CSC 572: Mobile Systems Architecture Fall 2018: Intro

Instructor: Yuhao Zhu

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Where to Find Stuff

- http://cs.rochester.edu/courses/572/fall2018/
 - General info
 - Various course materials
- Slack for <u>all</u> communication
 - Only place for all announcements
 - Q&A

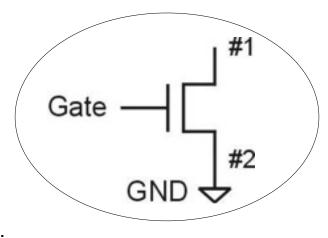
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n-type (NMOS)



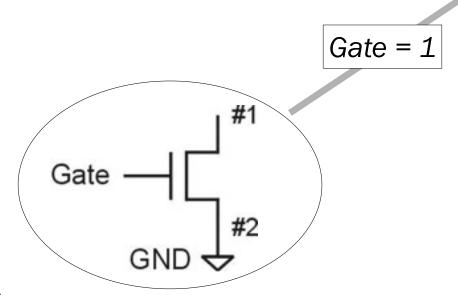
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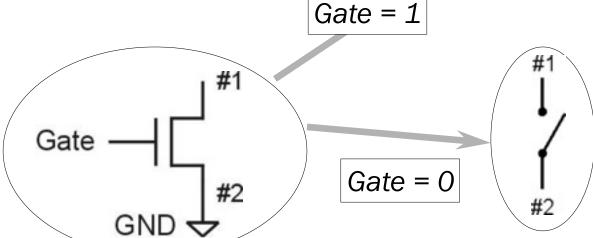
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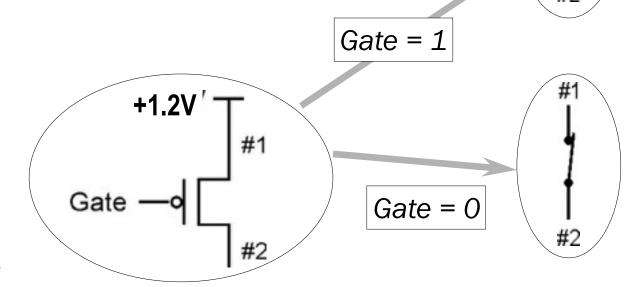
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- when Gate has <u>zero</u> voltage, open circuit between #1 and #2 (switch <u>open</u>)



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p-type is complementary to n-type (PMOS)

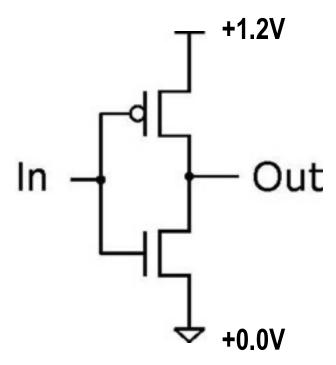
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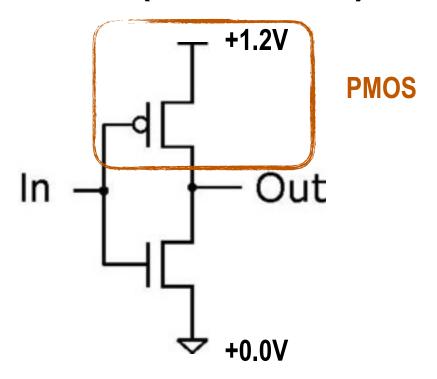


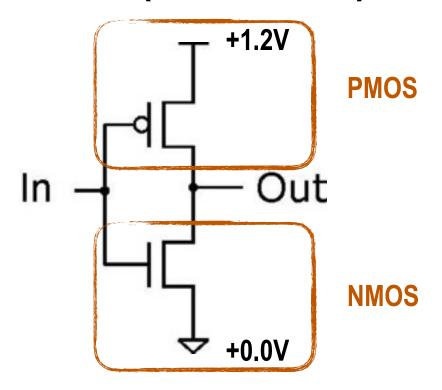
Terminal #1 must be connected to +1.2V

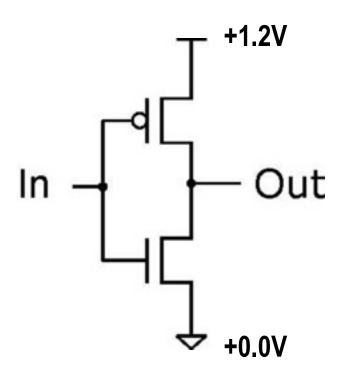
CMOS Circuit

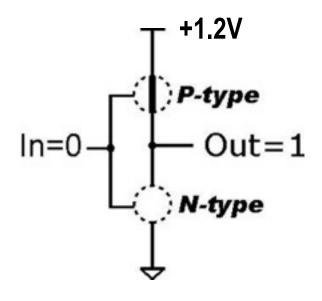
- Complementary MOS
- Uses both n-type and p-type MOS transistors
 - p-type
 - Attached to + voltage
 - Pulls output voltage UP when input is zero
 - n-type
 - Attached to GND
 - Pulls output voltage DOWN when input is one

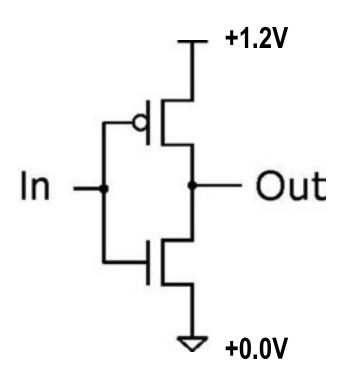


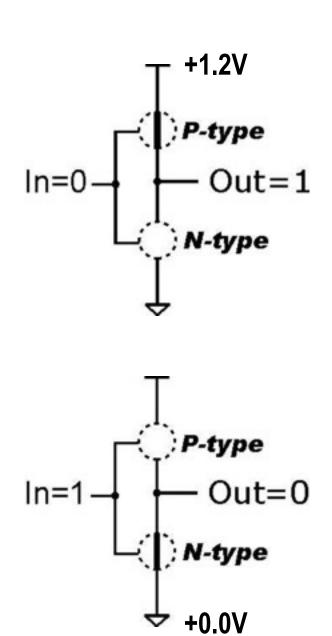


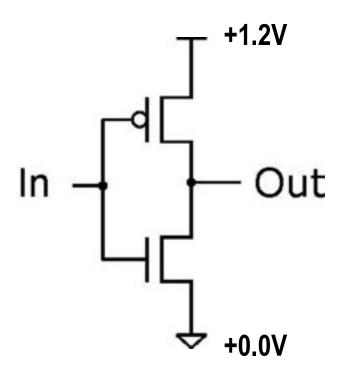


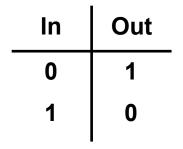


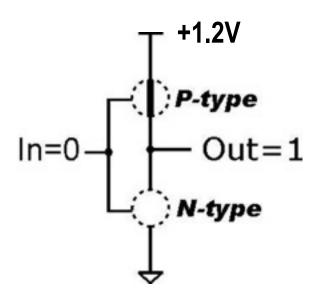


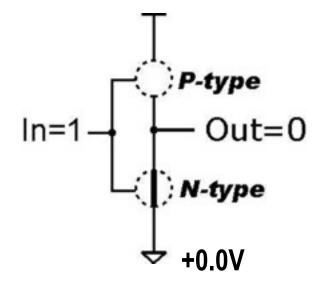


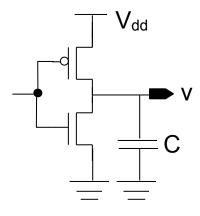


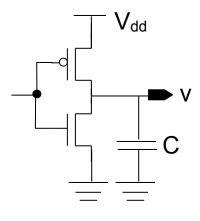


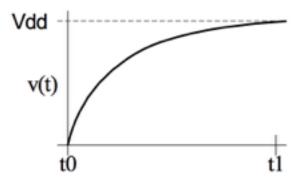


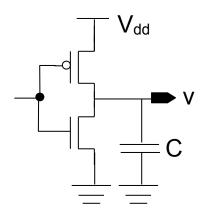


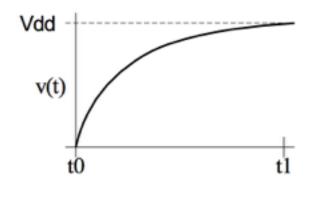






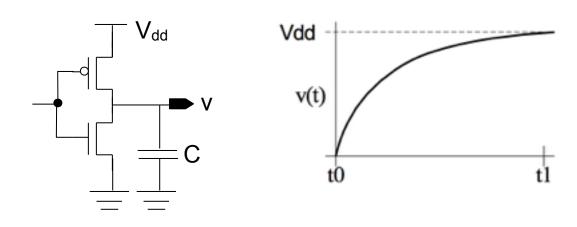






$$E_{sw} = \int_{t_0}^{t_1} P(t)dt = \int_{t_0}^{t_1} (V_{dd} - v) \cdot i(t)dt = \int_{t_0}^{t_1} (V_{dd} - v) \cdot c (dv/dt) dt =$$

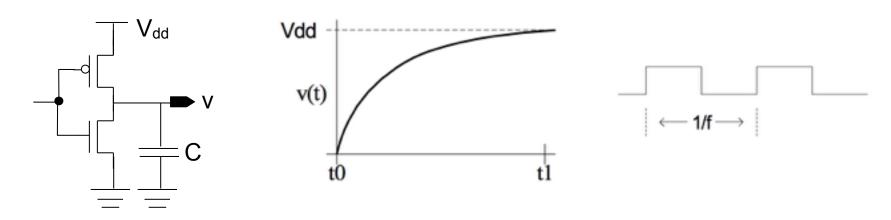
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Energy dissipated for every transition (0->1 or 1->0): $\frac{1}{2}$ C_L V_{dd}²



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Energy dissipated for every transition (0->1 or 1->0): ½ C_L V_{dd}²

$$P = a \cdot (E / T) = a \cdot E f = \frac{1}{2} a C V_{dd}^{2} f$$

a: switch activity factor. No switching, no dynamic power consumption

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 - 15% reduction in voltage requires about 15% slow down in frequency
 - What's the impact on dynamic power? $0.85^3 \approx 60\% -> 40\%$ dynamic power reduction.

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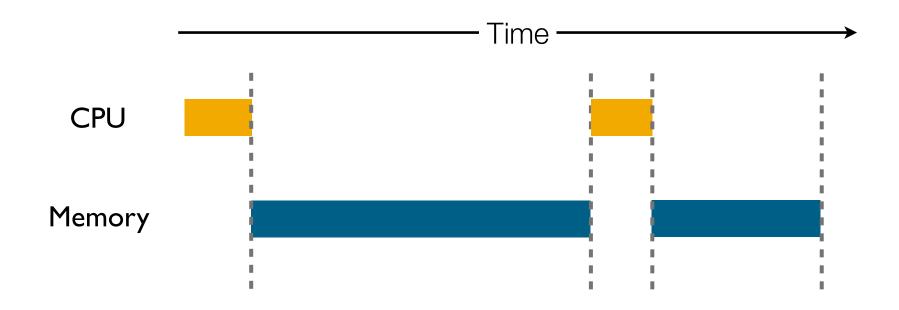
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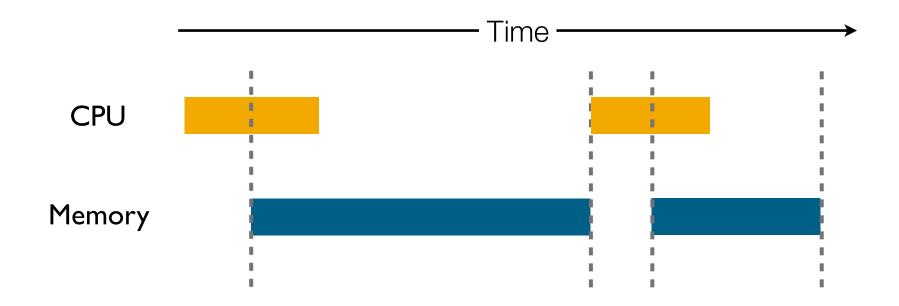
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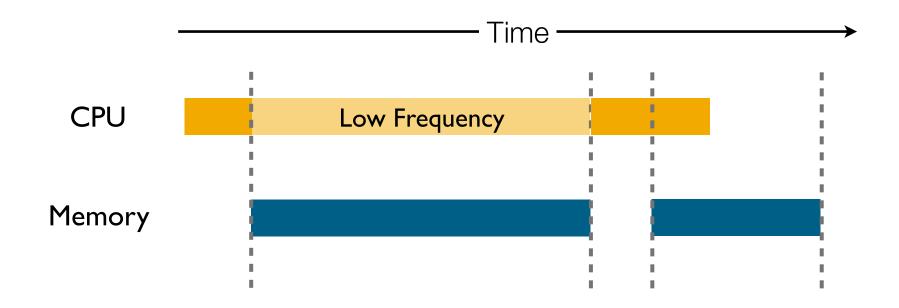
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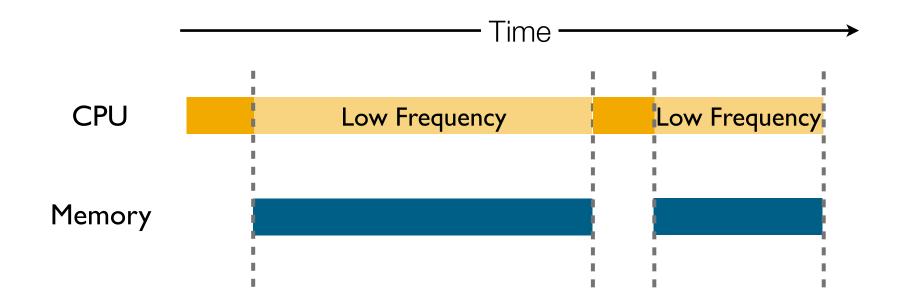
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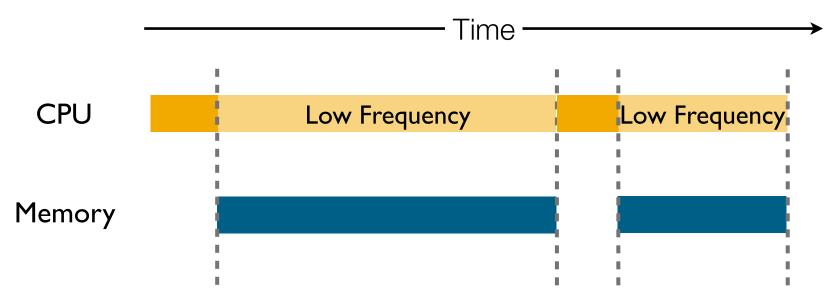
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 - Dynamic power becomes $4 \times (1/4)^3 = 1/16$





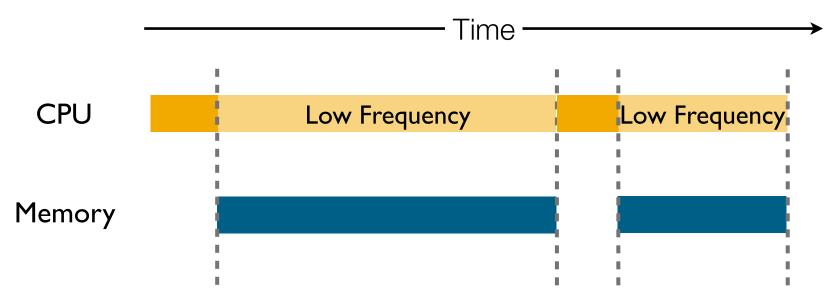






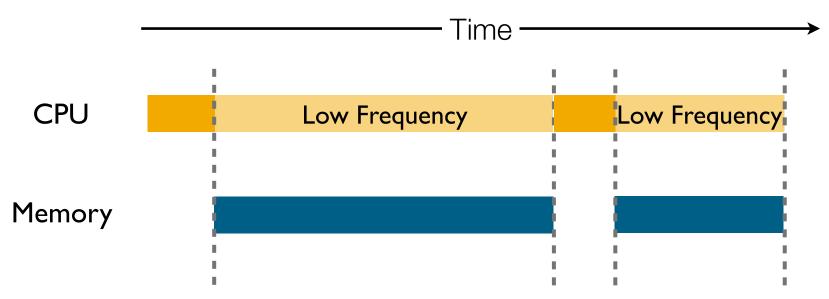
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Dynamic Voltage and Frequency Scaling



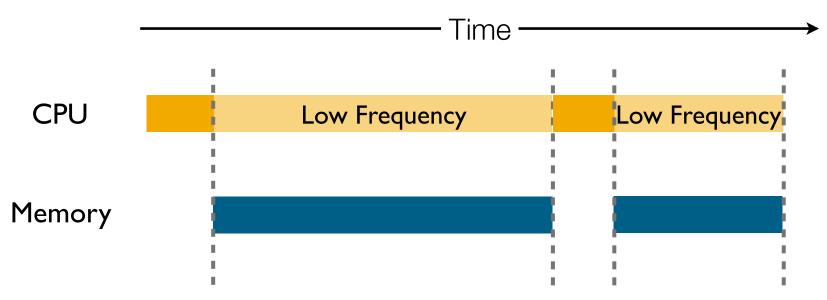
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- Mostly done in OS today as the "CPU frequency governor": based on CPU utilization, coarse-grained (e.g., ~10 ms)
- You can control it. Try it yourself.
- Hardware can do it in finer granularity, but more complex circuits

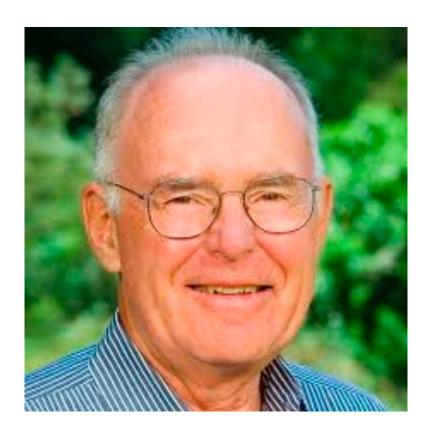


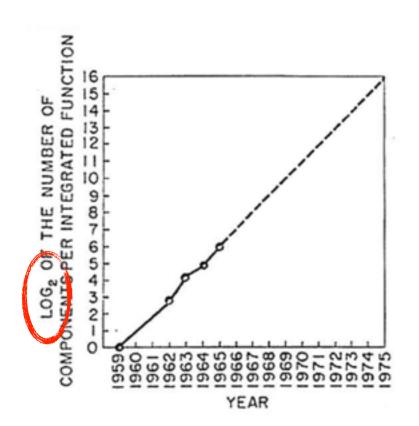
Computer Architecture Techniques for Power Efficiency

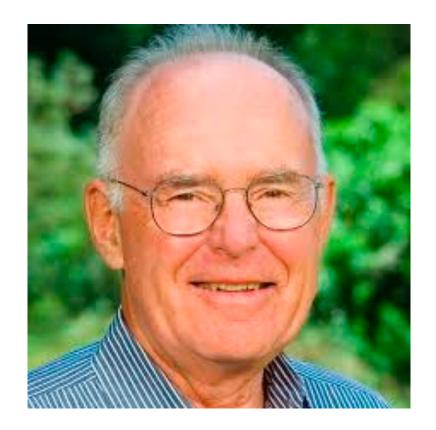
Stefanos Kaxiras Margaret Martonosi

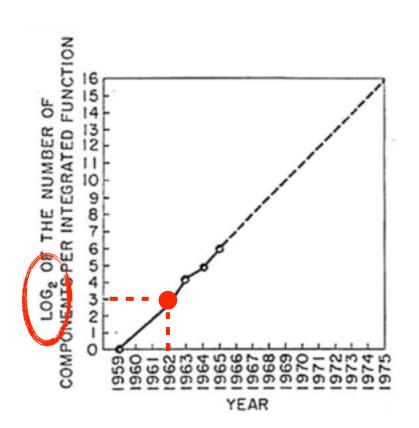
SYNTHESIS LECTURES ON COMPUTER ARCHITECTURE

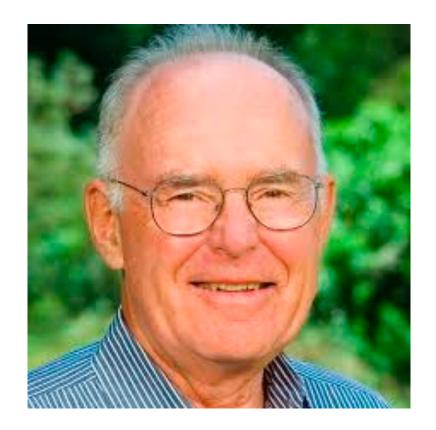
Mark D. Hill, Series Editor

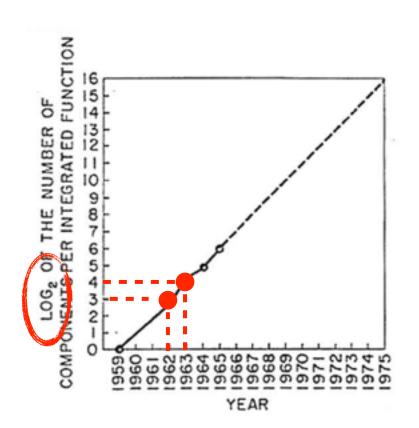


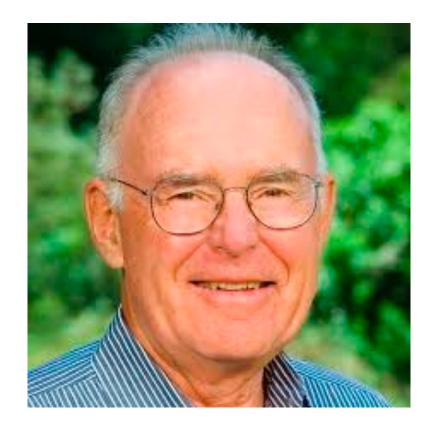




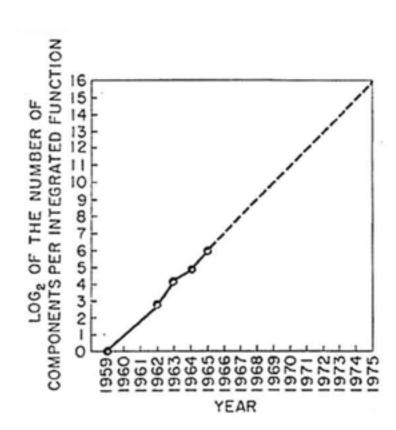




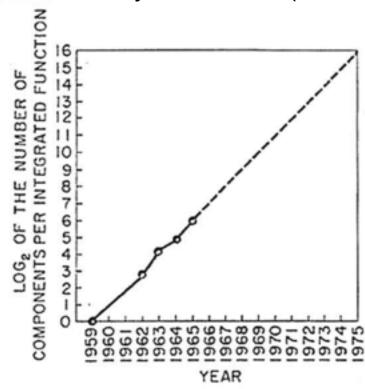


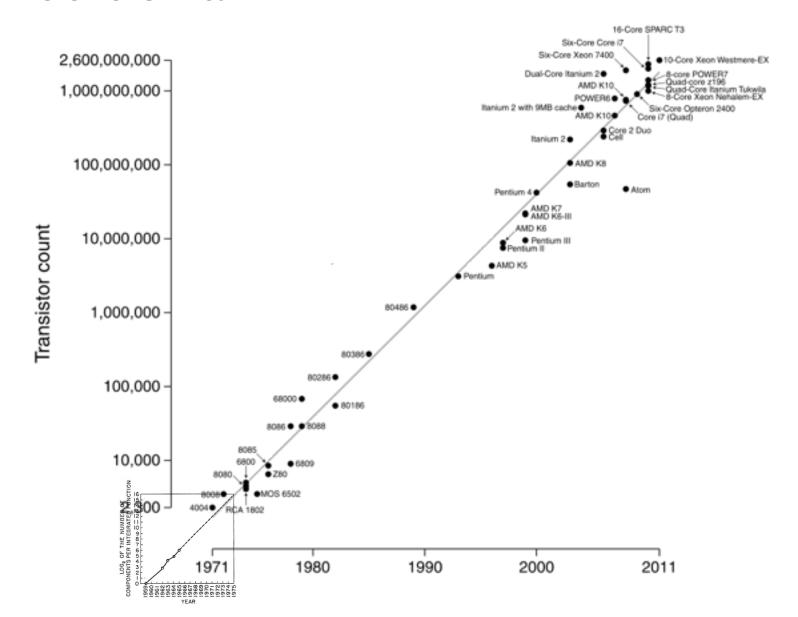


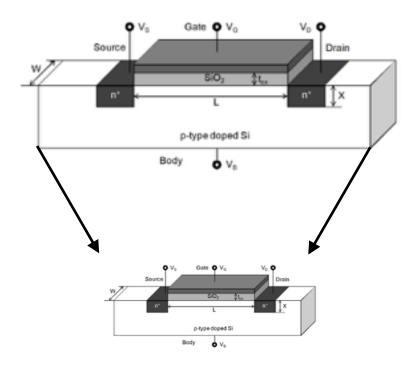
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- In 1975 he revised the prediction to doubling every 2 years



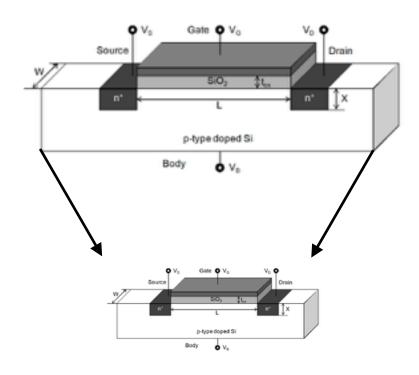
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- Today's widely-known Moore's Law: number of transistors double about every 18 months (Moore never used the number 18...)





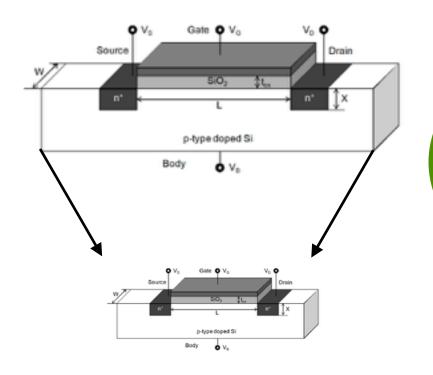


Scale factor α <1 α = 0.7 => 2X more transistors!



Parameter	Value	Scaled Value
Dopant concentrations	Na, Nd	Na/a, Nd/a
Dimensions	L, W, Tox	aL, aW, aTox
Field	Е	Е
Voltage	V	αV
Capacitance	С	αC
Current	1	al

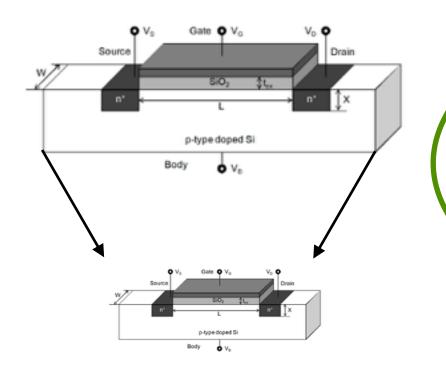
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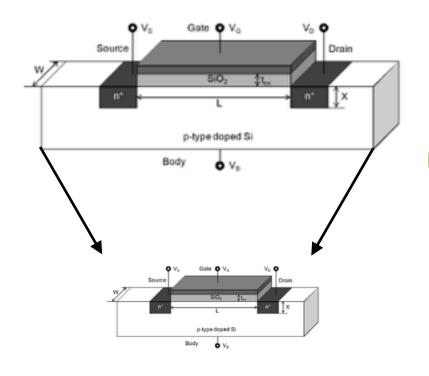
Transistors/Area	d	d/a²	
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Propagation time (~CV/I)	t	at	
Frequency (1/t)	f	f/a	

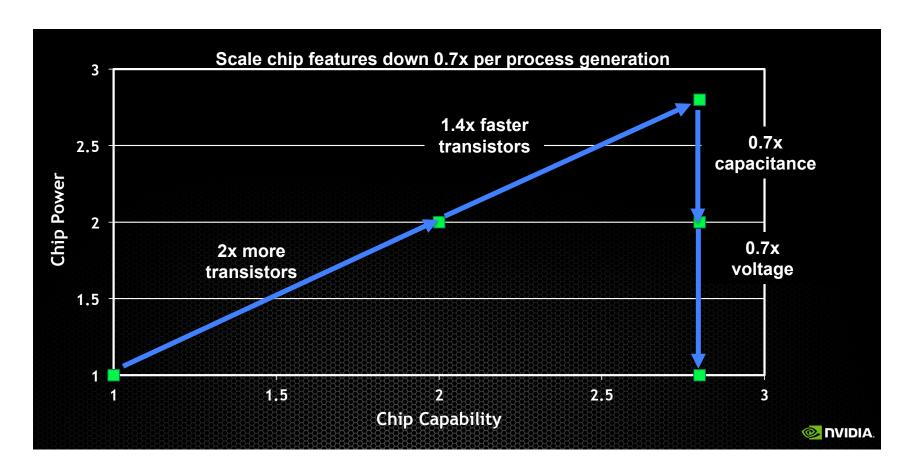
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Frequency (1/t)	f	f/a	
	\		_
Power (CV ² f)	Р	α^2P	
Power/area (Power density)	Pd	pd	

Every generation: 2.8X chip capability in same power



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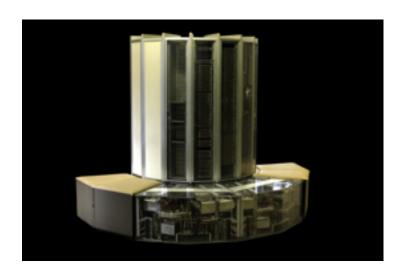
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Moore's law gave us more transistors; Dennard scaling made them useful.

Bob Colwell, DAC 2013, June 4, 2013

Moore's Law + Dennard Scaling Have Meant





• Frequency: 80 MHz

• Speed: 250 M Ops/second

• Scale: 2.5 Million transistors

• 5,000 kg, 115 KW

• Price: \$9M

80 manufactured



• 2014 iPhone 6

• Frequency: 1.4 GHz

• Speed: > 4 B Ops/second

• Scale: > 3 Billion transistors

• 120 g, < 5 W

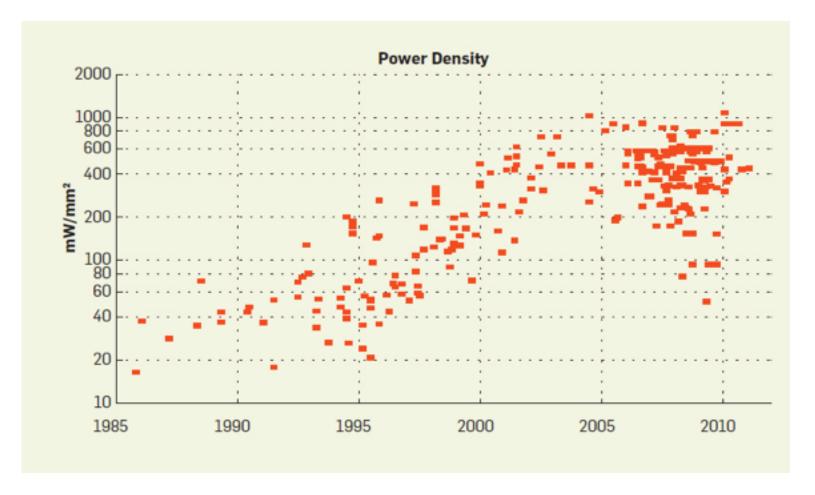
• Price: \$649

10 million sold in first 3 days

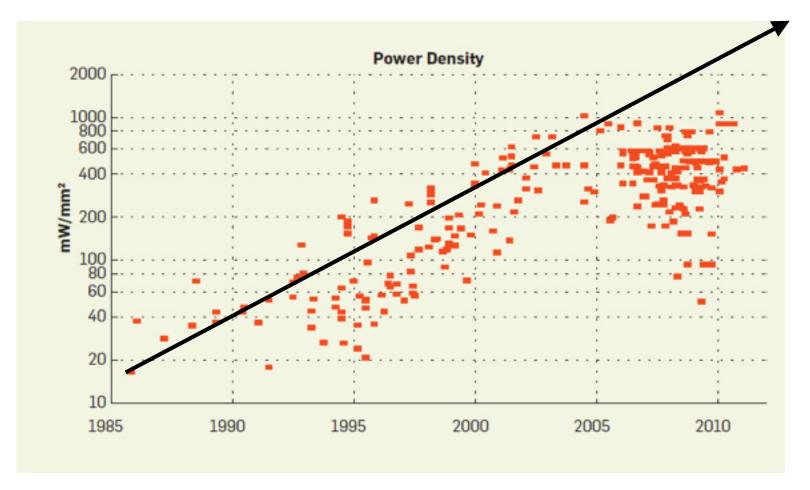
- Slightly worse than ideal Dennard Scaling
 - Power density steadily increasing, but still manageable

Parameter	Value	Scaled Value	
Dimensions	L, W, Tox	0.7 L, 0.7 W, 0.7 Tox	
Dopant concentrations	Na, Nd	1.4 Na, 1.4 Nd	
Voltage	V	0.7 V	0.9 V
Frequency	F	1.4 F	
Power/device	Р	0.5 P	0.8 P
Power/chip	Р	1 P	1.2 P
Power density	P/A	P/A	1.2 P/A

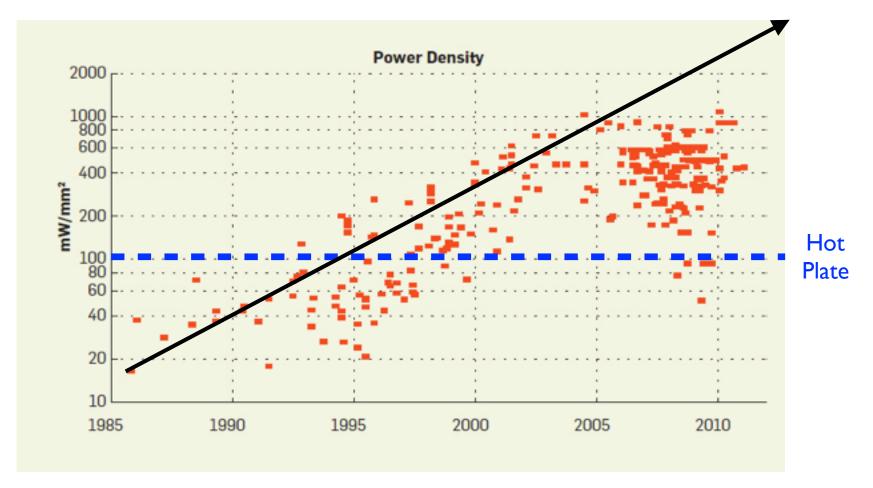
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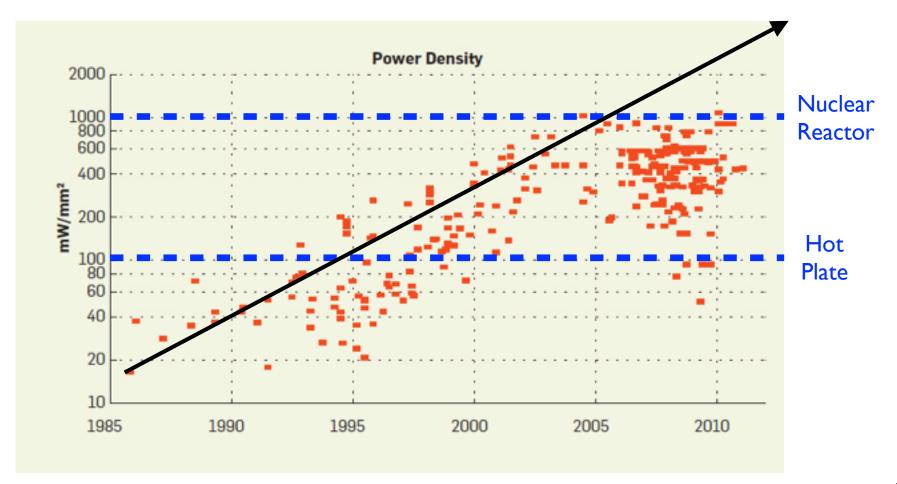
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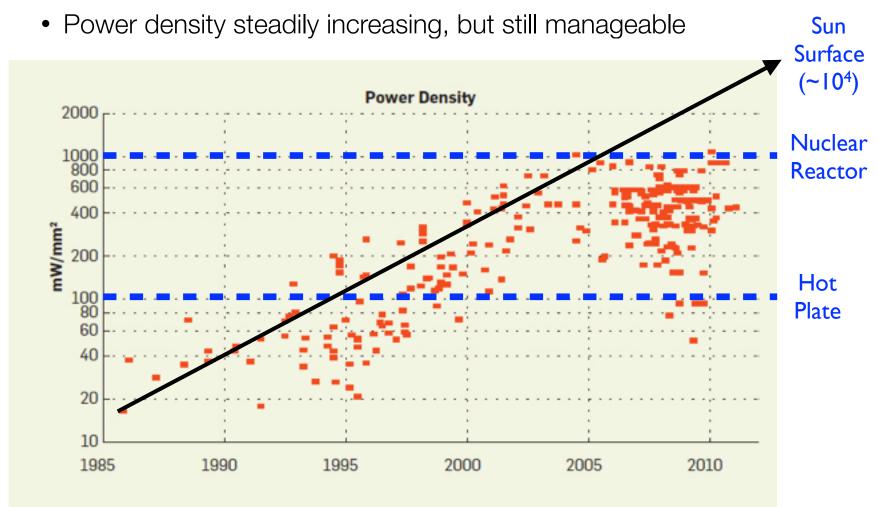
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 - Supply voltage V_{dd} stops scaling (Can't drop voltage below ~1 V)

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- There is a fundamental limit as to how much voltage we need to switch a transistor, called threshold voltage (V_{th}).
- V_{th} stopped scaling because leakage power/reliability/variation becomes huge issues, and accordingly V_{dd} stops scaling

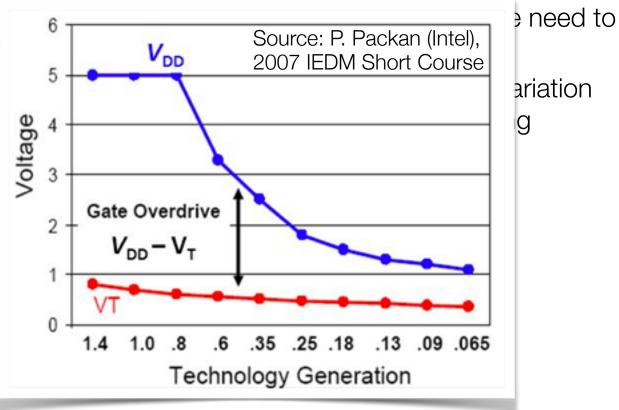
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 - V_{th} stopped scaling because leakage power/reliability/variation becomes huge issues, and accordingly V_{dd} stops scaling
- The demise of Dennard Scaling coupled with power density reaching the limit is a huge crisis for computing industry
 - Power density reached limit even with Dennard scaling, now voltage stops scaling, and things started becoming worse

Dark Silicon

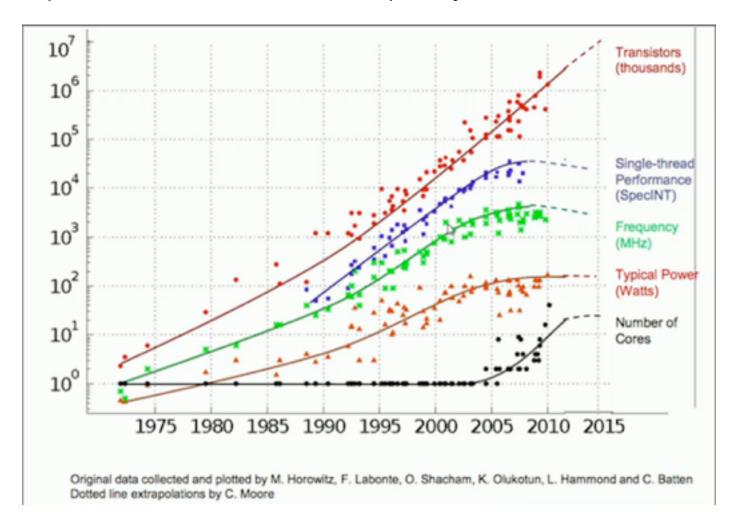
n. [därk, sĭl'ĭ-kən, -kŏn']

More transistors on chip (Moore's Law), but a growing fraction cannot actually be used due to power limits.

• Initial response has been to lower frequency and increase cores / chip

2005: End of Dennard Scaling

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Dark Silicon and the End of Multicore Scaling

Hadi Esmaeilzadeh† Emily Blem‡ Renée St. Amant§ Karthikeyan Sankaralingam‡ Doug Burger°

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ABSTRACT

Since 2005, processor designers have increased core counts to exploit Moore's Law scaling, rather than focusing on single-core performance. The failure of Dennard scaling, to which the shift to multicore parts is partially a response, may soon limit multicore scaling just as single-core scaling has been curtailed. This paper models multicore scaling limits by combining device scaling, single-core scaling, and multicore scaling to measure the speedup potential for a set of parallel workloads for the next five technology generations. For device scaling, we use both the ITRS projections and a set of more conservative device scaling parameters. To model singlecore scaling, we combine measurements from over 150 processors to derive Pareto-optimal frontiers for area/performance and power/performance. Finally, to model multicore scaling, we build a detailed performance model of upper-bound performance and lowerbound core power. The multicore designs we study include singlethreaded CPU-like and massively threaded GPU-like multicore chip organizations with symmetric, asymmetric, dynamic, and composed topologies. The study shows that regardless of chip organization and topology, multicore scaling is power limited to a degree not widely appreciated by the computing community. Even at 22 nm (just one year from now), 21% of a fixed-size chip must be powered off, and at 8 nm, this number grows to more than 50%. Through 2024, only 7.9× average speedup is possible across commonly used parallel workloads, leaving a nearly 24-fold gap from a target of doubled performance per generation.

Categories and Subject Descriptors: C.0 [Computer Systems Organization] General — Modeling of computer architecture: C.0

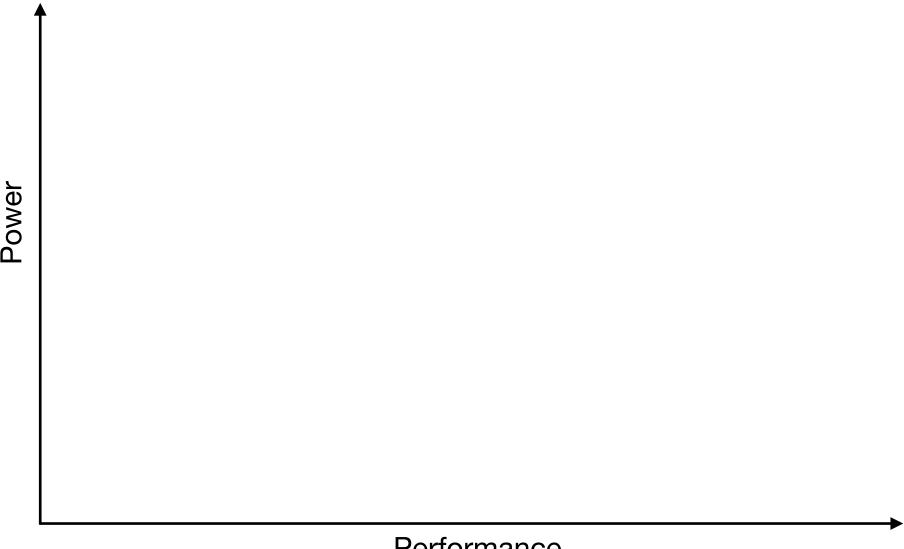
ture, and compiler advances, Moore's Law, coupled with Dennard scaling [11], has resulted in commensurate exponential performance increases. The recent shift to multicore designs has aimed to increase the number of cores along with transistor count increases, and continue the proportional scaling of performance. As a result, architecture researchers have started focusing on 100-core and 1000-core chips and related research topics and called for changes to the undergraduate curriculum to solve the parallel programming challenge for multicore designs at these scales.

With the failure of Dennard scaling-and thus slowed supply voltage scaling-core count scaling may be in jeopardy, which would leave the community with no clear scaling path to exploit continued transistor count increases. Since future designs will be power limited, higher core counts must provide performance gains despite the worsening energy and speed scaling of transistors, and given the available parallelism in applications. By studying these characteristics together, it is possible to predict for how many additional technology generations multicore scaling will provide a clear benefit. Since the energy efficiency of devices is not scaling along with integration capacity, and since few applications (even from emerging domains such as recognition, mining, and synthesis [5]) have parallelism levels that can efficiently use a 100-core or 1000-core chip, it is critical to understand how good multicore performance will be in the long term. In 2024, will processors have 32 times the performance of processors from 2008, exploiting five generations of core doubling?

Such a study must consider devices, core microarchitectures, chip organizations, and benchmark characteristics, applying area

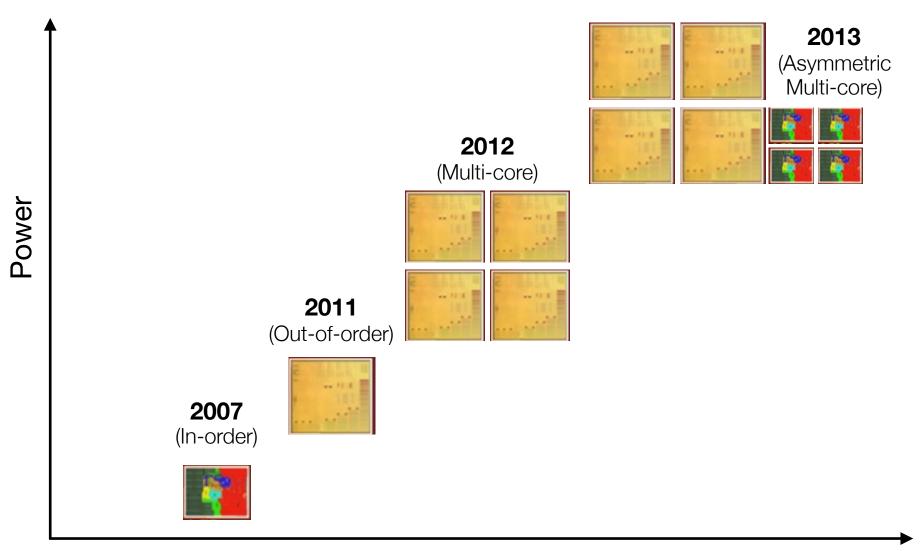
2007: A Revolutionary New Computer

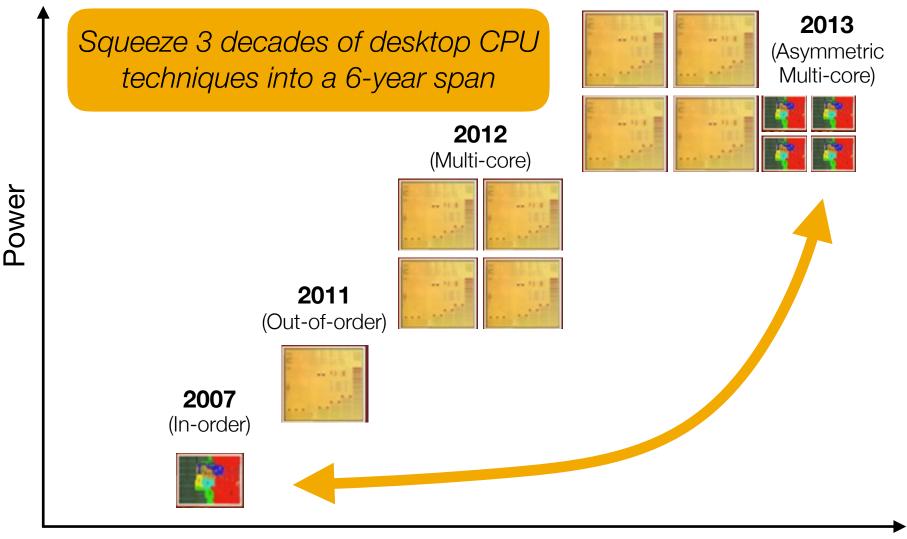




Performance

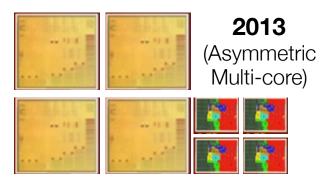
2007 (In-order)



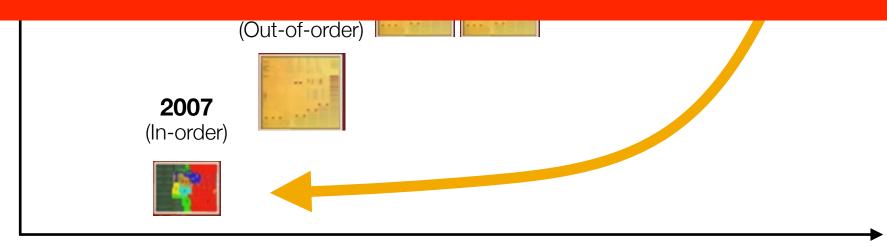




2012 (Multi-core)



Ran Into Dark Silicon Issue in 6 Years





No Moore's Law for batteries

Fred Schlachter¹

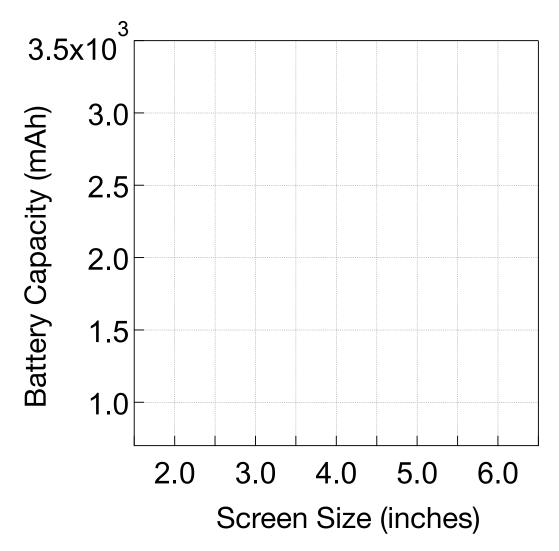
American Physical Society, Washington, DC 20045

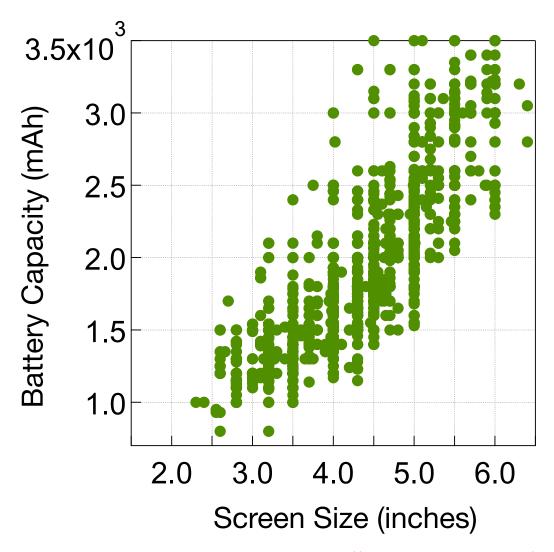
The public has become accustomed to rapid progress in mobile phone technology, computers, and access to information; tablet computers, smart phones, and other powerful new devices are familiar to most people on the planet.

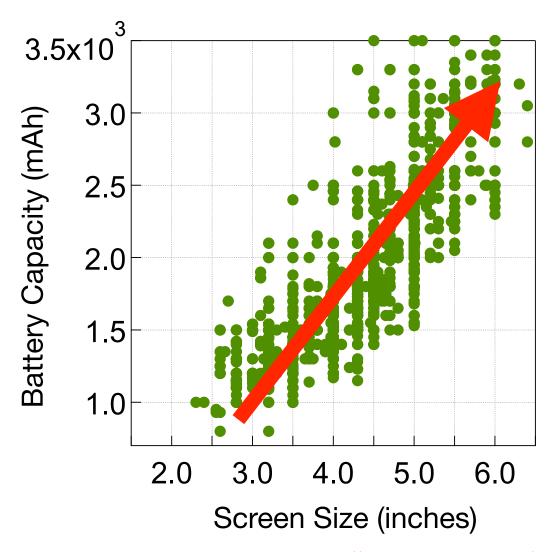
These developments are due in part to the ongoing exponential increase in computer processing power, doubling approximately every 2 years for the past several decades. This pattern is usually called Moore's Law and is named for Gordon Moore, a cofounder of Intel. The law is not a law like that for gravity; it is an empirical observation, which has become a self-fulfilling prophecy. Unfortunately, much of the public has come to expect that all technology does, will, or should follow such a law, which is not consistent with our everyday observations: For example, the maximum

there is a Moore's Law for computer processors is that electrons are small and they do not take up space on a chip. Chip performance is limited by the lithography technology used to fabricate the chips; as lithography improves ever smaller features can be made on processors. Batteries are not like this. Ions, which transfer charge in batteries, are large, and they take up space, as do anodes, cathodes, and electrolytes. A D-cell battery stores more energy than an AA-cell. Potentials in a battery are dictated by the relevant chemical reactions, thus limiting eventual battery performance. Significant improvement in battery capacity can only be made by changing to a different chemistry.

Scientists and battery experts, who have been optimistic in the recent past about improving lithium-ion batteries and about de-



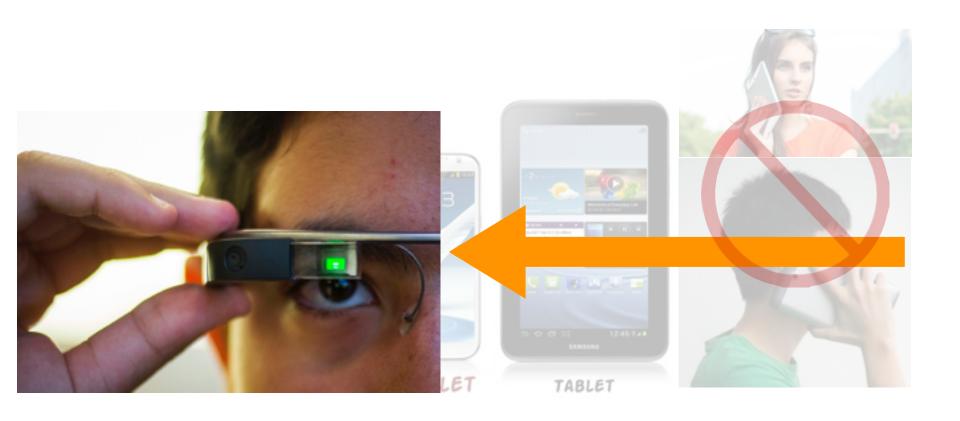




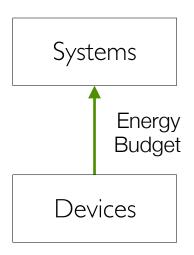


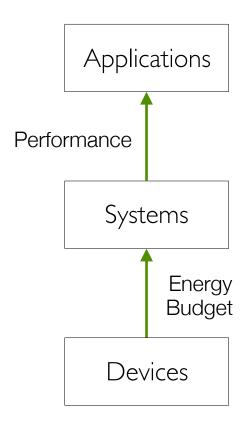


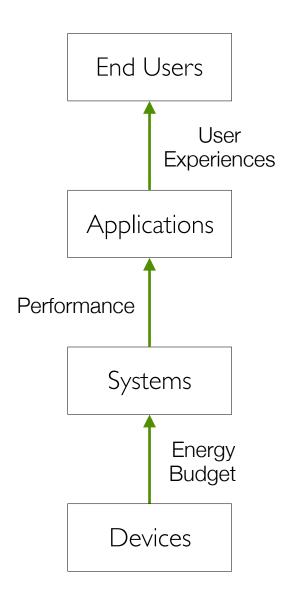


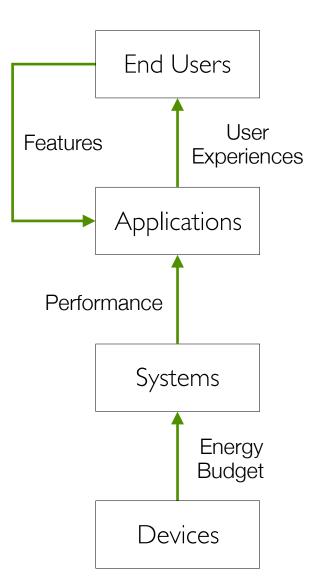


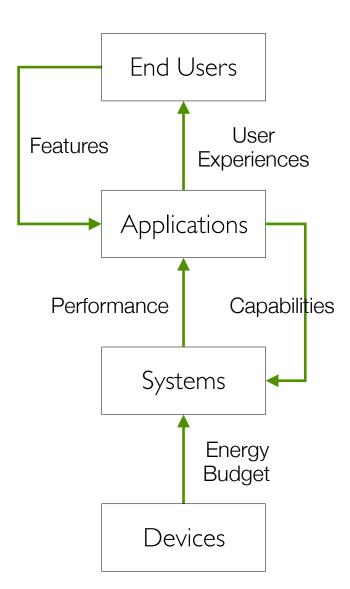
Devices

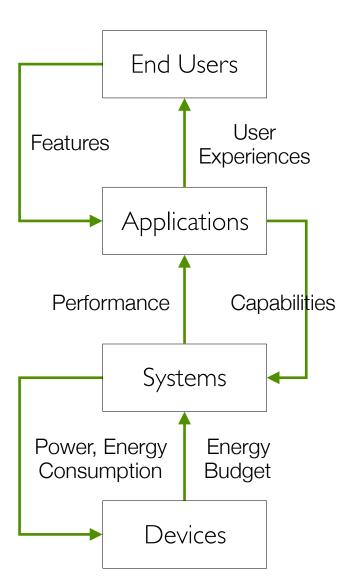


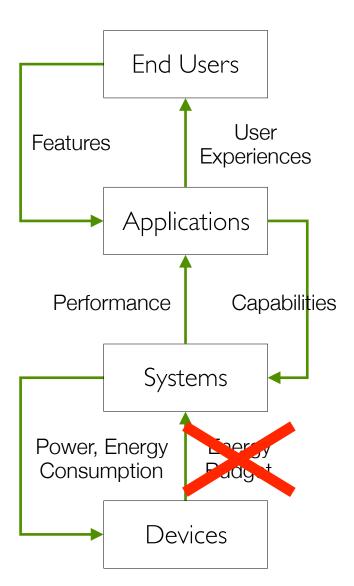












Mobile CPU's Rise to Power: Quantifying the Impact of Generational Mobile CPU Design Trends on Performance, Energy, and User Satisfaction

Matthew Halpern Yuhao Zhu Vijay Janapa Reddi The University of Texas at Austin, Department of Electrical and Computer Engineering {matthalp,yzhu}@utexas.edu, vj@ece.utexas.edu

Abstract

In this paper, we assess the past, present, and future of mobile CPU design. We study how mobile CPU designs trends have impacted the end-user, hardware design, and the holistic mobile device. We analyze the evolution of ten cutting-edge mobile CPU designs released over the past seven years. Specifically, we report measured performance, power, energy and user satisfaction trends across mobile CPU generations.

A key contribution of our work is that we contextualize the mobile CPU's evolution in terms of user satisfaction, which has largely been absent from prior mobile hardware studies. To bridge the gap between mobile CPU design and user satisfaction, we construct and conduct a novel crowdsourcing study that spans over 25,000 survey participants using the Amazon Mechanical Turk service. Our methodology allows us to identify what mobile CPU design techniques provide the most benefit to the end-user's quality of user experience.

Our results quantitatively demonstrate that CPUs play a crucial role in modern mobile system-on-chips (SoCs). Over the last seven years, both single- and multicore performance improvements have contributed to end-user satisfaction by reducing user-critical application response latencies. Mobile CPUs aggressively adopted many power-hungry desktoporiented design techniques to reach these performance levels. Unlike other smartphone components (e.g. display and radio) whose peak power consumption has decreased over time, the mobile CPU's peak power consumption has steadily increased.

As the limits of technology scaling restrict the ability of desktop-like scaling to continue for mobile CPUs, specialized accelerators appear to be a promising alternative that can help sustain the power, performance, and energy improvements that

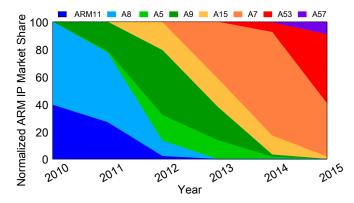


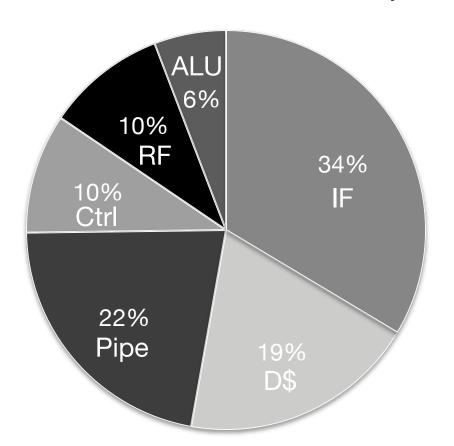
Fig. 1: Breakdown of yearly ARM Cortex-A CPU design market share. Mobile CPU core designs have rapid design iteration and innovation. At least one new core design is released each year and newer designs overshadow the older ones.

rate to keep pace with end-user demands. Fig. 1, based on data mined from over 1700 Android smartphone specifications, conveys the fast pace at which mobile CPU designs have evolved. Considering the ARM-based Cortex-A series alone, the most dominant mobile CPU design in smartphones and tablets to date [1], at least one new CPU core design has been released each year for the last six years – each significantly more advanced than the last. In comparison, x86-based desktop CPU designs did not exhibit as dramatic changes. Intel-based desktop processors only exhibited four significant core design changes throughout the same time span.

The rapid design innovation, pervasiveness in society, and power-constrained nature of mobile hardware necessitate the need to understand the implications of their current design trends on future designs. Mobile CPUs have evolved from em-

General-Purpose CPU = Instruction Delivery + Data Feeding + Execution + Control, where instruction delivery, data feeding & control are pure overhead

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IF: Instruction fetch

Ctrl: Other control logics

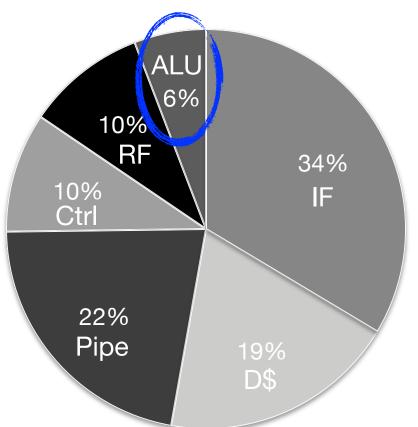
Pipe: Pipeline reg, bus, clock

D\$: Data cache

RF: Register file

ALU: Functional units

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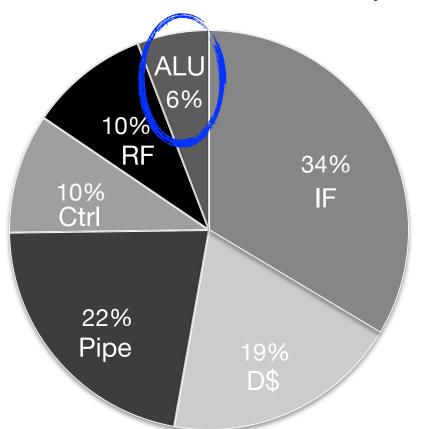
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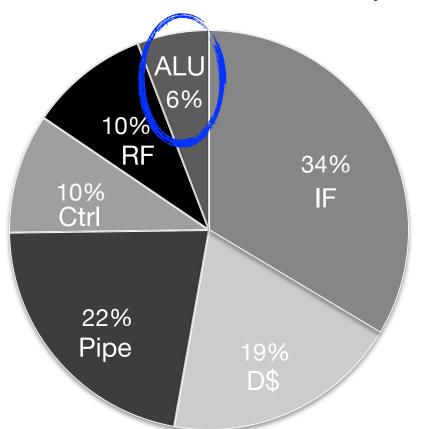
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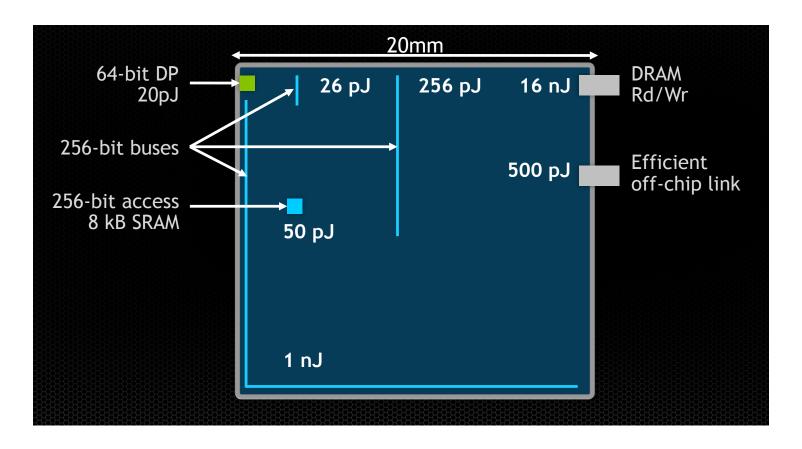
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Doing Actual Work

General-Purpose CPU = Instruction Delivery + Data Feeding + Execution + Control, where instruction delivery, data feeding & control are pure overhead



Now What?

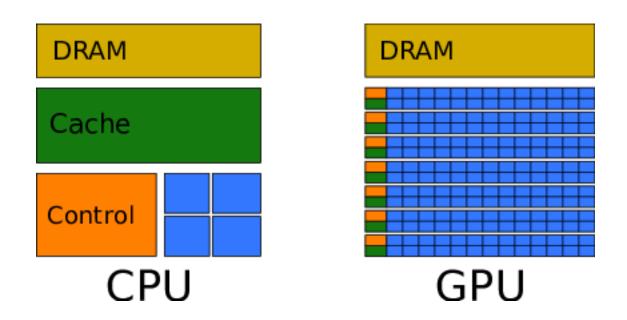
Entering the Era of Specialization

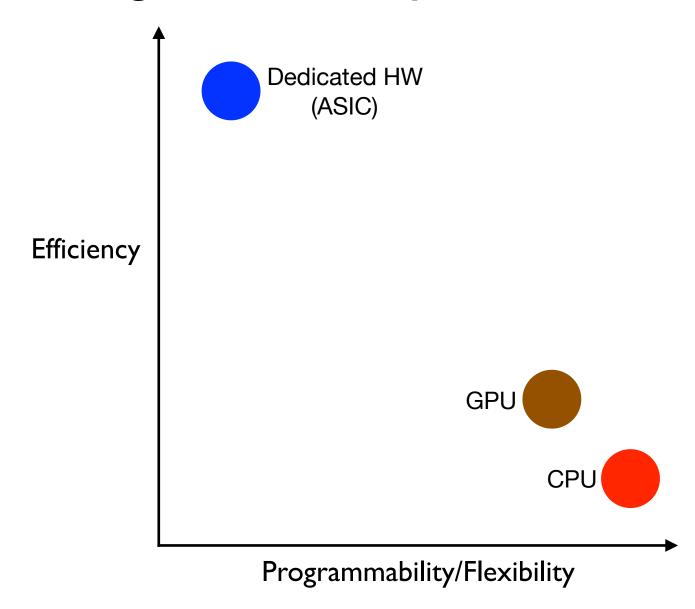
 Instead of building general-purpose processors that can do everything, but inefficiently, let's build specialized processors that can only do limited things, but extremely efficiently.

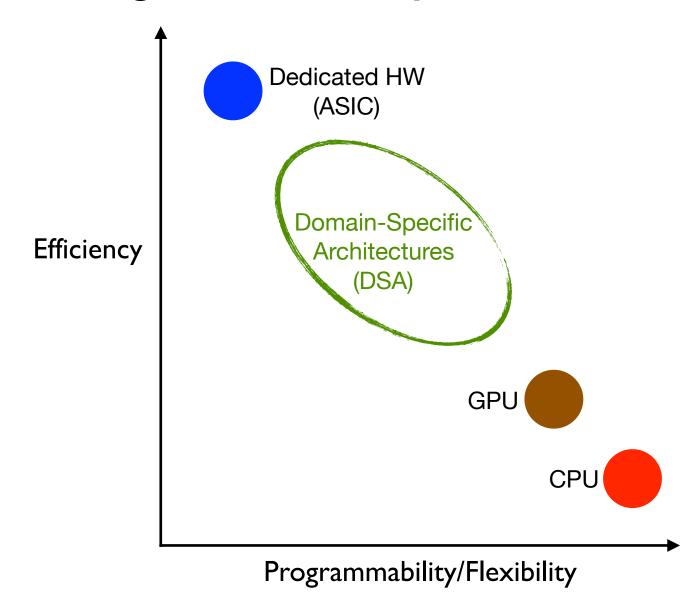
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- Extreme example: Application-Specific Integrated Circuit (ASIC)
- Imagine the entire processor is an FP adder with 2 registers
 - Instruction delivery: none. Instructions are implicit (add).
 - Data feeding: simple.
 - Control: little: clock the adder, simple pipeline, etc.
 - Execution: will be the major power consumer.
 - Flexibility/programmability: very limited: addition only, nothing else!

- Another example: Graphics Processing Unit (GPU)
 - SIMT: Single instruction multiple thread
 - SIMT amortizes control/instruction delivery overhead
 - Data feeding is still very complex
 - More efficient execution for applications that are massively parallel









30 second video: 1920 x 1080, @ 30fps

8-bits per color → 24 bits/pixel → 6.2MB/frame (6.2 MB*30 sec*30 fps = 5.2 GB)

Actual H.264 video file size: 65.4 MB (80-to-1 compression ratio)

Compression/encoding performed in real time on iPhone 5s

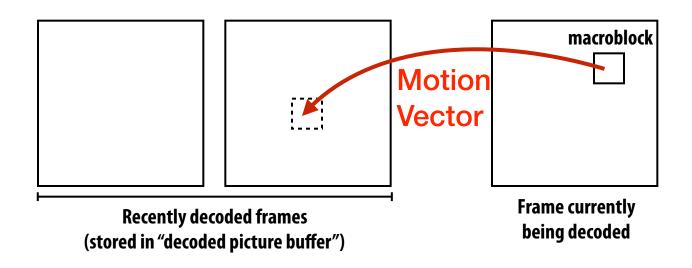


Main Idea: Exploiting Redundancies

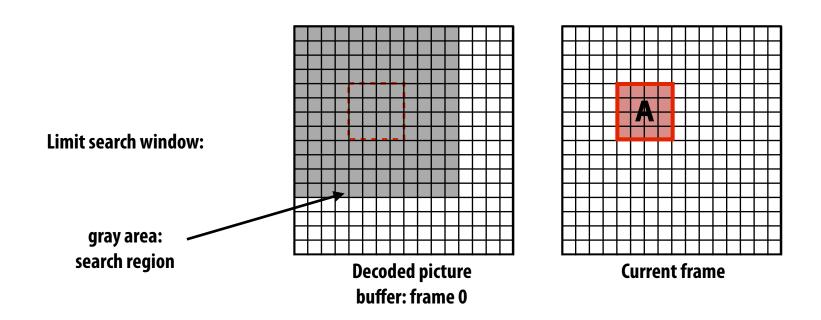
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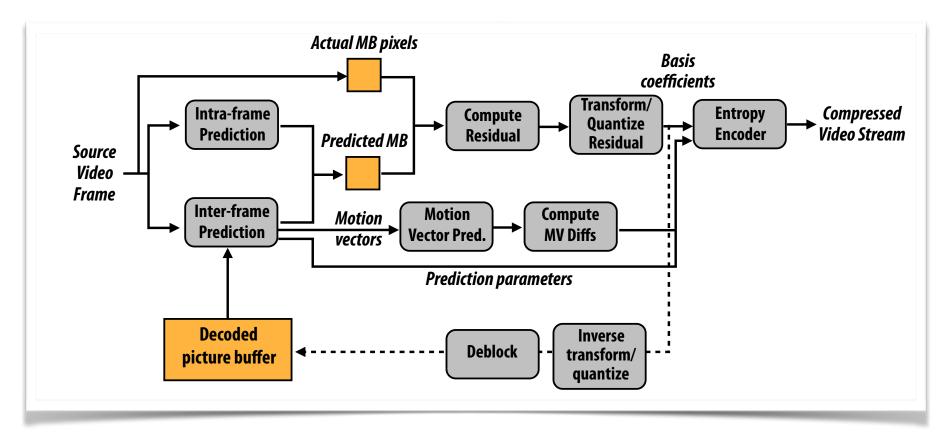
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- Key Operation: Motion Estimation
- Remember, must execute motion estimation in real-time for HD video (1920x1080), on a low-power smartphone.

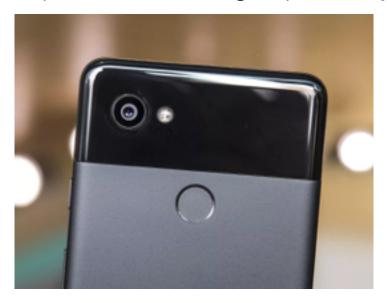


 Specialized hardware for H.264 video codec is virtually in every (mobile) platforms. Very efficient for video (de)-compression, but can't do much else.



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- But smartphone cameras aren't as good as high-end digital single-lens reflex cameras.
 - Aperture, focal length, pixels, dynamic range, sensors, resolution, etc.





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- But smartphone cameras aren't as good as high-end digital single-lens reflex cameras.
 - Aperture, focal length, pixels, dynamic range, sensors, resolution, etc.
- How to achieve DSLR-like quality in a smartphone form factor?
- Computational photography: digitally post-processing images
 - E.g., High-dynamic range (HDR)
 - Used to be just in desktop photo editing software (e.g., PhotoShop), but now in high-end smartphones



Short Exposure



Long Exposure









Short Exposure

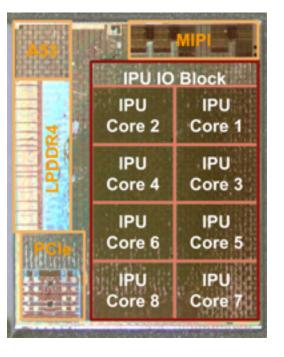
Long Exposure



- ISP (Image Signal Processor): Specialized processors for imaging and computational photography algorithms.
- Fast, energy-efficient, but only for imaging

Google Pixel 2





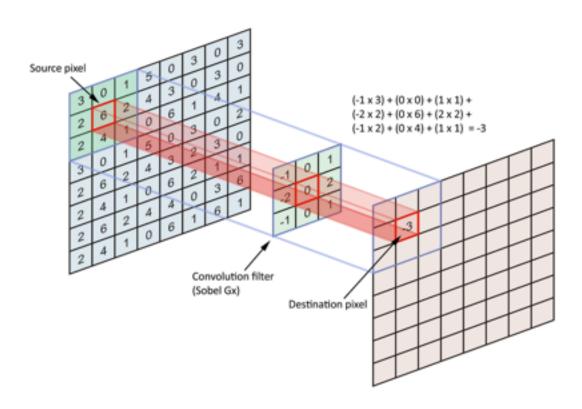
Example: Machine Learning

- Machine learning (e.g., Neural Networks) takes over the world
- Computer vision is the poster-child example
- Natural language processing, Precision medicine, robotics planning, house rent/load prediction, games, etc.



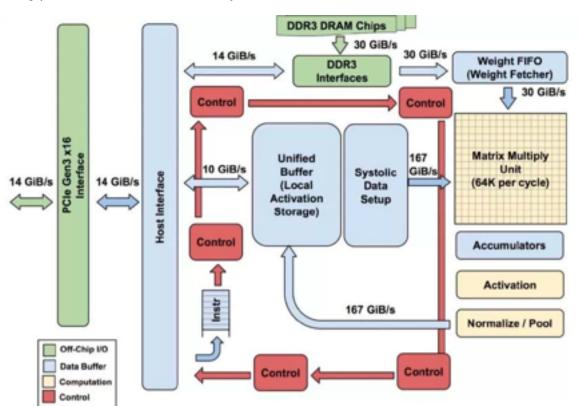
Example: Machine Learning

- Neural networks make heavy use of the convolution operation
 - Convolution can be transformed to matrix-multiplication
 - Convolutional neural networks (CNN) are by far the most popular NN, especially effectively for computer vision tasks

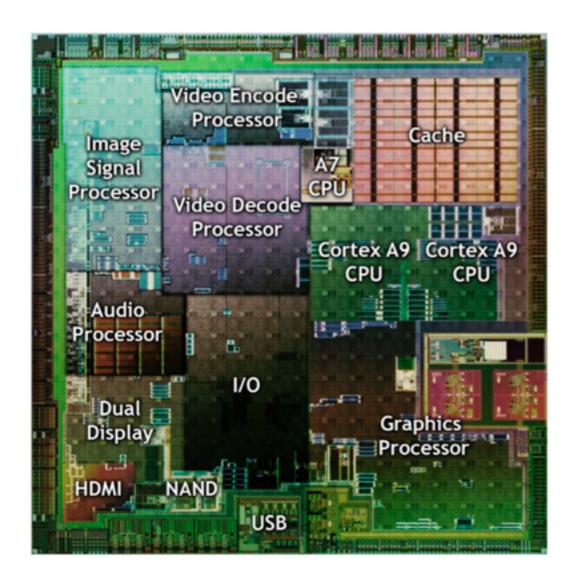


Example: Machine Learning

- Google Tensor Processing Unit (TPU)
 - Specialized processor (i.e., systolic array architecture) for tensor processing (matrix multiply)
 - (Arguably) 30x~80x more power-efficient than GPU



Today's Mobile Processor Chips



Problem Algorithm Program Instruction Set Architecture Microarchitecture Circuit

- Look Up
 - Nature of the problems

Problem

Algorithm

Program

Instruction Set Architecture

Microarchitecture

Circuit

- Look Up
 - Nature of the problems
- Look Down
 - Nature of the circuit technology and physics

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 - Evaluating old ideas in light of new technologies
- Look Forward
 - Listen to dreamers and predict the future

Problem

Algorithm

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Instruction Set Architecture

Microarchitecture

Circuit