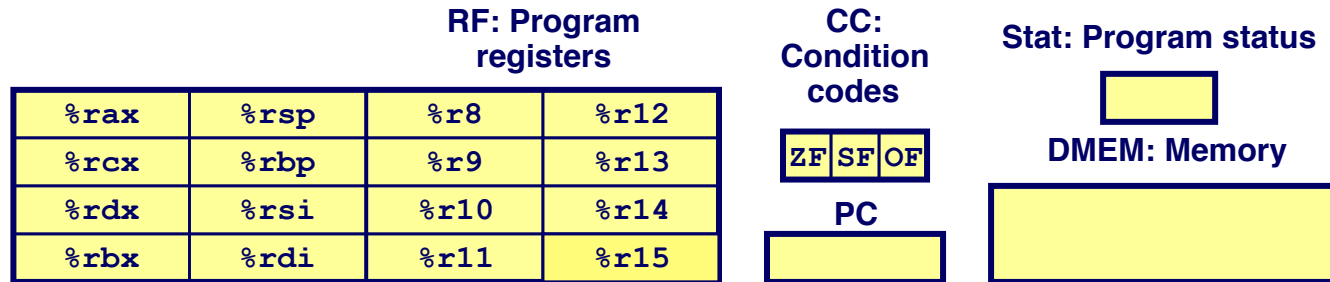
- Processor state is what's visible to assembly programs. Also known as architecture state.
- Program Registers: 16 registers.
- Condition Codes: Single-bit flags set by arithmetic or logical instructions (ZF, SF, OF)
- Program Counter: Indicates address of next instruction

(Simplified) x86 Processor State



- Processor state is what's visible to assembly programs. Also known as architecture state.
- Program Registers: 16 registers.
- Condition Codes: Single-bit flags set by arithmetic or logical instructions (ZF, SF, OF)
- Program Counter: Indicates address of next instruction
- Program Status: Indicates either normal operation or error condition

(Simplified) x86 Processor State



- Processor state is what's visible to assembly programs. Also known as architecture state.
- Program Registers: 16 registers.
- Condition Codes: Single-bit flags set by arithmetic or logical instructions (ZF, SF, OF)
- Program Counter: Indicates address of next instruction
- Program Status: Indicates either normal operation or error condition
- Memory
 - Byte-addressable storage array
 - Words stored in little-endian byte order

Why Have Instructions?

- Why do we need an ISA? Can we directly program the hardware?

Why Have Instructions?

- Why do we need an ISA? Can we directly program the hardware?
- Simplifies interface
 - Software knows what is available
 - Hardware knows what needs to be implemented

Why Have Instructions?

- Why do we need an ISA? Can we directly program the hardware?
- Simplifies interface
 - Software knows what is available
 - Hardware knows what needs to be implemented
- Abstraction protects software and hardware
 - Software can run on new machines
 - Hardware can run old software

Why Have Instructions?

- Why do we need an ISA? Can we directly program the hardware?
- Simplifies interface
 - Software knows what is available
 - Hardware knows what needs to be implemented
- Abstraction protects software and hardware
 - Software can run on new machines
 - Hardware can run old software
- Alternatives: Application-Specific Integrated Circuits (ASIC)
 - No instructions, (largely) not programmable, fixed-functioned, so no instruction fetch, decoding, etc.
 - So could be implemented extremely efficiently.
 - Examples: video/audio codec, (conventional) image signal processors, (conventional) IP packet router

Today: Instruction Encoding

- How to translate assembly instructions to binary
 - Essentially how an assembler works
- Using the Y86-64 ISA: Simplified version of x86-64

How are Instructions Encoded in Binary?

- Remember that instructions are stored in memory **as bits** (just like data)
- Each instruction is fetched (according to the address specified in the PC), decoded, and executed by the CPU
- The ISA defines the format of an instruction (syntax) and its meaning (semantics)
- Idea: encode the two major fields, opcode and operand, separately in bits.
 - The OPCODE field says what the instruction does (e.g. ADD)
 - The OPERAND field(s) say where to find inputs and outputs

Y86-64 Instructions

halt

nop

cmovXX rA, rB

irmovq V, rB

rmmovq rA, D(rB)

mrmovq D(rB), rA

OPq rA, rB

jXX Dest

call Dest

ret

pushq rA

popq rA

Y86-64 Instructions

halt

nop

cmovXX rA, rB

irmovq V, rB

rmmovq rA, D(rB)

mrmovq D(rB), rA

OPq rA, rB

jXX Dest

call Dest

ret

pushq rA

popq rA

jmp

jle

jl

je

jne

jge

jg

Y86-64 Instructions

halt

nop

cmovXX rA, rB

irmovq V, rB

rmmovq rA, D(rB)

mrmovq D(rB), rA

OPq rA, rB

jXX Dest

call Dest

ret

pushq rA

popq rA

addq

subq

andq

xorq

jmp

jle

jl

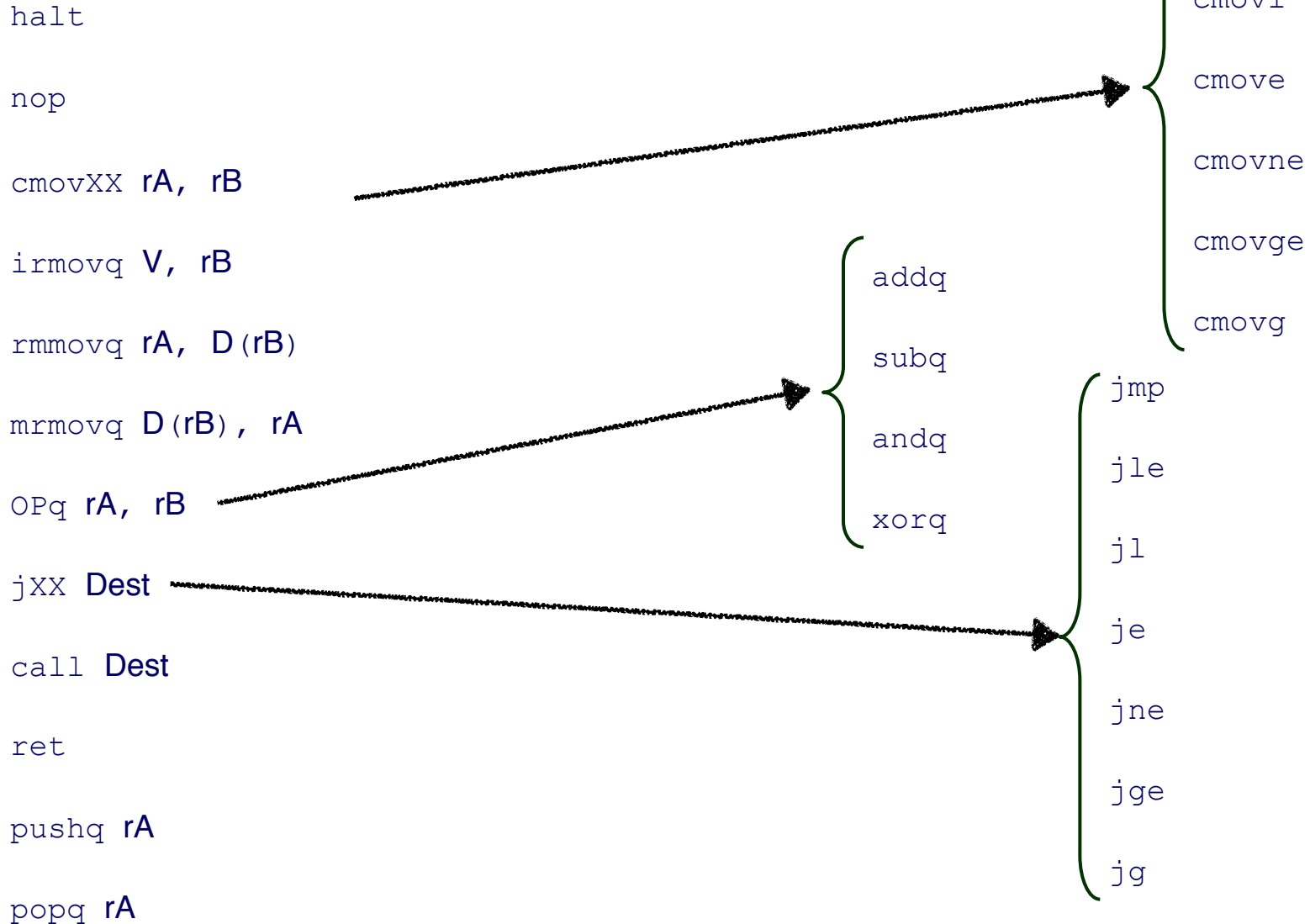
je

jne

jge

jg

Y86-64 Instructions



Y86-64 Instructions

How to encode them in bits?

halt

nop

cmovXX rA, rB

irmovq V, rB

rmmovq rA, D(rB)

mrmovq D(rB), rA

OPq rA, rB

jXX Dest

call Dest

ret

pushq rA

popq rA

rmmovq

cmovle

cmovl

cmove

cmovne

cmovge

cmovg

addq

subq

andq

xorq

jmp

jle

jl

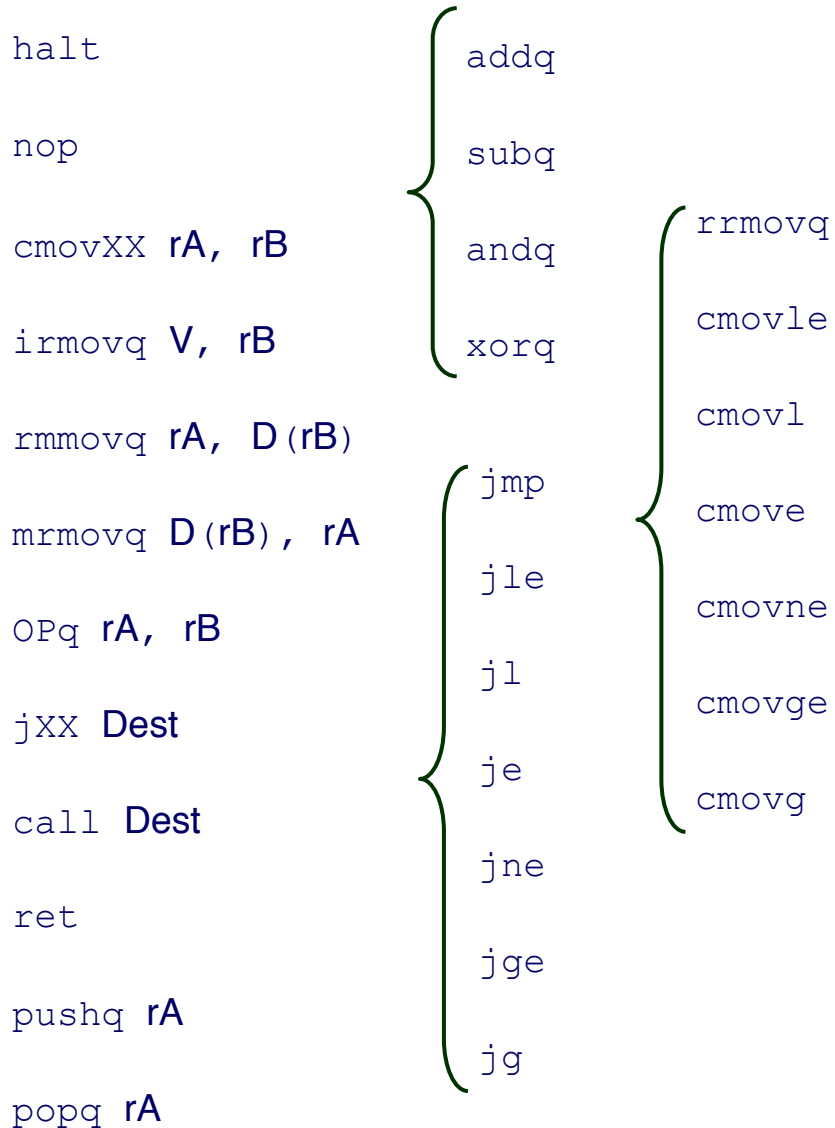
je

jne

jge

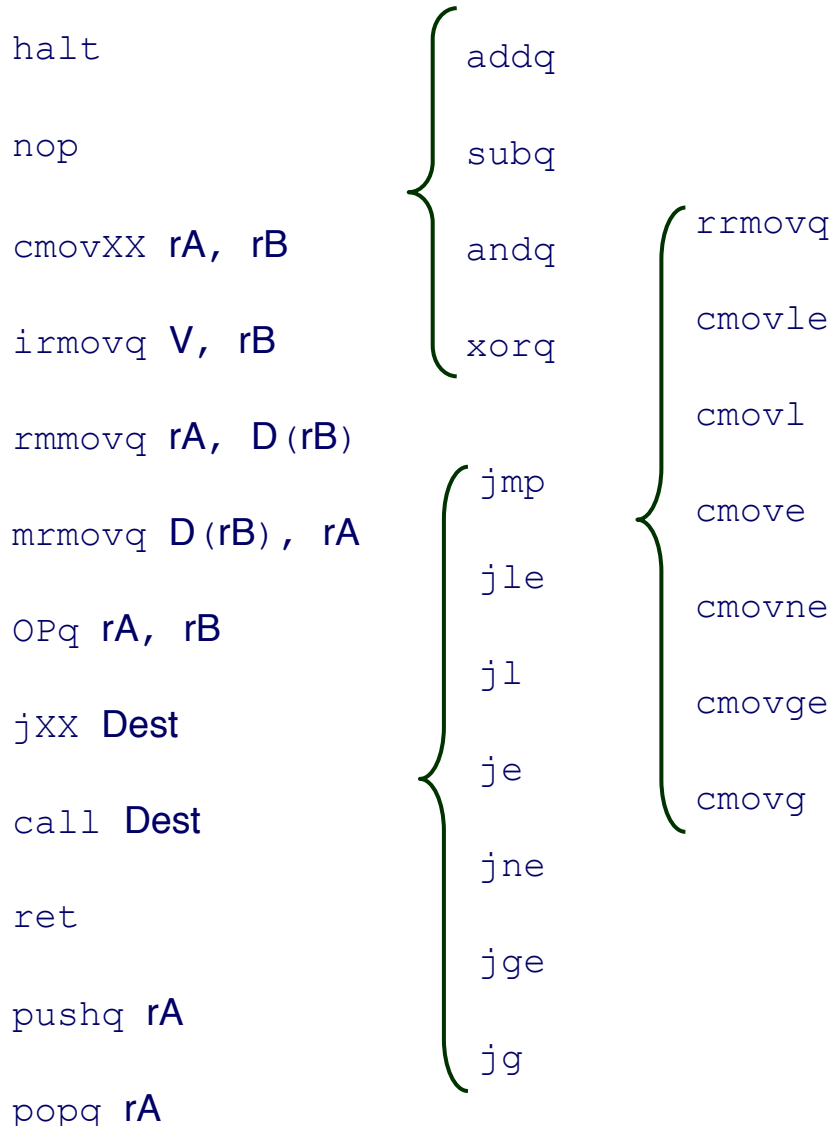
jg

Encoding Operands



- 27 Instructions, so need 5 bits for encoding the operand

Encoding Operands



- 27 Instructions, so need 5 bits for encoding the operand
- Or: group similar instructions, use one opcode for them, and then use more bits to indicate specific instructions within a group.

Encoding Operands

```
halt
nop
cmovXX rA, rB
irmovq V, rB
rmmovq rA, D(rB)
mrmovq D(rB), rA
OPq rA, rB
jXX Dest
call Dest
ret
pushq rA
popq rA
```

addq

subq

andq

xorq

jmp

jle

jl

je

jne

jge

jg

rrmovq

cmovle

cmovl

cmove

cmovne

cmovge

cmovg

- 27 Instructions, so need 5 bits for encoding the operand
- Or: group similar instructions, use one opcode for them, and then use more bits to indicate specific instructions within a group.
- E.g., 12 categories, so 4 bits

Encoding Operands

halt
nop
cmovXX rA, rB
irmovq V, rB
rrmovq rA, D(rB)
mrmovq D(rB), rA
OPq rA, rB
jXX Dest
call Dest
ret
pushq rA
popq rA

addq
subq
andq
xorq

jmp
jle
jl
je
jne
jge
jg

rrmovq
cmovle
cmovl
cmove
cmovne
cmovge
cmovg

- 27 Instructions, so need 5 bits for encoding the operand
- Or: group similar instructions, use one opcode for them, and then use more bits to indicate specific instructions within a group.
- E.g., 12 categories, so 4 bits
- There are four instructions within the OPq category, so additional 2 bits. Similarly, 3 more bits for jXX and cmovXX, respectively.

Encoding Operands

halt
nop
cmovXX rA, rB
irmovq V, rB
rrmovq rA, D(rB)
mrmovq D(rB), rA
OPq rA, rB
jXX Dest
call Dest
ret
pushq rA
popq rA

addq
subq
andq
xorq

jmp
jle
jl
je
jne
jge
jg

rrmovq
cmovle
cmovl
cmove
cmovne
cmovge
cmovg

- 27 Instructions, so need 5 bits for encoding the operand
- Or: group similar instructions, use one opcode for them, and then use more bits to indicate specific instructions within a group.
- E.g., 12 categories, so 4 bits
- There are four instructions within the OPq category, so additional 2 bits. Similarly, 3 more bits for jXX and cmovXX, respectively.
- Which one is better???

Encoding Operands

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn								
irmovq V, rB	3	0								
rmmovq rA, D(rB)	4	0								
mrmmovq D(rB), rA	5	0								
OPq rA, rB	6	fn								
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0								
popq rA	B	0								

- Design decision chosen by the textbook authors (don't have to be this way!)
 - Use 4 bits to encode the instruction category
 - Another 4 bits to encode the specific instructions within a category
 - So 1 bytes for encoding operand
 - Is this better than the alternative of using 5 bits without classifying instructions?
 - Trade-offs.

Encoding Registers

Each register has 4-bit ID

- Same encoding as in x86-64
- Register ID 15 (0xF) indicates “no register”

%rax	0	%r8	8
%rcx	1	%r9	9
%rdx	2	%r10	A
%rbx	3	%r11	B
%rsp	4	%r12	C
%rbp	5	%r13	D
%rsi	6	%r14	E
%rdi	7	No Register	F

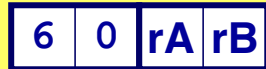
Encoding Registers

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB						
rmmovq rA, D(rB)	4	0	rA	rB						
mrmovq D(rB), rA	5	0	rA	rB						
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Instruction Example

Addition Instruction

`addq rA, rB`



- Add value in register rA to that in register rB
 - Store result in register rB
- Set condition codes based on result
- e.g., `addq %rax,%rsi` Encoding: 60 06
- Two-byte encoding
 - First indicates instruction type
 - Second gives source and destination registers

Instruction Example

Addition Instruction

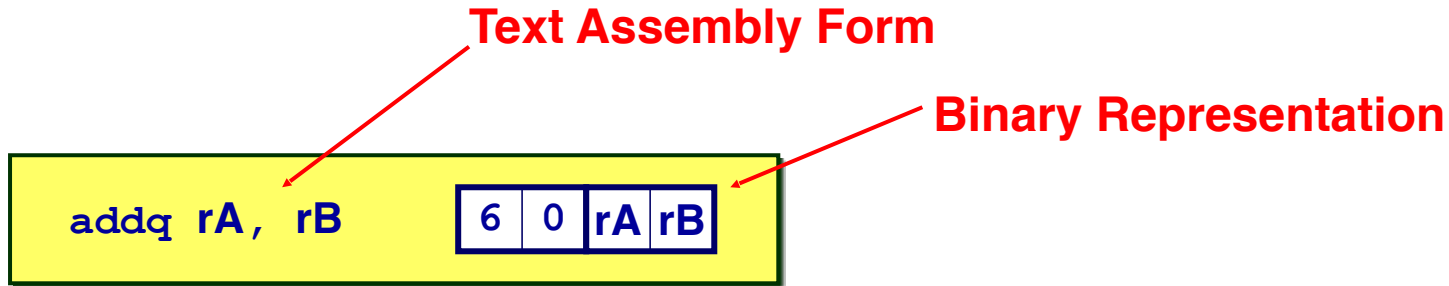
Text Assembly Form



- Add value in register rA to that in register rB
 - Store result in register rB
- Set condition codes based on result
- e.g., `addq %rax, %rsi` Encoding: 60 06
- Two-byte encoding
 - First indicates instruction type
 - Second gives source and destination registers

Instruction Example

Addition Instruction



- Add value in register rA to that in register rB
 - Store result in register rB
- Set condition codes based on result
- e.g., `addq %rax, %rsi` Encoding: 60 06
- Two-byte encoding
 - First indicates instruction type
 - Second gives source and destination registers

Arithmetic and Logical Operations

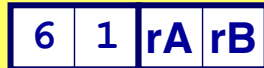
Add

`addq rA, rB`



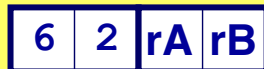
Subtract (rA from rB)

`subq rA, rB`



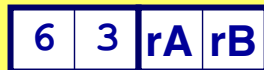
And

`andq rA, rB`



Exclusive-Or

`xorq rA, rB`



- Referred to generically as “OPq”
- Encodings differ only by “function code”
 - Low-order 4 bytes in first instruction word
- Set condition codes as side effect

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB						
rmmovq rA, D(rB)	4	0	rA	rB						
mrmovq D(rB), rA	5	0	rA	rB						
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB						
rmmovq rA, D(rB)	4	0	rA	rB						
mrmovq D(rB), rA	5	0	rA	rB						
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

irmovq \$0xabcd, %rdx

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB						
mrmovq D(rB), rA	5	0	rA	rB						
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	rmmovq %rsi,0x41c(%rsp)					
mrmovq D(rB), rA	5	0	rA	rB						
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmovq D(rB), rA	5	0	rA	rB						
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmovq D(rB), rA	5	0	rA	rB	mrmovq -12(%rbp), %rcx					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Move Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

The instruction length limits the immediate value and displacement.

Move Instruction Examples

Y86-64

```
irmovq $0xabcd, %rdx
```

Encoding: 30 82 cd ab 00 00 00 00 00 00

```
rrmovq %rsp, %rbx
```

Encoding: 20 43

```
mrmovq -12(%rbp), %rcx
```

Encoding: 50 15 f4 ff ff ff ff ff ff ff

```
rmmovq %rsi, 0x41c(%rsp)
```

Encoding: 40 64 1c 04 00 00 00 00 00 00

Jump/Call Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
rrmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

Jump/Call Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
rmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

jle .L4

Jump/Call Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn								
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

The assembly would assume a start address of the program, and then calculates the address of each instruction.

jle .L4

Jump/Call Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn	Dest (essentially the target address)							
call Dest	8	0								
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

The assembly would assume a start address of the program, and then calculates the address of each instruction.

Jump/Call Instructions

Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn	Dest (essentially the target address)							
call Dest	8	0			call foo					
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

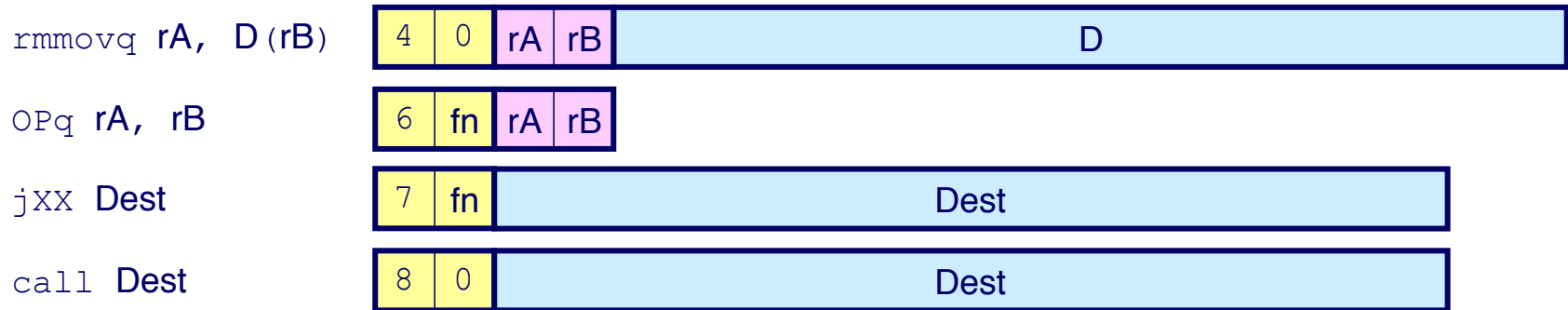
The assembly would assume a start address of the program, and then calculates the address of each instruction.

Jump/Call Instructions

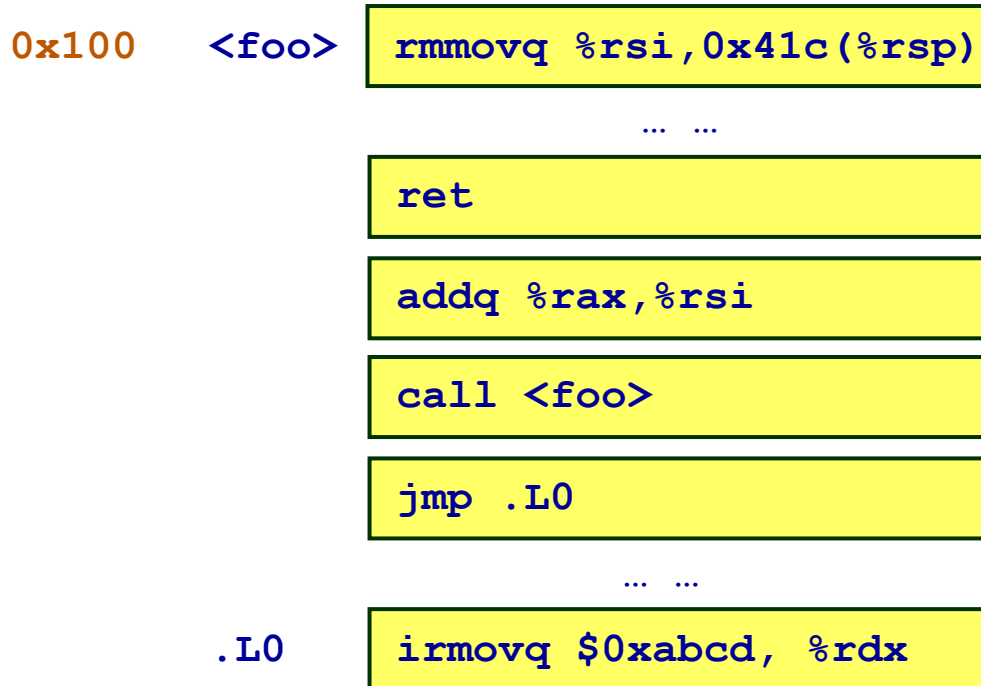
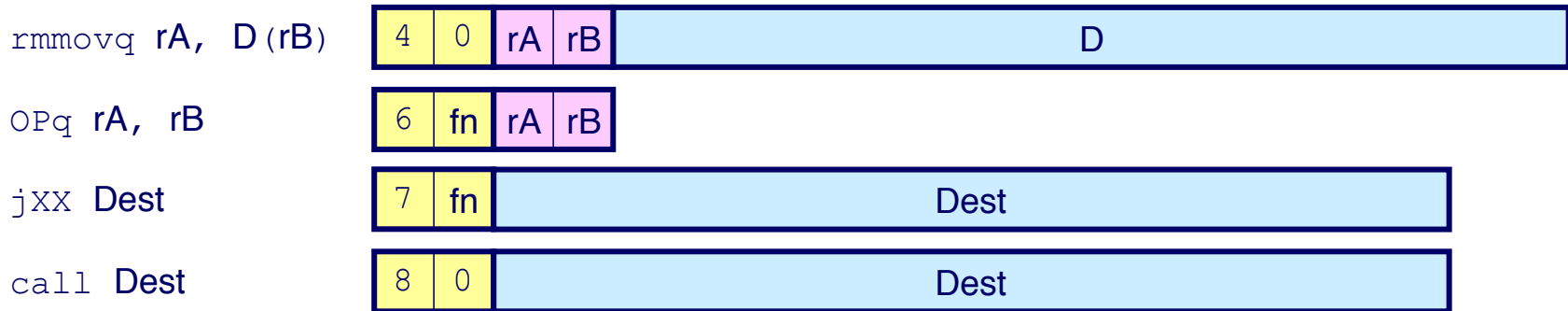
Byte	0	1	2	3	4	5	6	7	8	9
halt	0	0								
nop	1	0								
cmovXX rA, rB	2	fn	rA	rB						
irmovq V, rB	3	0	F	rB	V					
rmmovq rA, D(rB)	4	0	rA	rB	D					
mrmmovq D(rB), rA	5	0	rA	rB	D					
OPq rA, rB	6	fn	rA	rB						
jXX Dest	7	fn	Dest (essentially the target address)							
call Dest	8	0	Dest (essentially the start address of the callee)							
ret	9	0								
pushq rA	A	0	rA	F						
popq rA	B	0	rA	F						

The assembly would assume a start address of the program, and then calculates the address of each instruction.

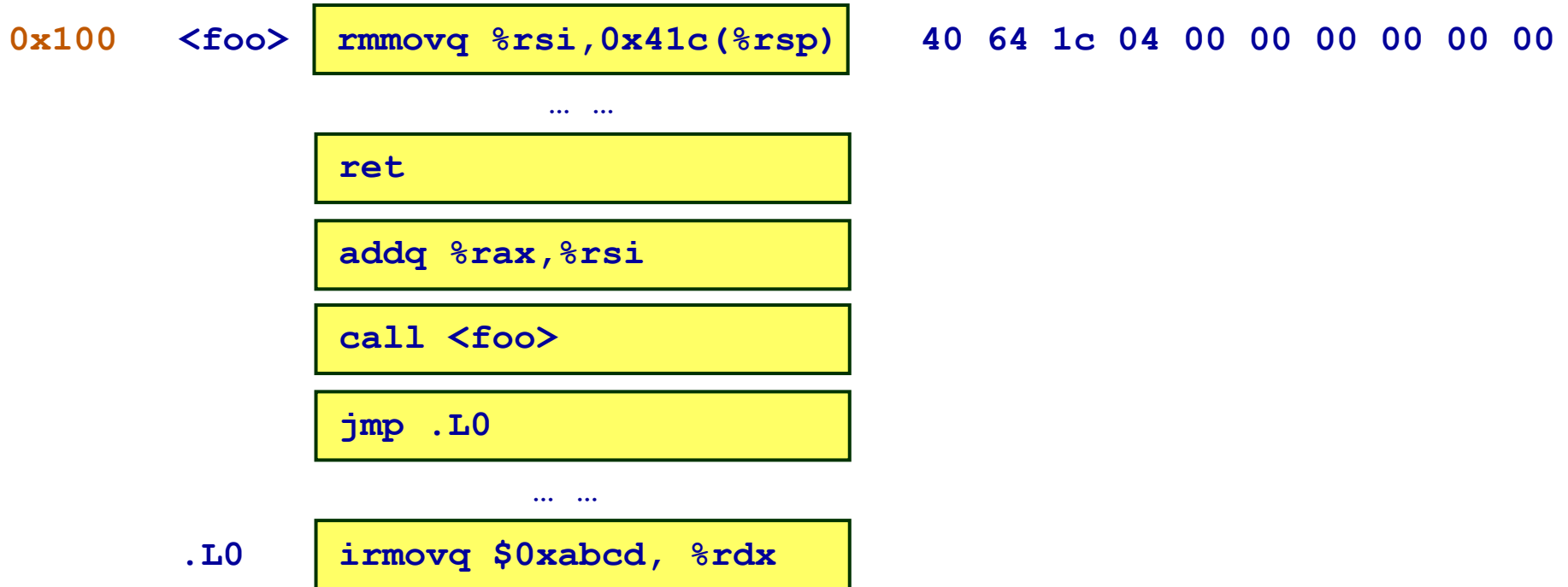
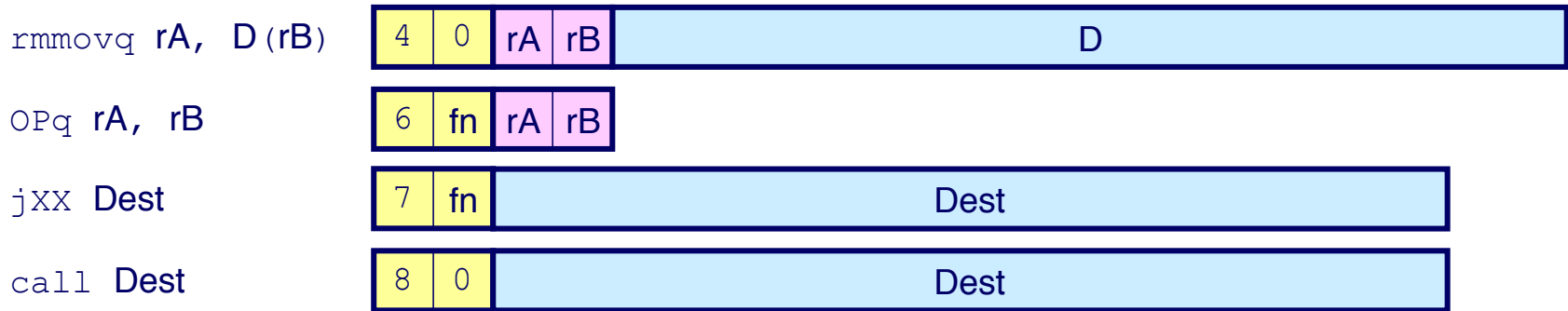
How Does An Assembler Work?



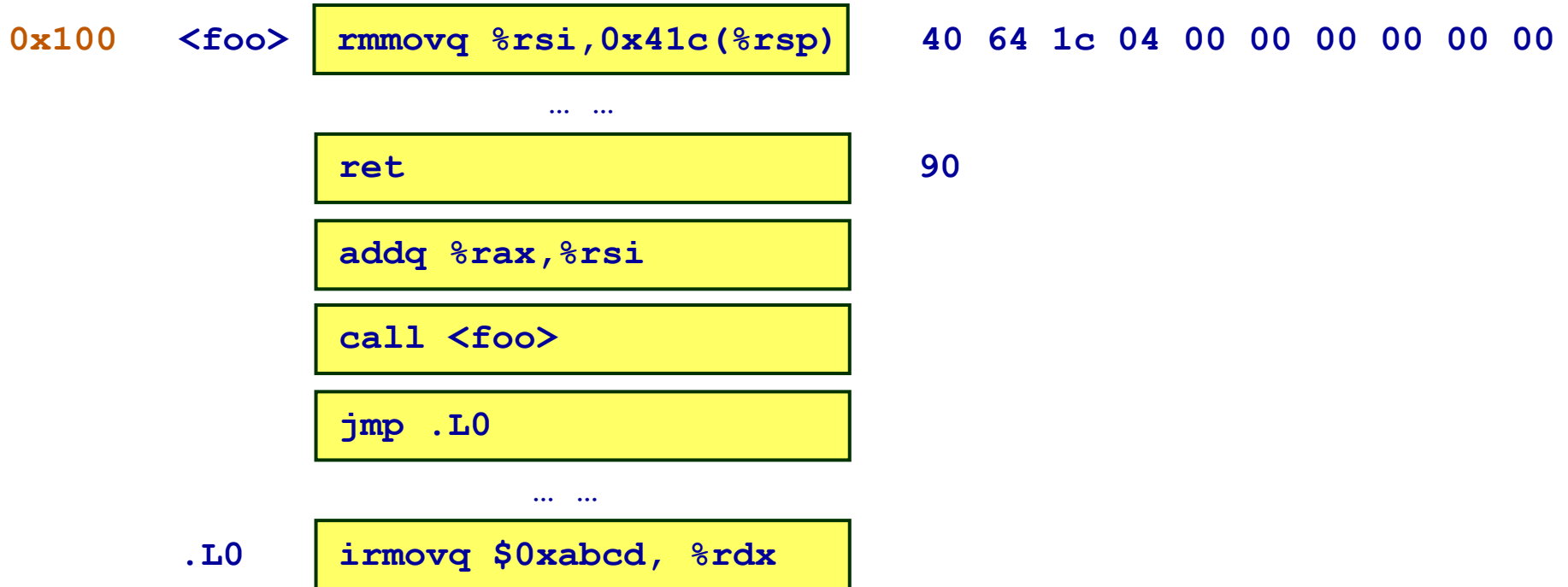
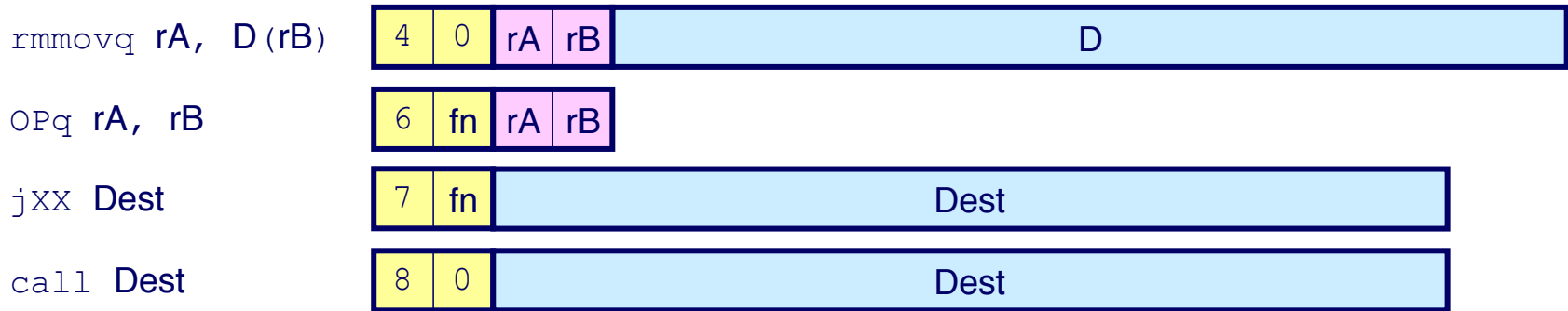
How Does An Assembler Work?



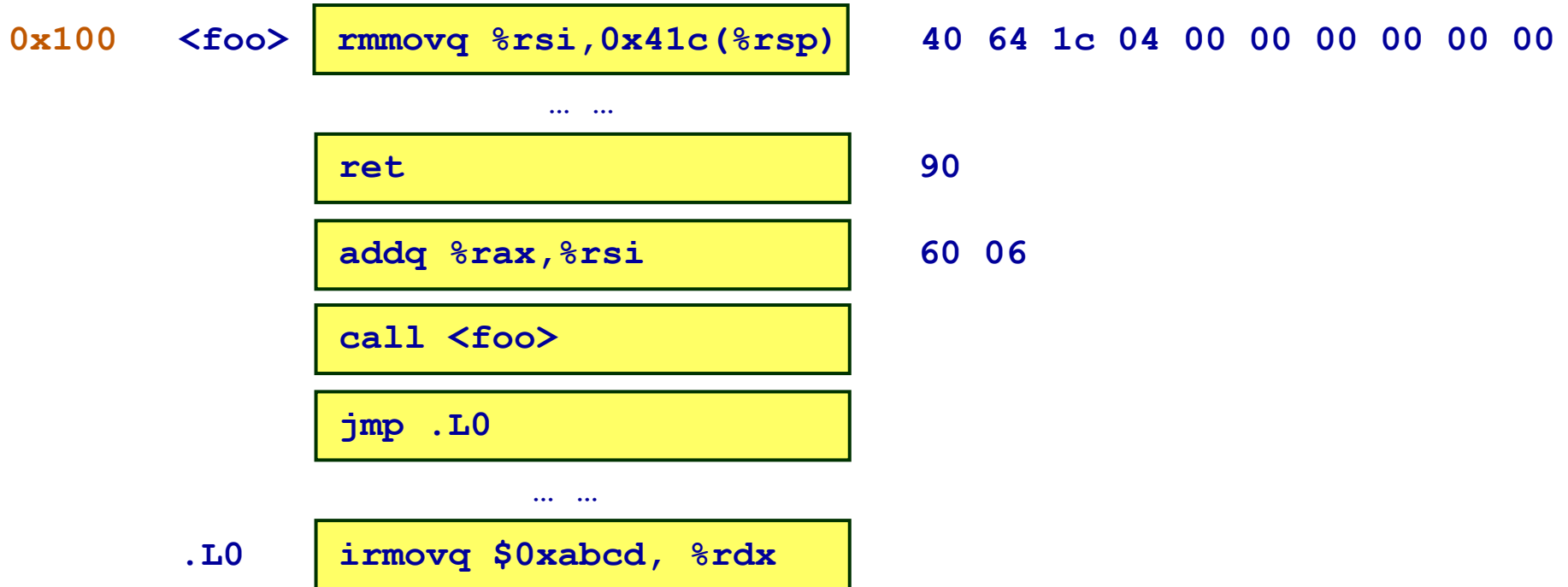
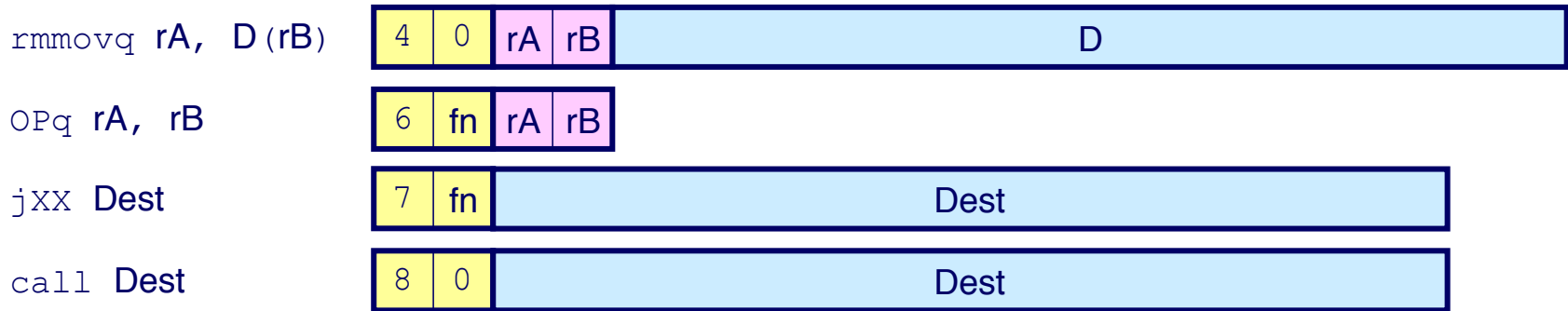
How Does An Assembler Work?



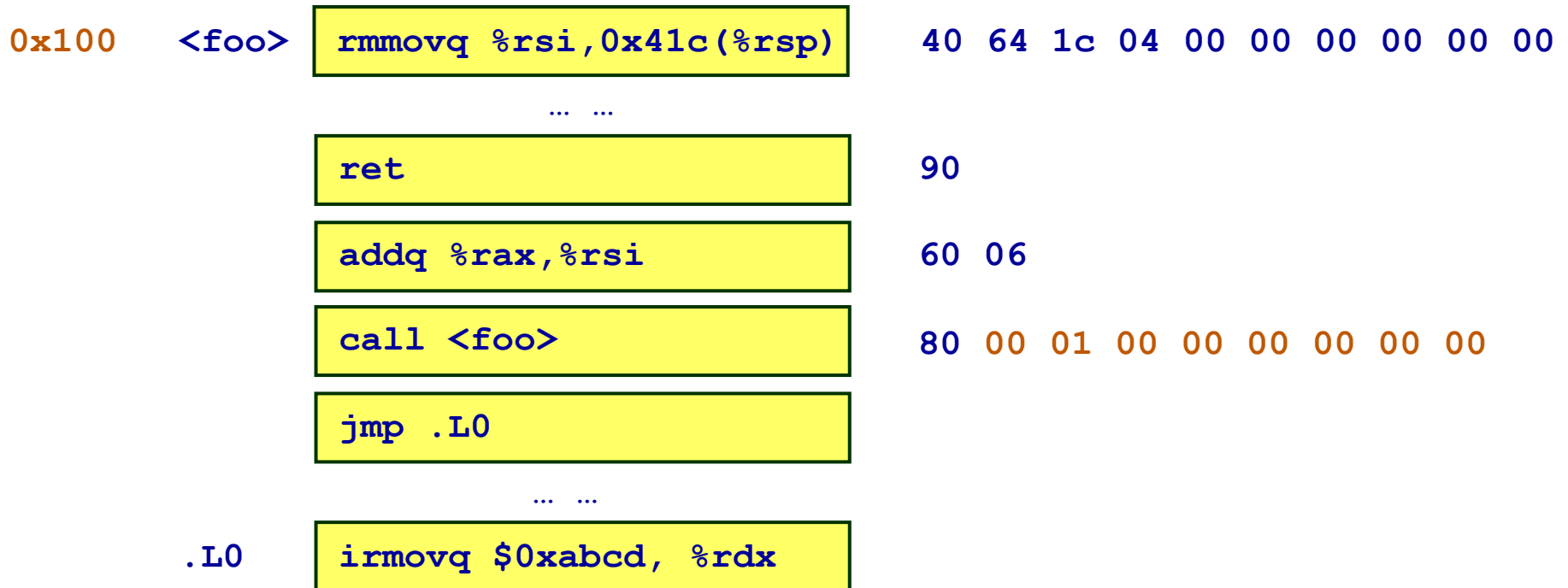
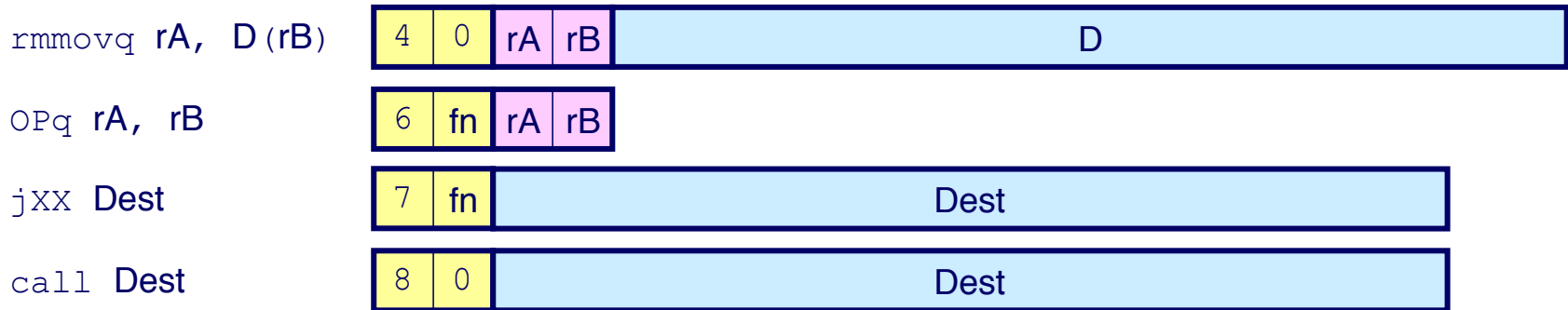
How Does An Assembler Work?



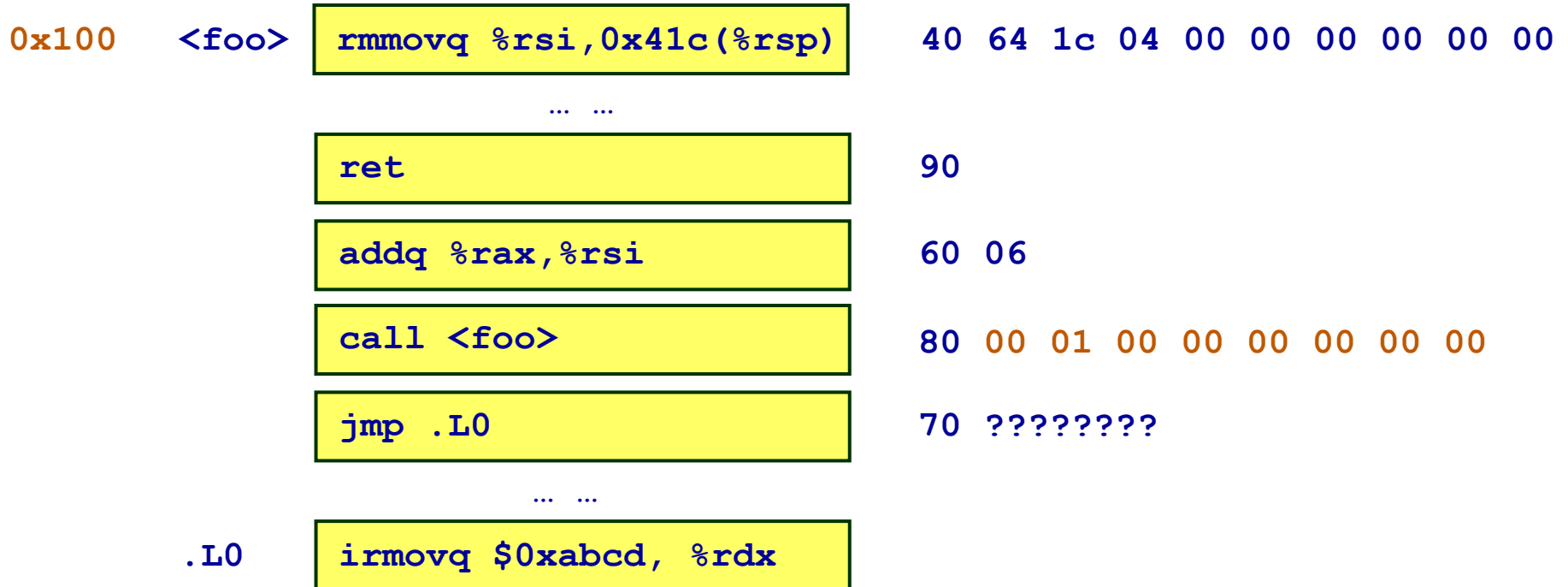
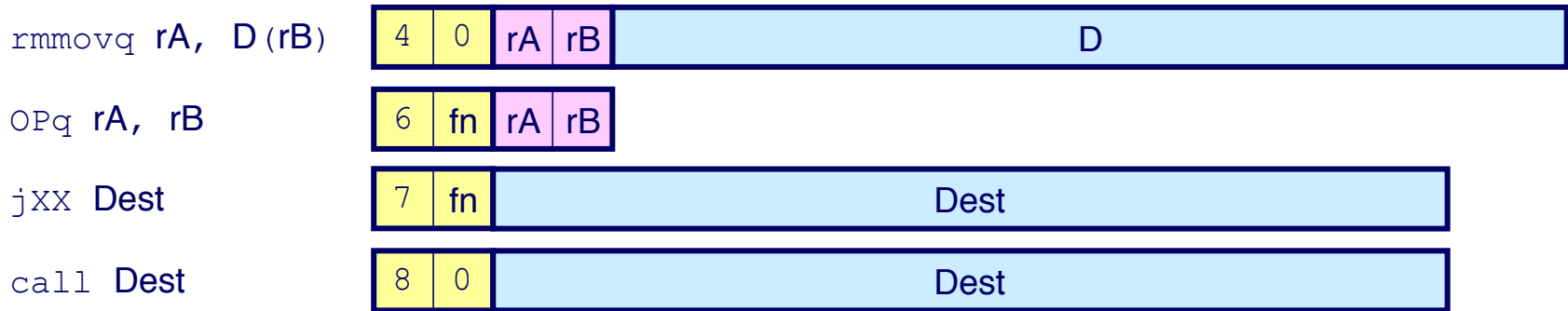
How Does An Assembler Work?



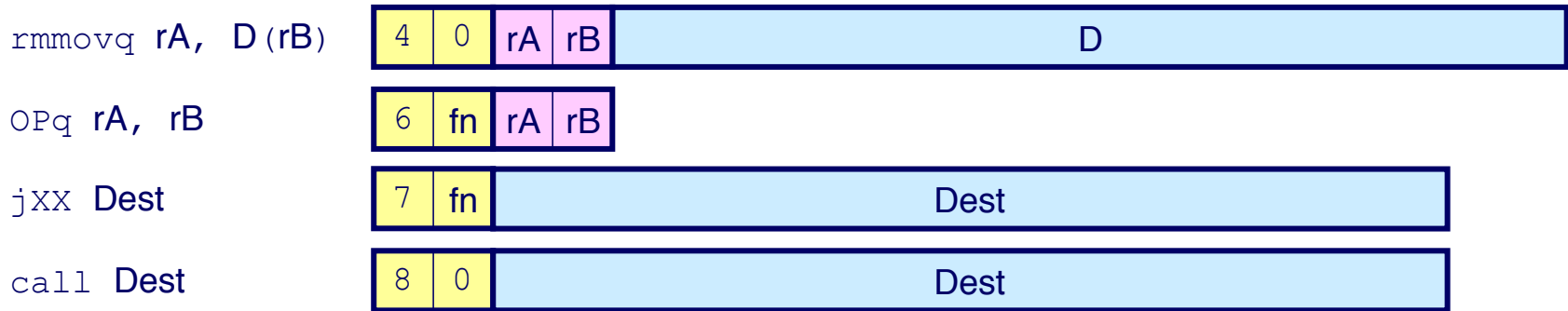
How Does An Assembler Work?



How Does An Assembler Work?

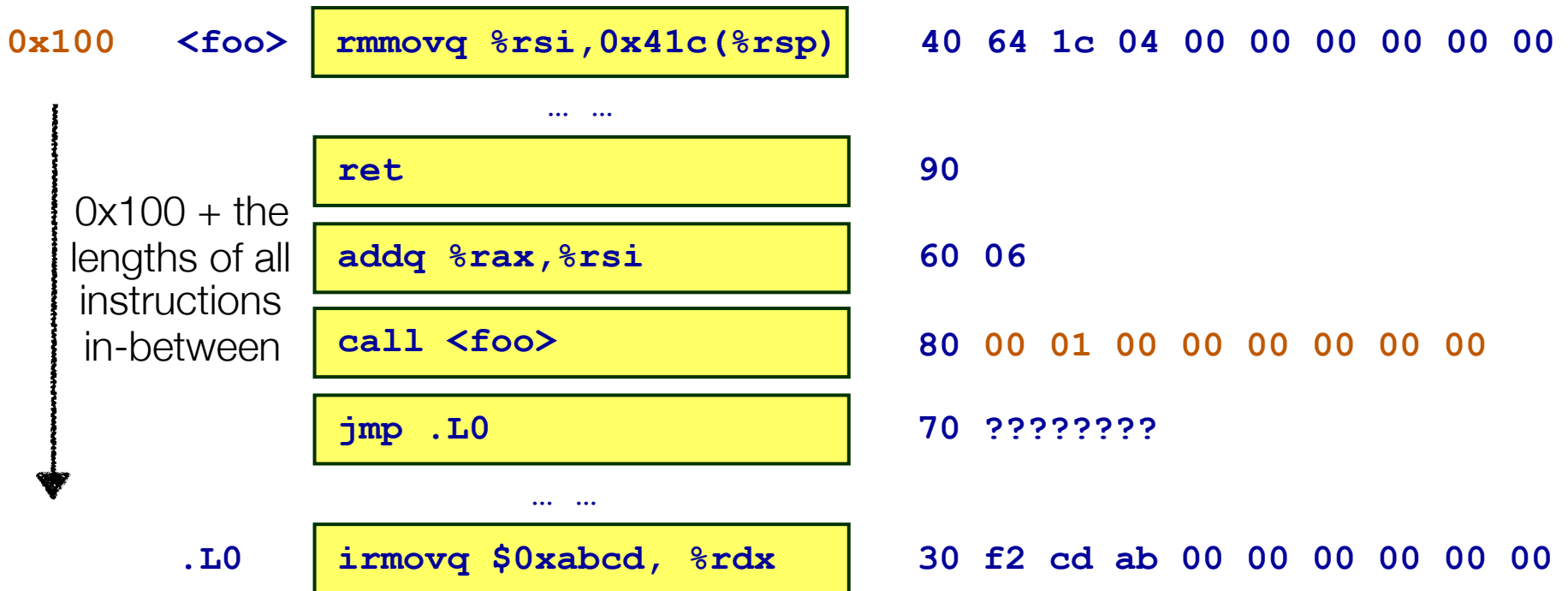
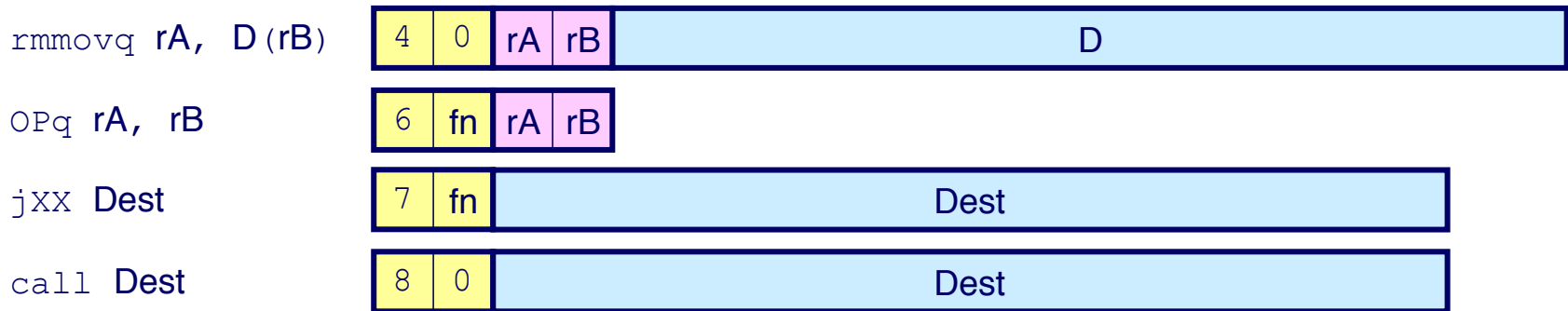


How Does An Assembler Work?

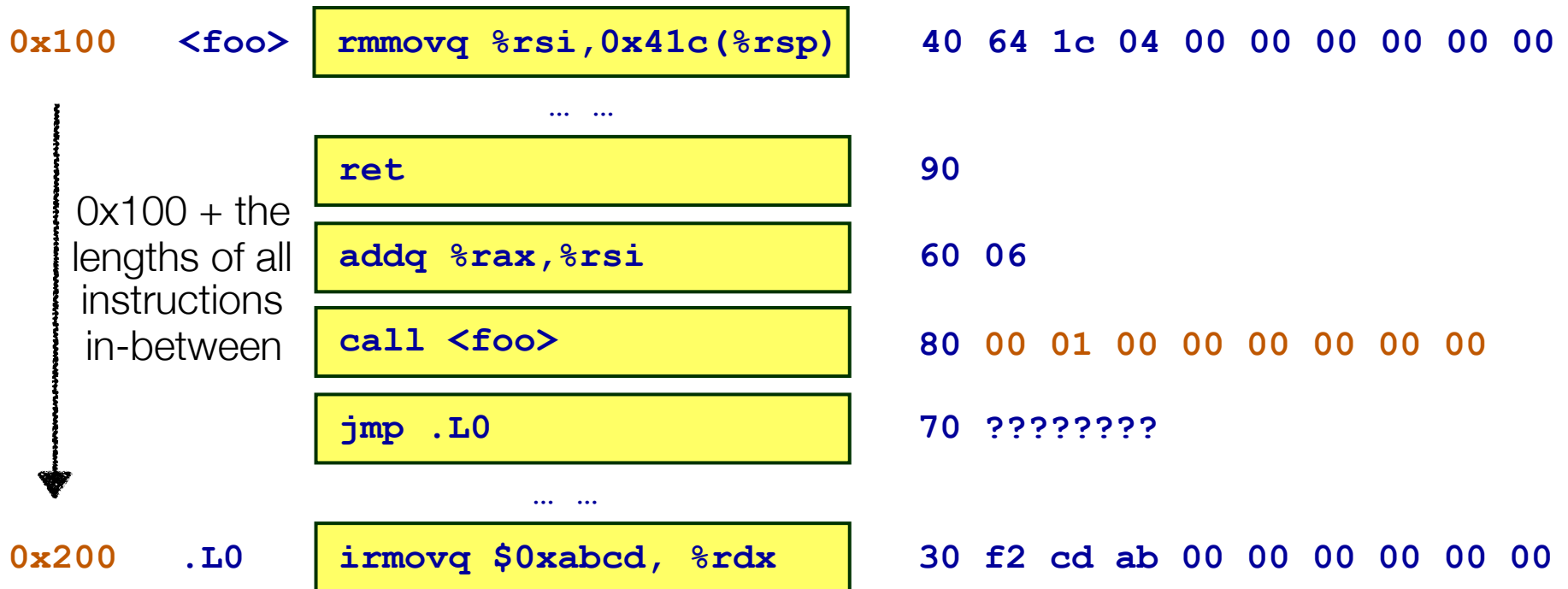
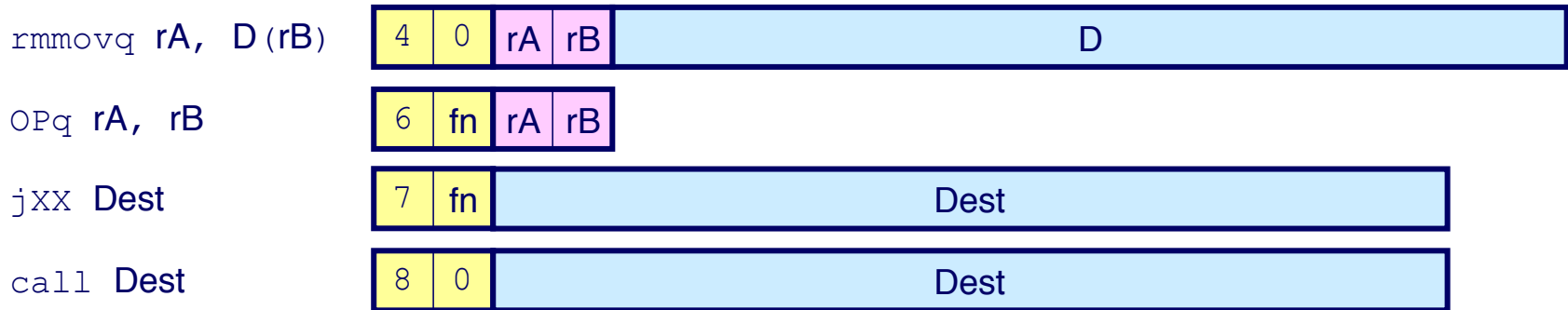


0x100	<foo>	rmmovq %rsi,0x41c(%rsp)	40	64	1c	04	00	00	00	00	00	00
		...										
		ret	90									
		addq %rax,%rsi	60	06								
		call <foo>	80	00	01	00	00	00	00	00	00	00
		jmp .L0	70	????????								
		...										
.L0		irmovq \$0xabcd, %rdx	30	f2	cd	ab	00	00	00	00	00	00

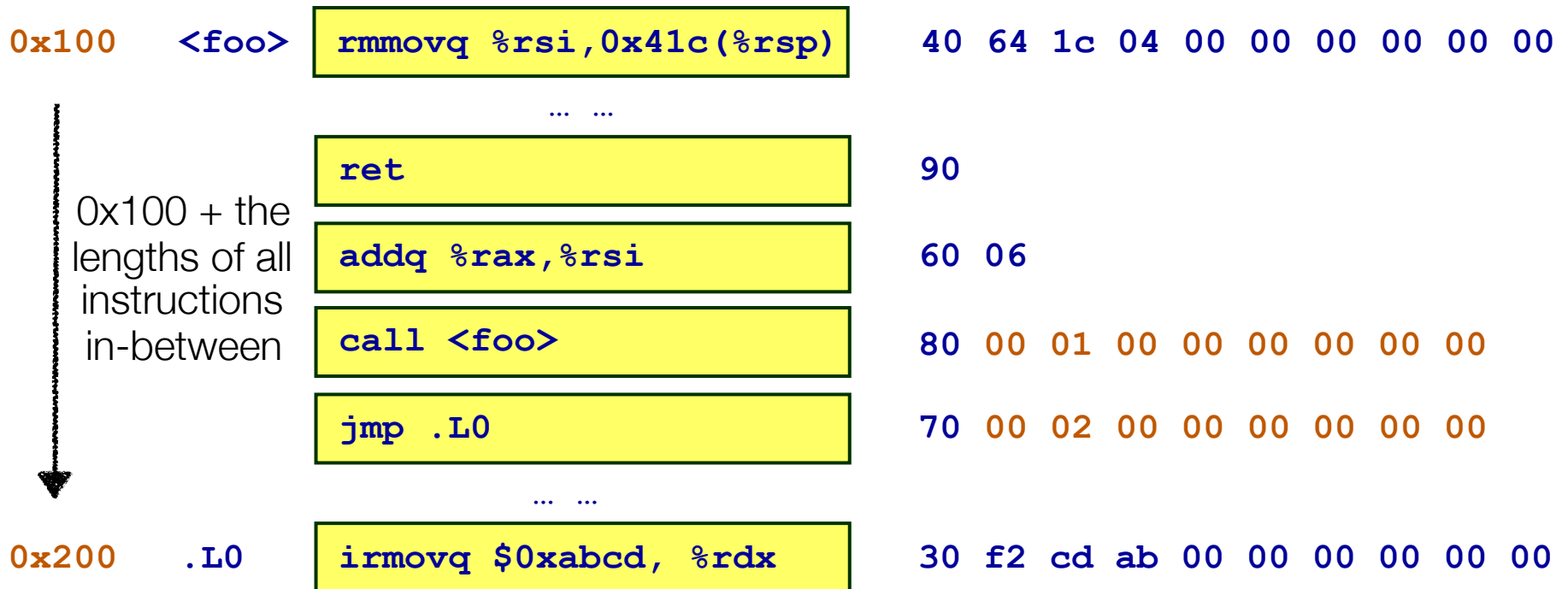
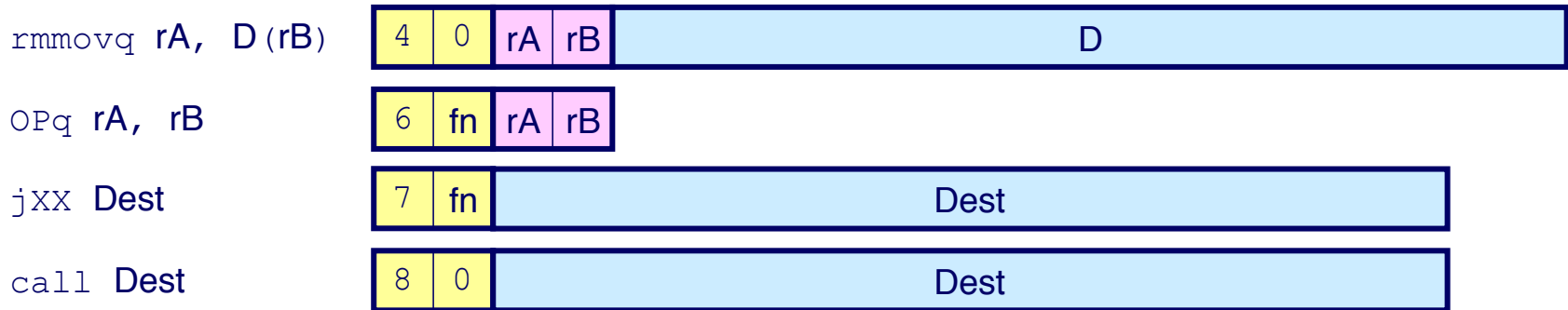
How Does An Assembler Work?



How Does An Assembler Work?

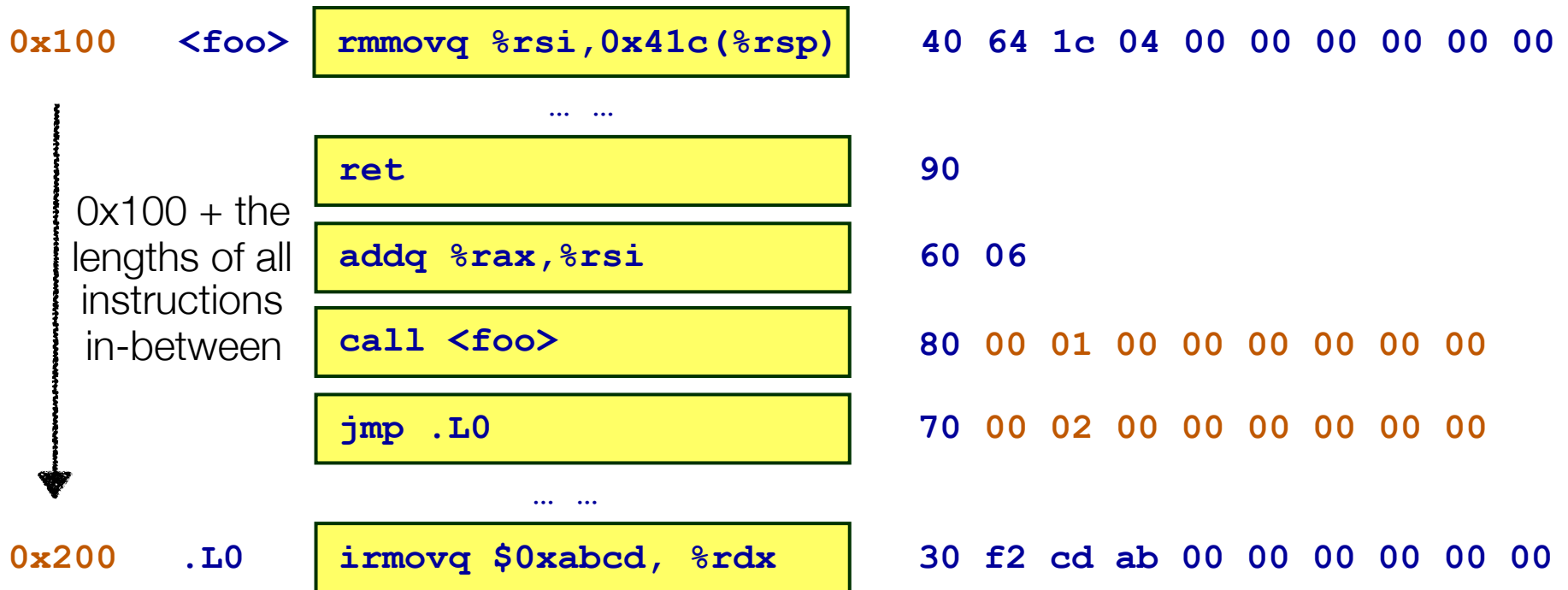


How Does An Assembler Work?



How Does An Assembler Work?

- The assembler is a program that translates assembly code to binary code
- The OS tells the assembler the start address of the code (sort of...)
- Translate the assembly program line by line
- Need to build a “label map” that maps each label to its address



Jump Instructions

Jump Unconditionally

jmp Dest 7 0 Dest

Jump When Less or Equal

jle Dest 7 1 Dest

Jump When Less

jl Dest 7 2 Dest

Jump When Equal

je Dest 7 3 Dest

Jump When Not Equal

jne Dest 7 4 Dest

Jump When Greater or Equal

jge Dest 7 5 Dest

Jump When Greater

jg Dest 7 6 Dest

Subroutine Call and Return

call Dest

8

0

Dest

- Push address of next instruction onto stack
- Start executing instructions at Dest
- Like x86-64

ret

9

0

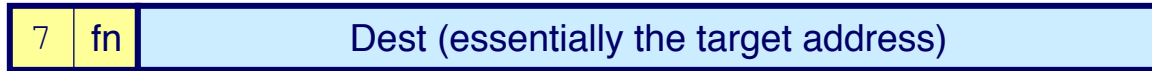
- Pop value from stack
- Use as address for next instruction
- Like x86-64

One More Complication...

Byte

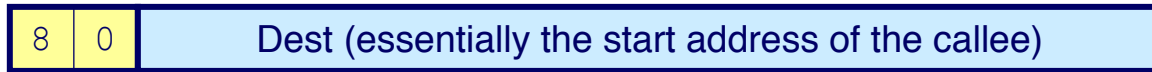
0 1 2 3 4 5 6 7 8 9

`jXX Dest`



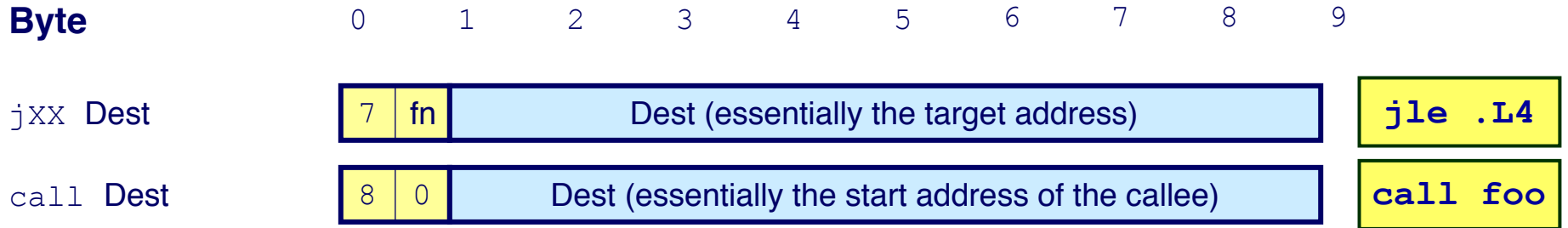
`jle .L4`

`call Dest`



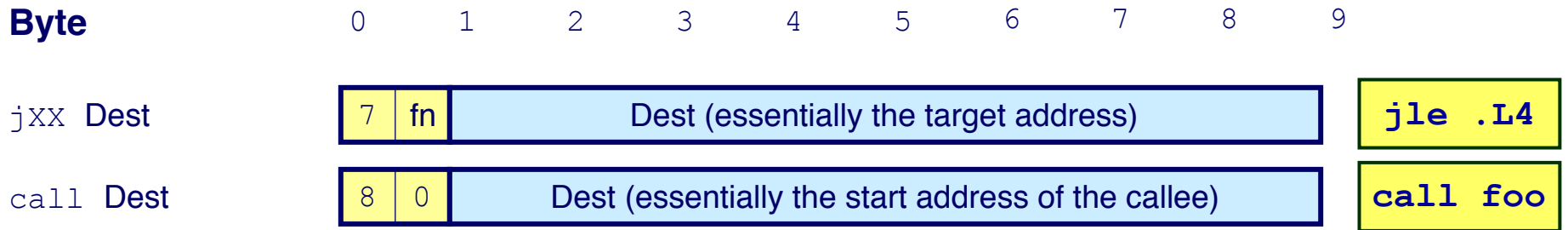
`call foo`

One More Complication...



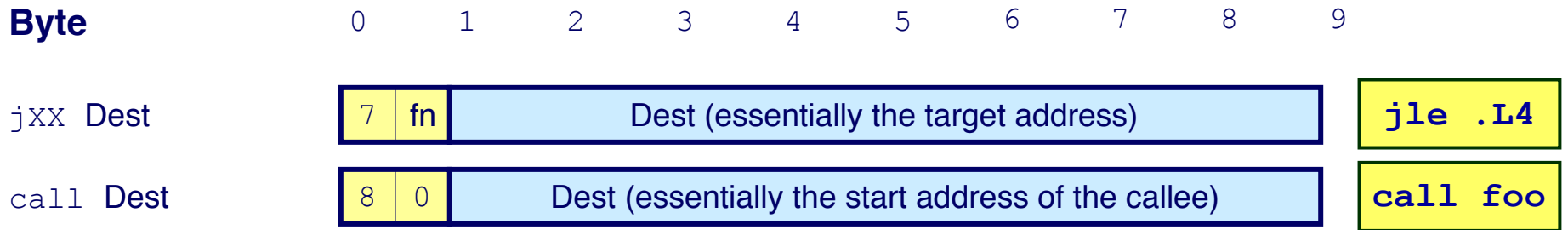
- The instruction length limits how far you can jump/call functions. What if the jump target has a very long address that can't fit in 8 bytes?
 - Or if we can use only say 4 bytes for the target address?

One More Complication...



- The instruction length limits how far you can jump/call functions. What if the jump target has a very long address that can't fit in 8 bytes?
 - Or if we can use only say 4 bytes for the target address?
- One alternative: use a super long instruction encoding format.
 - Simple to encode, but space inefficient (waste bits for jumps to short addr.)

One More Complication...



- The instruction length limits how far you can jump/call functions. What if the jump target has a very long address that can't fit in 8 bytes?
 - Or if we can use only say 4 bytes for the target address?
- One alternative: use a super long instruction encoding format.
 - Simple to encode, but space inefficient (waste bits for jumps to short addr.)
- Another alternative: encode the relative address, not the absolute address
 - E.g., encode (.L4 - current address) in Dest

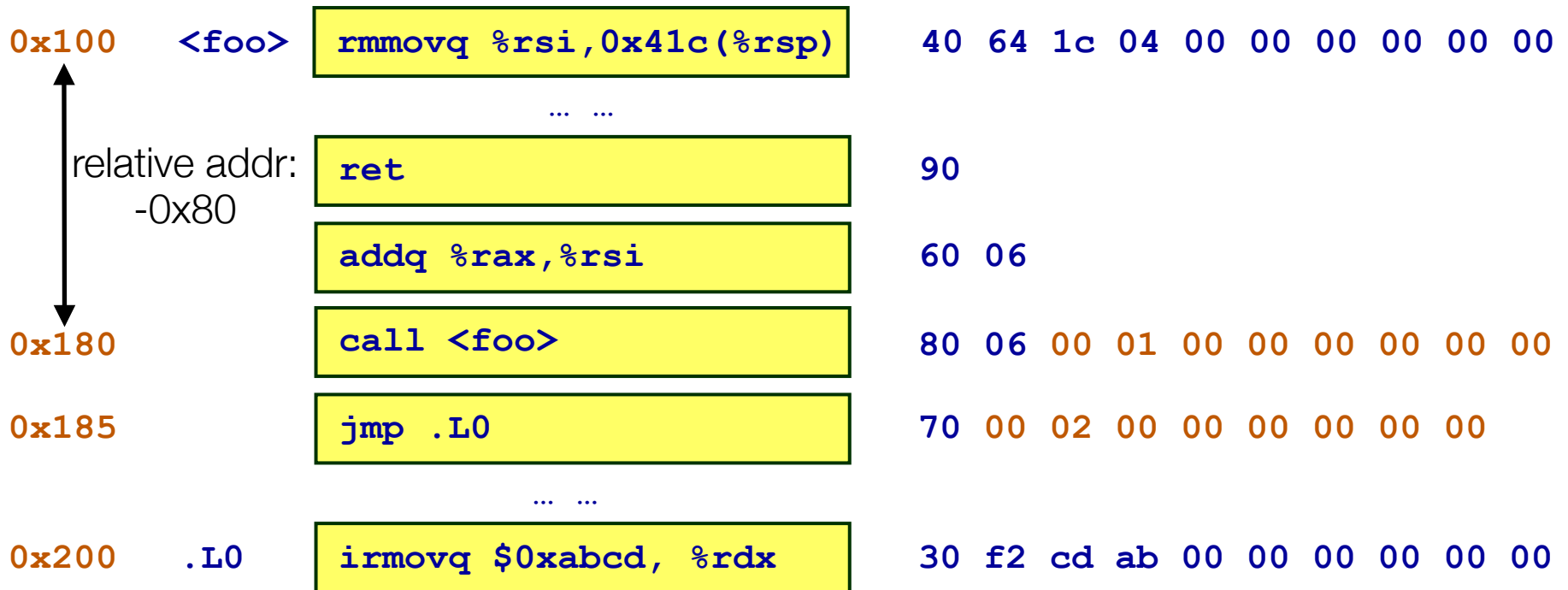
Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?

0x100	<foo>	rmmovq %rsi,0x41c(%rsp)	40 64 1c 04 00 00 00 00 00 00 00
... ..			
		ret	90
		addq %rax,%rsi	60 06
0x180		call <foo>	80 06 00 01 00 00 00 00 00 00 00
0x185		jmp .L0	70 00 02 00 00 00 00 00 00 00 00
... ..			
0x200	.L0	irmovq \$0xabcd, %rdx	30 f2 cd ab 00 00 00 00 00 00 00

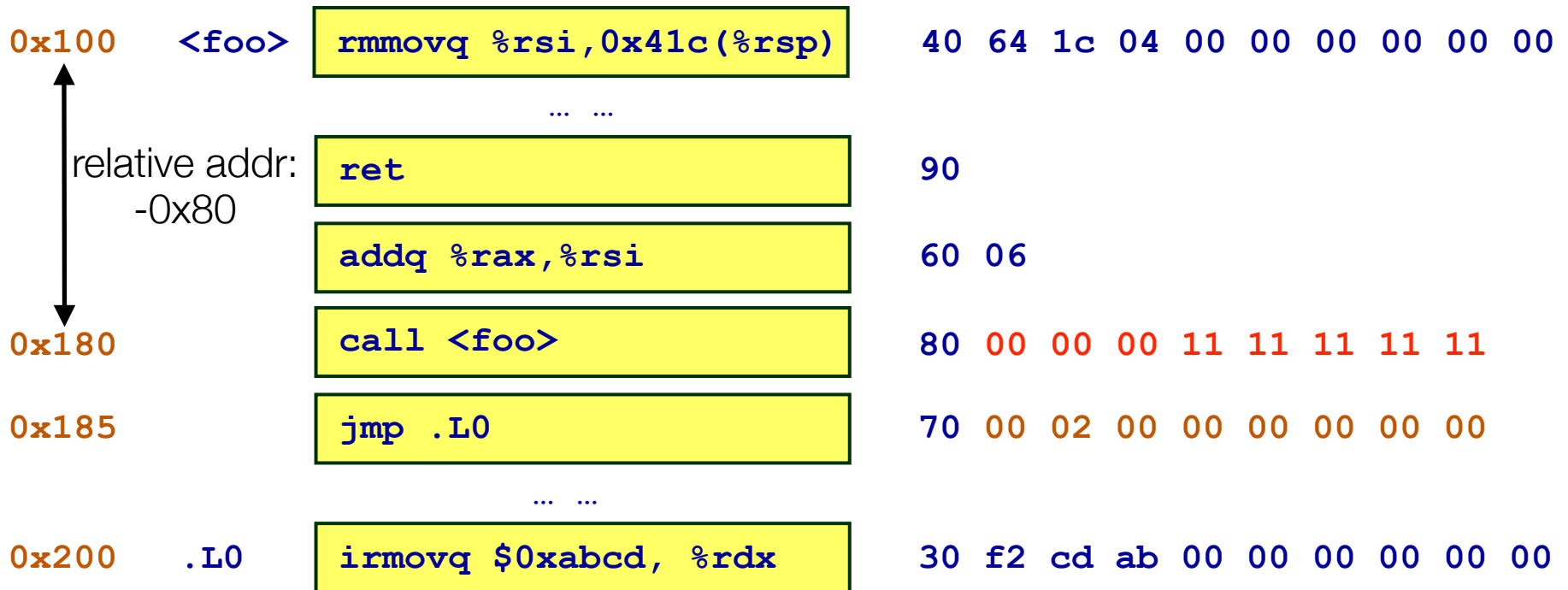
Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?



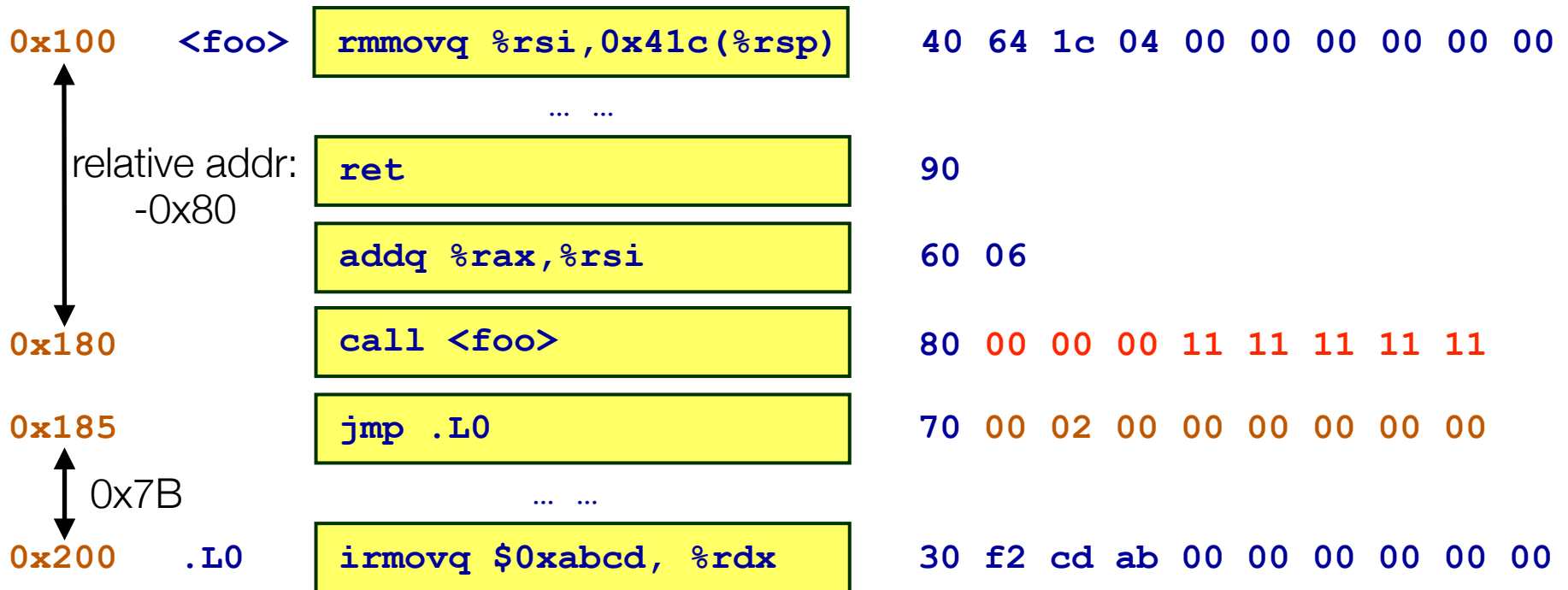
Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?



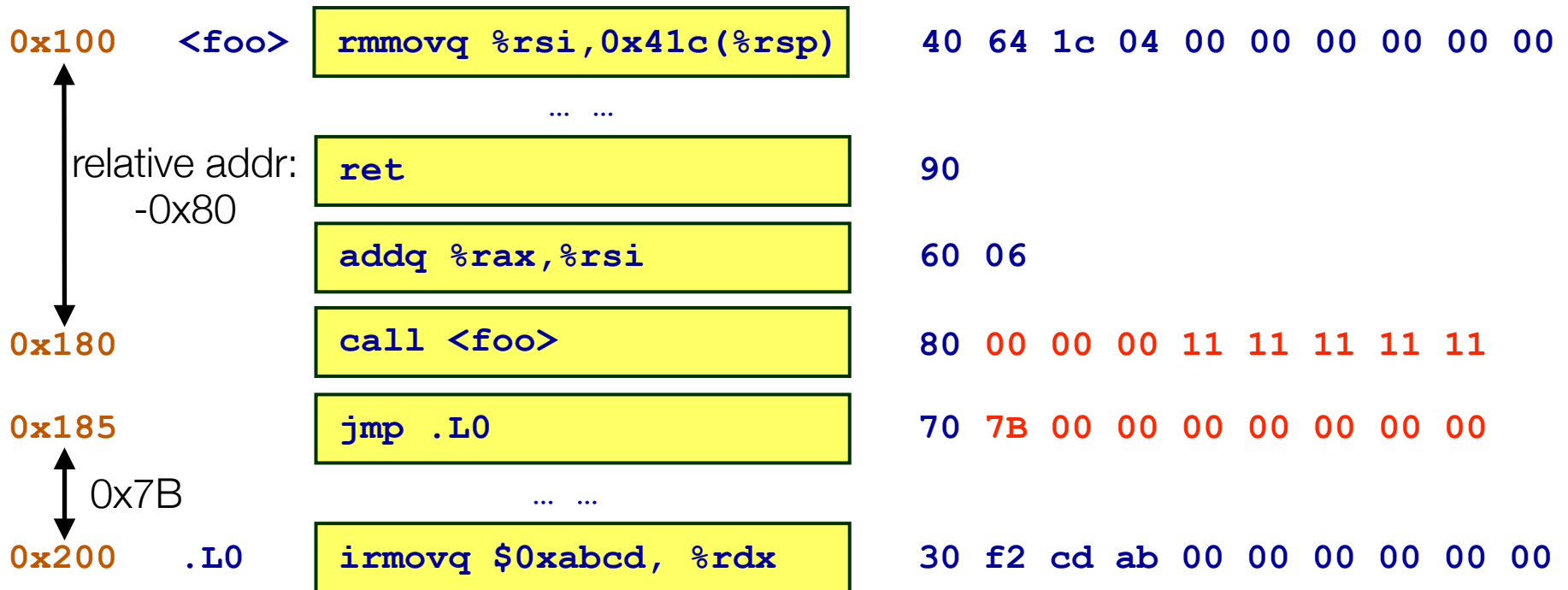
Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?



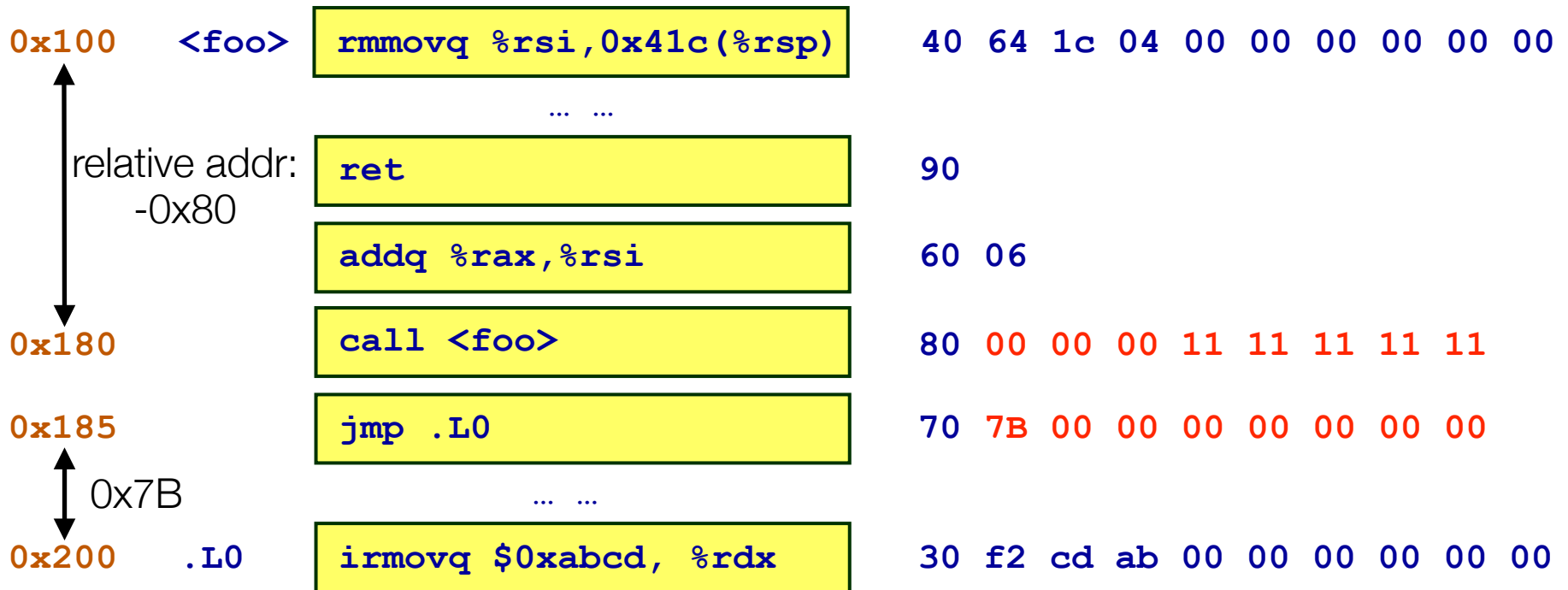
Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?



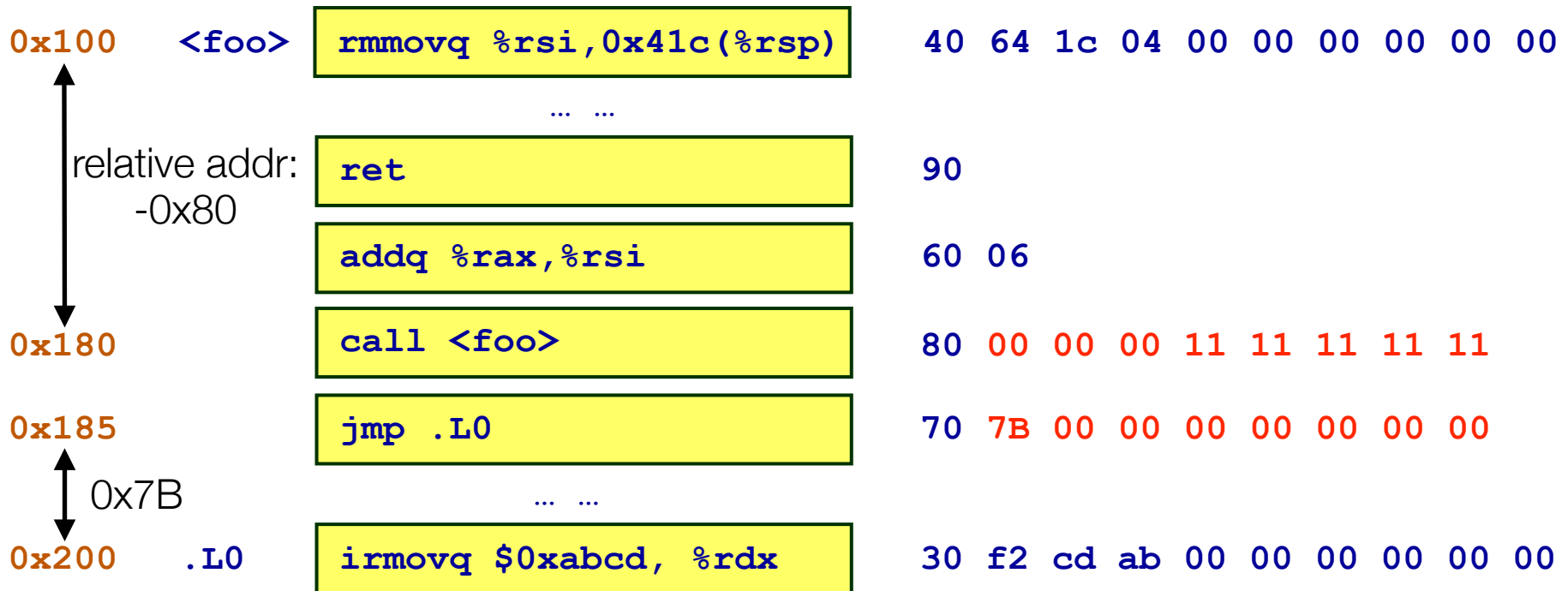
Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?
- If we use relative address, the exact start address of the code doesn't matter. Why?



Using Relative Addresses for Jumps

- What if the ISA encoding uses relative address for jump and call?
- If we use relative address, the exact start address of the code doesn't matter. Why?
- This code is called Position-Independent Code (PIC)



Miscellaneous Instructions



- Don't do anything



- Stop executing instructions
- Usually can't be executed in the user mode, only by the OS
- Encoding ensures that program hitting memory initialized to zero will halt

Variable Length Instructions

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).
- Advantages of variable length ISAs

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).
- Advantages of variable length ISAs
 - More compact. Some instructions do not need that many bits. (Actually what's the optimal way of encoding instructions in a variable length ISA?)

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).
- **Advantages of variable length ISAs**
 - More compact. Some instructions do not need that many bits. (Actually what's the optimal way of encoding instructions in a variable length ISA?)
 - Can have arbitrary number of instructions: easy to add new inst.

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).
- **Advantages of variable length ISAs**
 - More compact. Some instructions do not need that many bits. (Actually what's the optimal way of encoding instructions in a variable length ISA?)
 - Can have arbitrary number of instructions: easy to add new inst.
- **What is the down side?**

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).
- **Advantages of variable length ISAs**
 - More compact. Some instructions do not need that many bits. (Actually what's the optimal way of encoding instructions in a variable length ISA?)
 - Can have arbitrary number of instructions: easy to add new inst.
- **What is the down side?**
 - Fetch and decode are harder to implement. More on this later.

Variable Length Instructions

- X86 (and Y86) is a variable length ISA (1 to 15 bytes), where different instructions have different lengths.
- There are fixed length ISAs: all instructions have the same length
 - ARM's ISA for micro-controllers have a 4-bit ISA. Very Long Instruction Word (VLIW) ISAs have instructions that are hundreds of bytes long.
 - Or you can have a combination of both: e.g., 16-bit ISA with 32-bit extensions (e.g, ARM Thumb-extension).
- Advantages of variable length ISAs
 - More compact. Some instructions do not need that many bits. (Actually what's the optimal way of encoding instructions in a variable length ISA?)
 - Can have arbitrary number of instructions: easy to add new inst.
- What is the down side?
 - Fetch and decode are harder to implement. More on this later.
- A good writeup showing some of the complexity involved:
<http://www.c-jump.com/CIS77/CPU/x86/lecture.html>