

# Damped Harmonic Oscillator

- 2nd-order system
- Very basic approach to all systems.



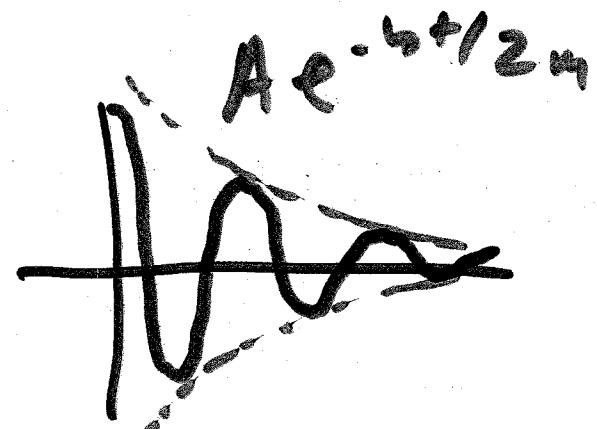
$-kx$  spring force

$-b \frac{dx}{dt}$  damping force

$$F = m\ddot{x}$$

$$-kx - b \frac{dx}{dt} = m \frac{d^2x}{dt^2}$$

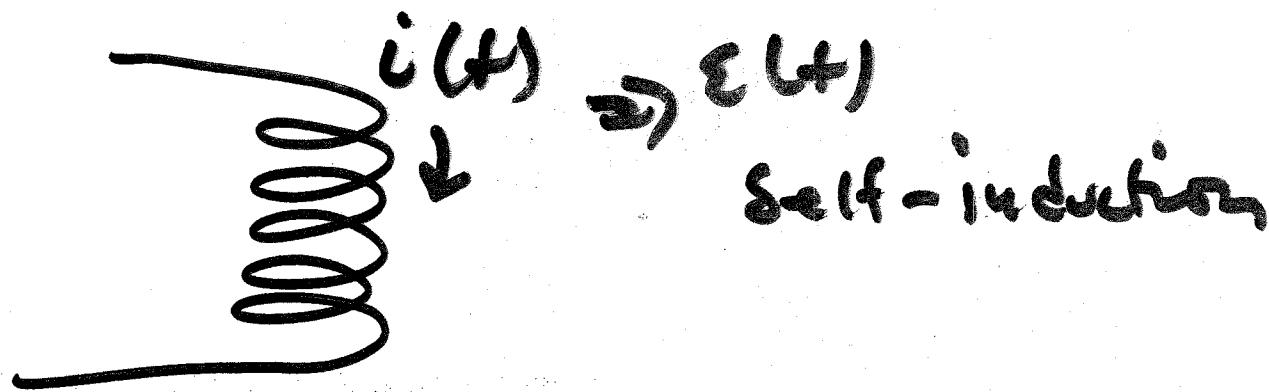
$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = 0$$



$$x = Ae^{-bt/2m} \cos(\omega' t + \delta)$$

$$\omega' = \sqrt{\frac{k}{m} - \left(\frac{b}{2m}\right)^2}$$

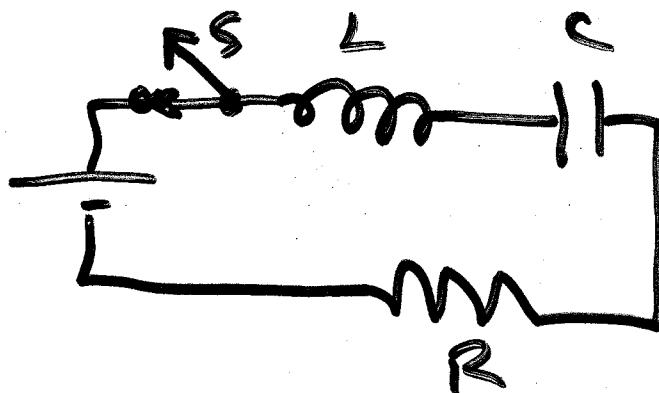
# INDUCTANCE



self-induction

coil

$$\epsilon = -L \frac{di}{dt} = -L \frac{d^2q}{dt^2}$$

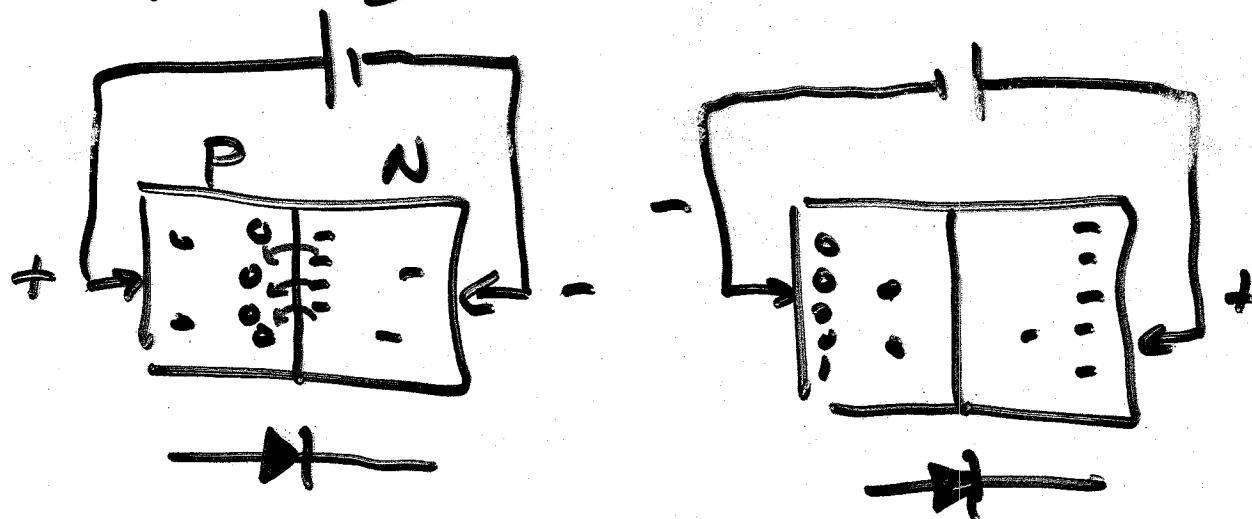


$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = 0 \quad \}$$

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = 0 \quad \}$$

⇒ Analog computers, controllers, ...

# HOW DIODES WORK (KIMMERS)



if  $V > 0.6$  Volts,  
electrons jump the  
gap!

Forward Bias

Voltage (charge)  
attracts holes and  
electrons away from  
junction. No  
jumping.

Reverse Bias

# TRANSISTOR:

- bipolar
- Many types - field effect
- components ICs; essential ingredient. Must know about if build own interfaces, want to connect ICs, design circuits.
- Mosas or the Art of Electronics  
Horowitz & Hill (Cambridge).

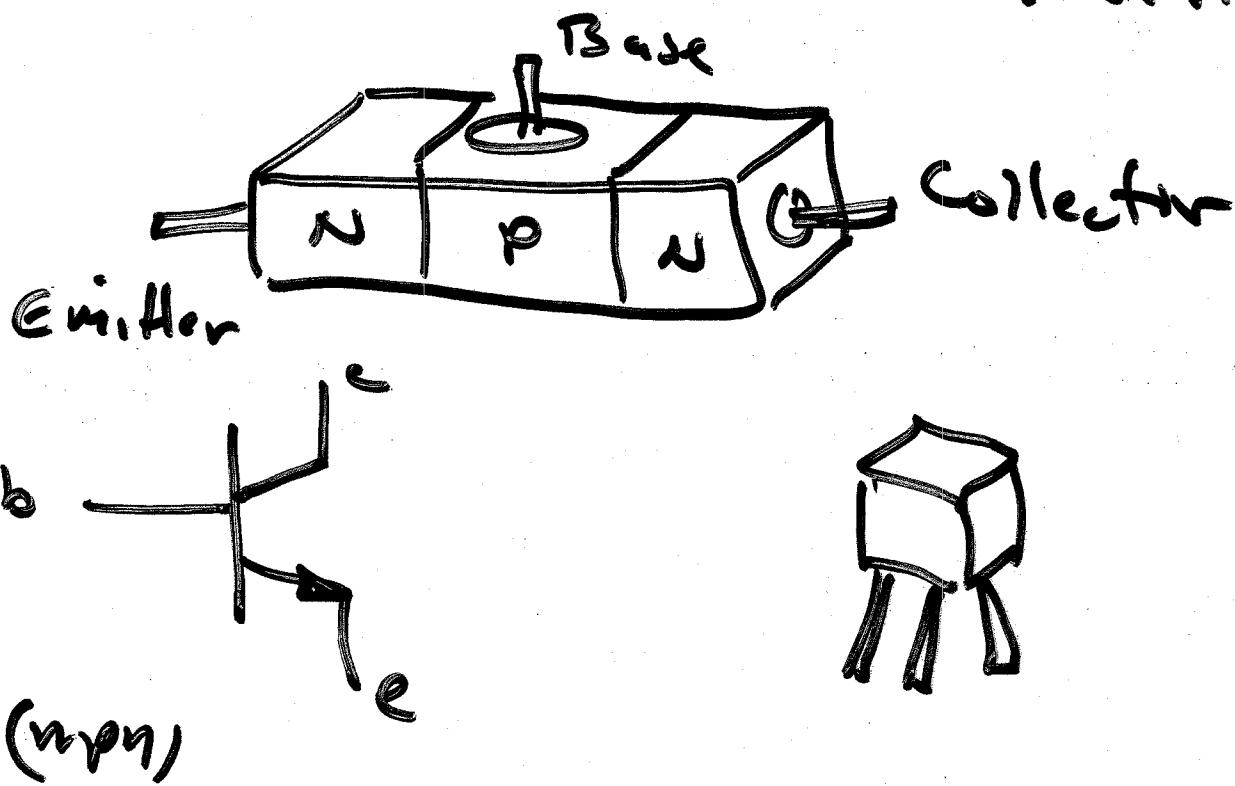
## o Basic Property:

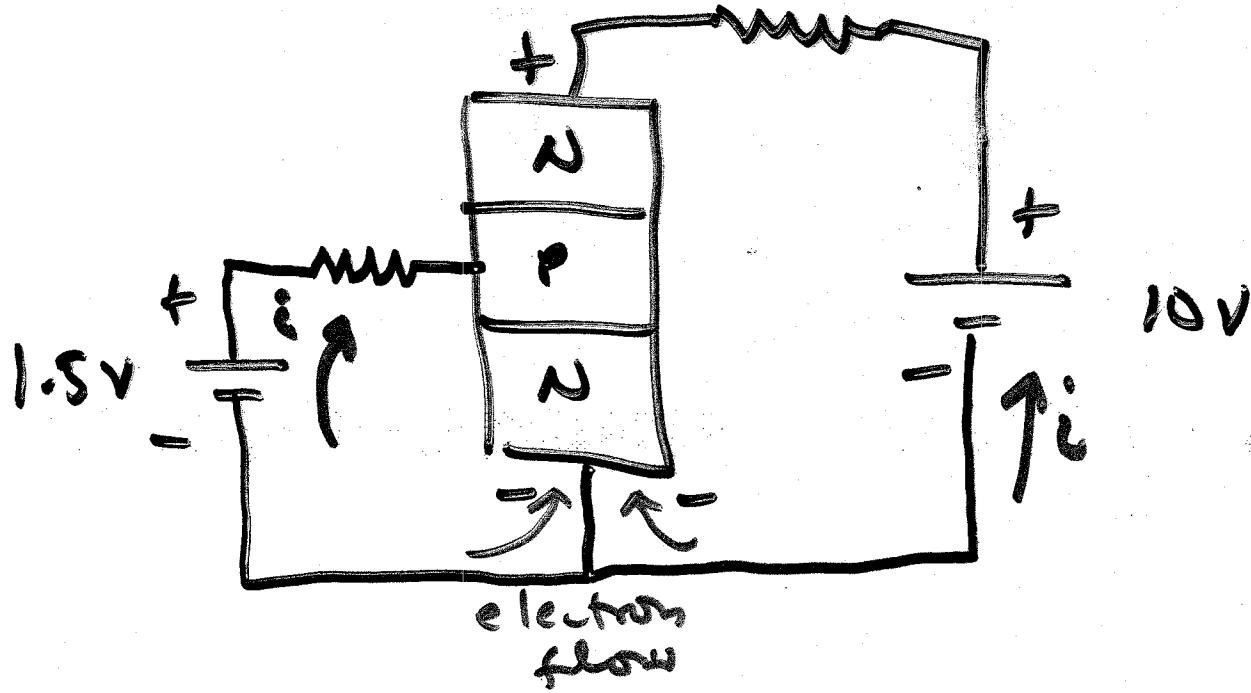
3-terminal  
active  
non linear

- active: can amplify signals
  - can build oscillators where some output is fed back to input.
  - can control big signals with small ones.

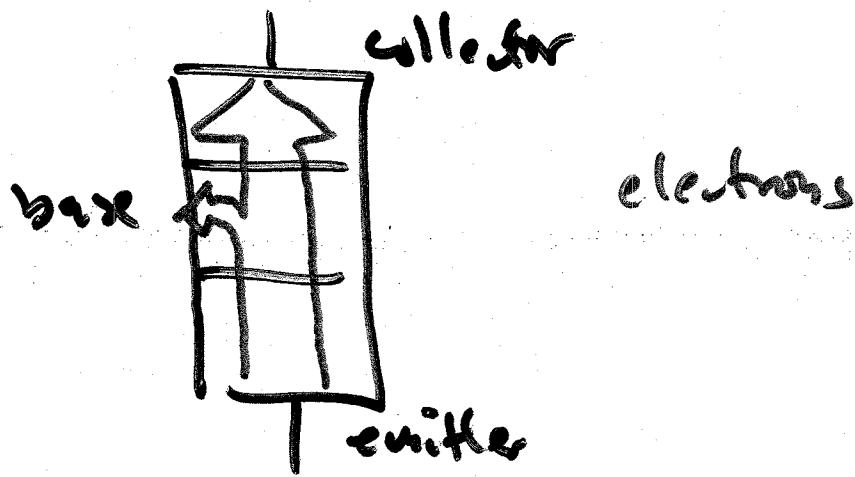
## BIPOLAR :

- Add a 2nd junction to pn diode, get npn or pnp transistor.
- Middle layer acts like a faucet controlling current across all 3 layers. Its small size means it takes less current to control it.



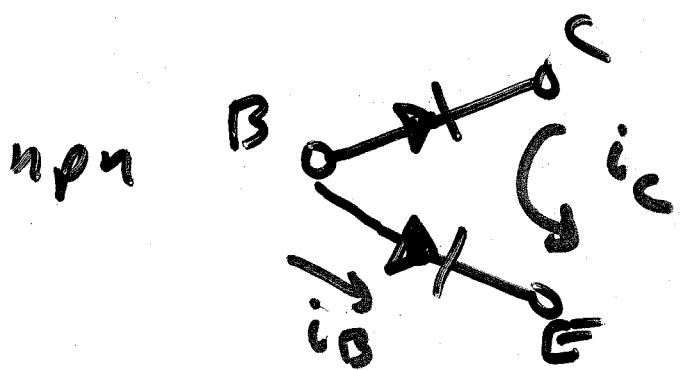


— ~~MM~~ Limit current the transistor.



For npn:

1. Collector must be more positive than emitter.
2. Individually, base-emitter and base-collector circuits act like diodes. Normally b-e diode conducts and b-c is reverse biased.



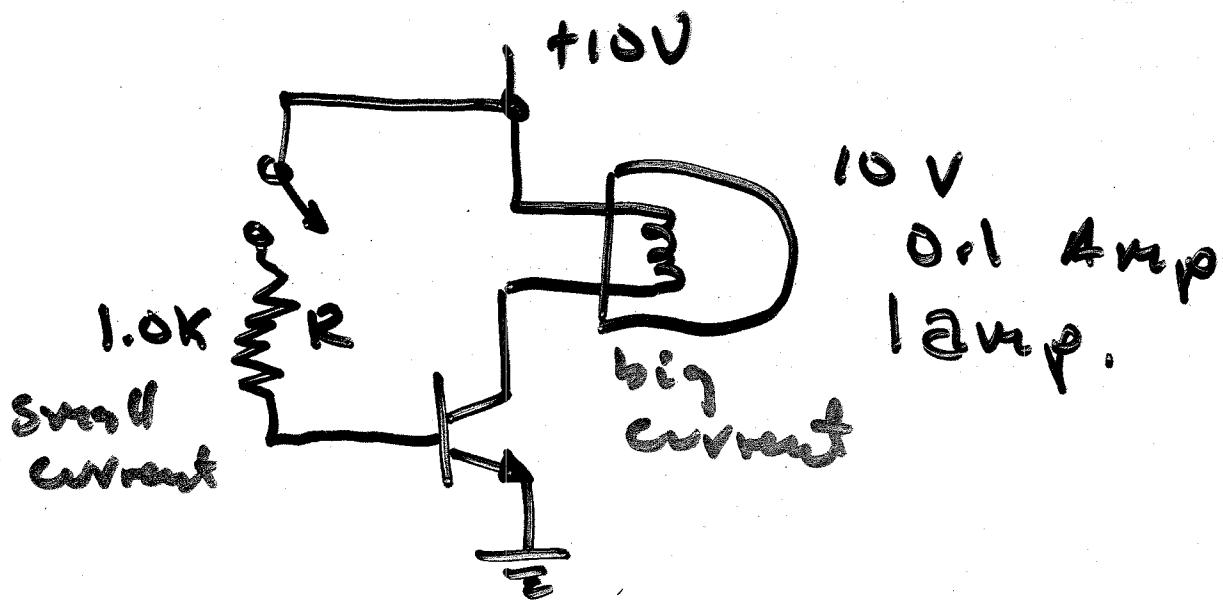
3. Any transistor has maximum  $I_C$ ,  $I_B$ ,  $V_{CE}$ . Else  $\frac{1}{2} \text{pow} = 0$ . Also other limits.
4. If ok so far, expect

$$I_C = \beta I_B, \quad \beta \approx 100$$

How? NOT FWD conduction of BC: that's reverse-biased: it's "Transistor action". [5]

E.G.

## TRANSISTOR SWITCH



o Close switch: base rises to .6 V.

(b-e diode is in forward conduction)

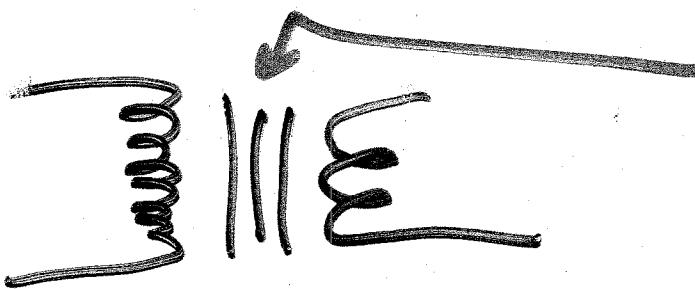
o Drop across R is thus 9.4 V, so base current is  $9.4 \text{ mA}$  ( $\frac{9.4}{1000}$ ).

o Lamp lights. at 10 Volts, lamp has  $I = 100 \text{ mA}$  current.

o Transistor does not go to  $940 \mu\text{A}$ ; it saturates with collector as close to ground as it can get ( $1.1\text{V}$ ). 5

See MIMUS pp 48-57  
for more EEs, all about  
Field-Effet Transistors, etc.

# TRANSFORMERS



Primary      Secondary

AC voltage applied to primary  
appears at secondary with  
voltage multiplication proportional  
to the turns ratio of the transformer  
and current inversely proportional to  
the ratio.

Line 110 →  $\frac{V}{?}$   
Voltage      ↘ 1,000, ... 10,000 V.

"Power Transformers"

Audios =

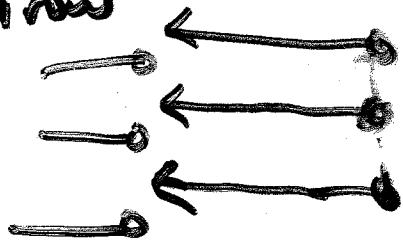
radios =

frequencies =

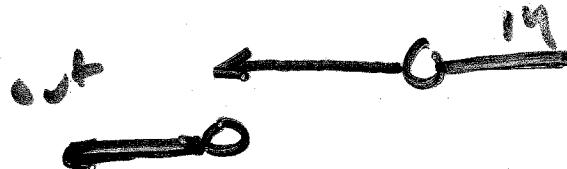
(5)

# RELAYS

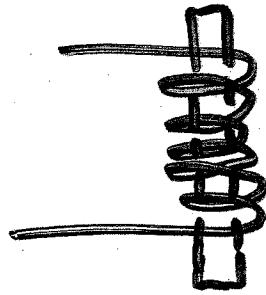
flow



Poles



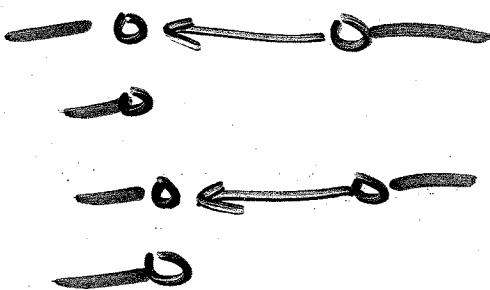
SPST



electro-  
magnet



SPDT



DPDT

# SENSORS

- TOUCH
- SIGHT
- TASTE
- SMELL
- HEARING
- PROPRIOCEPTION
- PROXIMITY
- RANGE
- DIRECTION

} ROBOTS

EVERETT'S BOOK ON RESERVE

MIMMS: 65-77.

J+F: Ch. 5

INTERFACING SENSORS .. J+F  
(like all I/O)

(WE'LL DO LATER)

ROBOTS ARE SENSOR-DEPRIVED.<sup>1</sup> 10

## TOUCH

- SWITCHES ( $\mu$  SWITCHES)
- FORCE (Artificial Skin, string gauges)

## DIRECTION

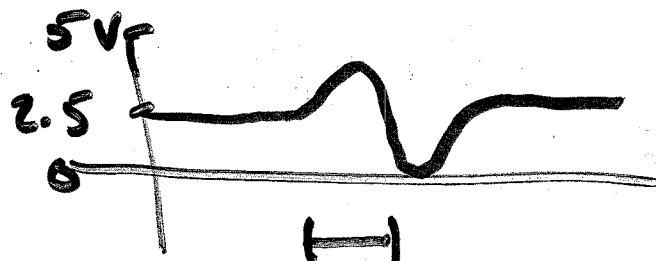
- COMPASS (SERIAL OUTPUT)
- GPS (Differences)

## LOCATION

- GPS
- SHAFT ENCODERS (ODOMETRY)

## HEAT -

- PYRO ELECTRIC SENSOR  
(JFF p. 135)



Heat Source Goes By

## UV

- HOME FIRE FIGHTING UNREST

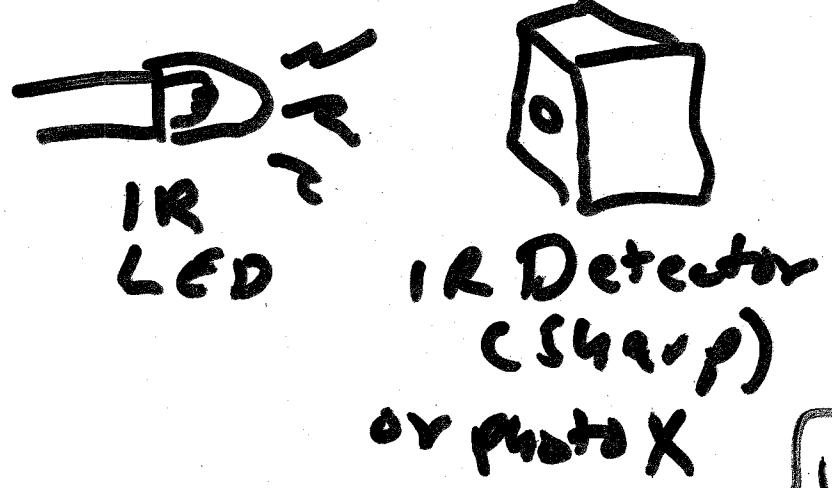
# TASTE, SHELL: CURRENT RESEARCH.

## HEARINGS:

- MICROPHONE (CLAP SENSOR; NOISE!).
- PIEZOELECTRIC FILM
  - VIBRATIONS
  - FORCE
  - TEMPERATURE
  - IR RADIATION
- SONAR
  - POLAROID IC17
  - RANGE
  - PROXIMITY

## PROXIMITY

- IR
- SONAR



## LIGHT:

- VISION: cf. Ballard & Brown  
Sunkar et.al

CSC 249/449

3 small cameras,  
e.g. Quickcam.

Hobby-Scale devices

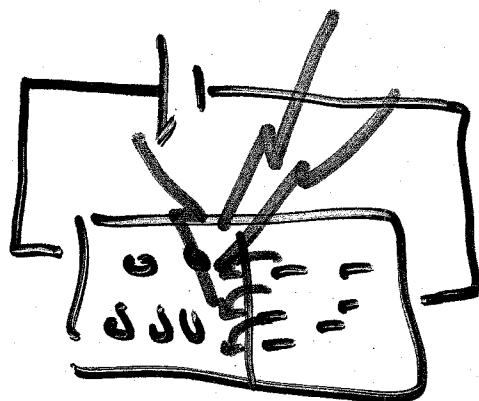
Light-Emitting Diodes (LEDs)

Photo diodes

Photo transistors

# LEDS

- Simply p-n junction diodes.
- Very efficient
- Various colors, wavelengths.

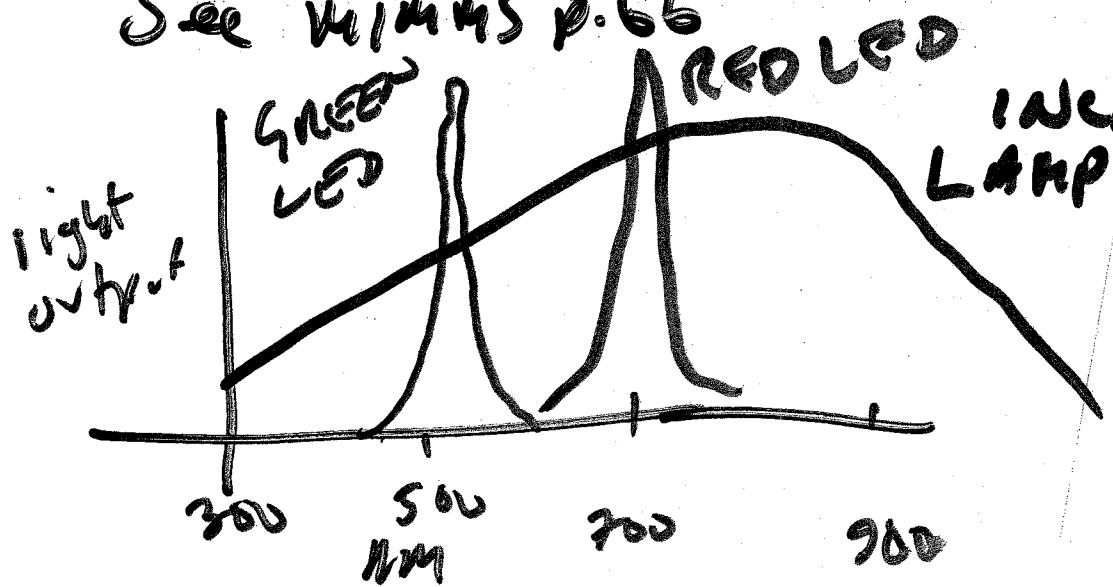


→ Current  
← Electron.

.6 V (Silicon)  
1.3 V (Gallium  
Arsenide)

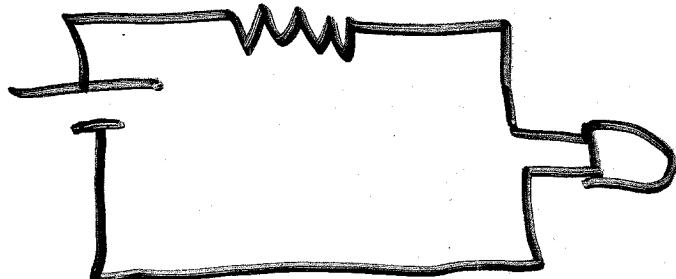
$$R = \frac{V}{I}$$

See Williams p.66



INCLINED LAMP  
from a 5  
if  $V_{LED} =$   
 $= 1.90$ .

- Voltage - current relationship  
limits!
- light & current
- voltage related to wavelength.
- pulsed operation at enormous currents.



Current -  
limiting  
resistor.

$$R = \frac{E}{I} = \frac{V - V_{LED}}{I_{LED}}$$

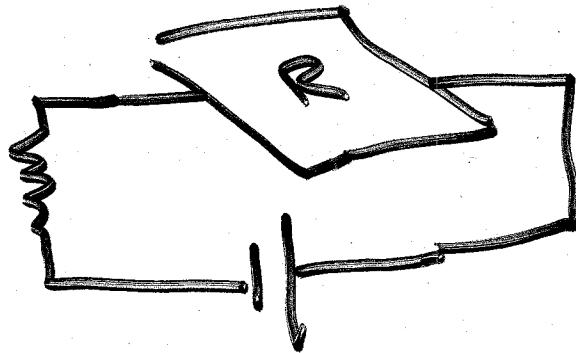
To operate LED at 20 mAmp from a 5-volt power supply,  
if  $V_{LED} = 1.2\text{ V}$  (from its specs)  
 $= 190\Omega$

# SEMICONDUCTOR LIGHT DETECTORS

- photons excites electrons to higher levels & create holes... if electrons & holes separate, can get a current.

PHOTORESISTOR (CDS) (PLS)  
(Light Meters)

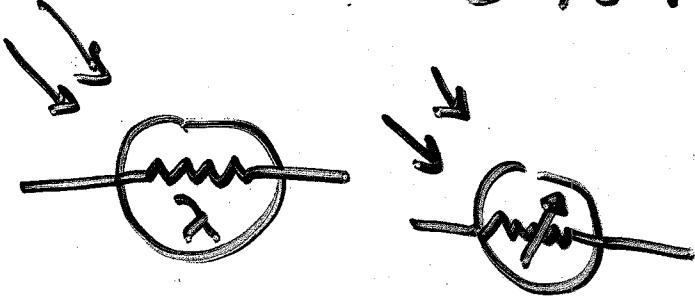
Circuit



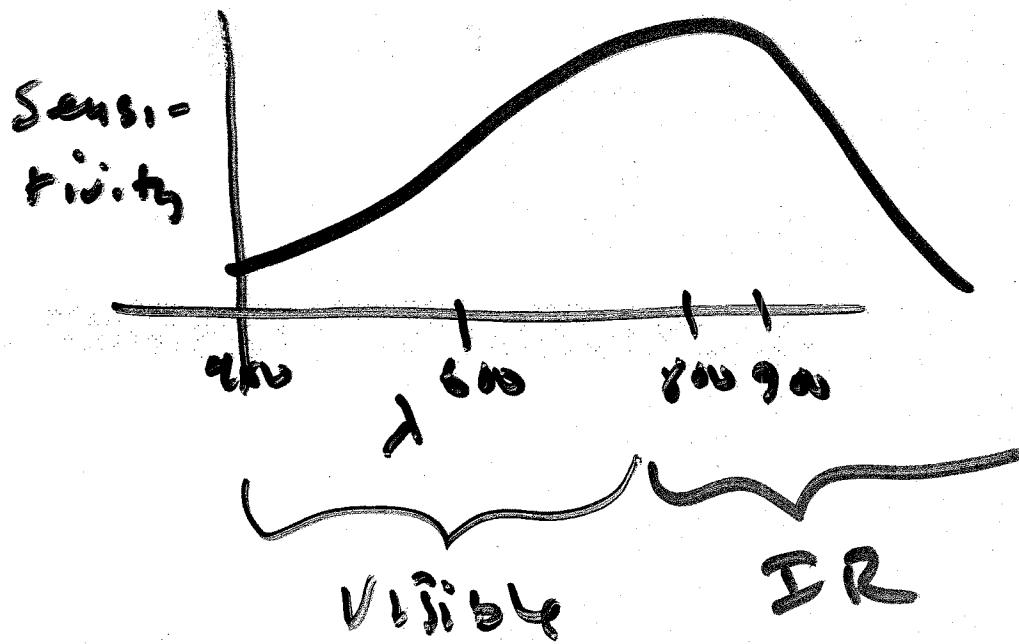
green      IR

$$R \approx 10^6 \Omega \text{ no light}$$
$$R \approx 10^2 \Omega \text{ light.}$$

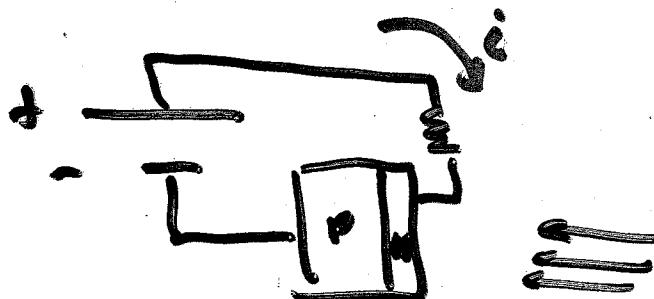
- TAKE a few ms to respond, minutes to return to normal.



# PHOTO DIODES (PN Junction).



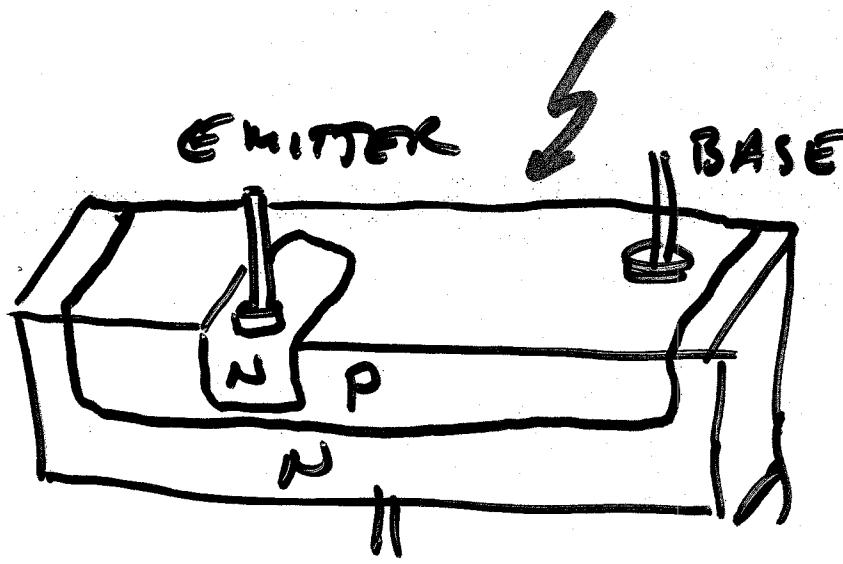
- PHOTOVOLTAIC  
Illumination  $\rightarrow$  current source
- PHOTO CONDUCTIVE  
Illumination ~~is~~ overcomes  
reverse-bias, current flows.  
Dark  $\rightarrow$  "Dark Current"



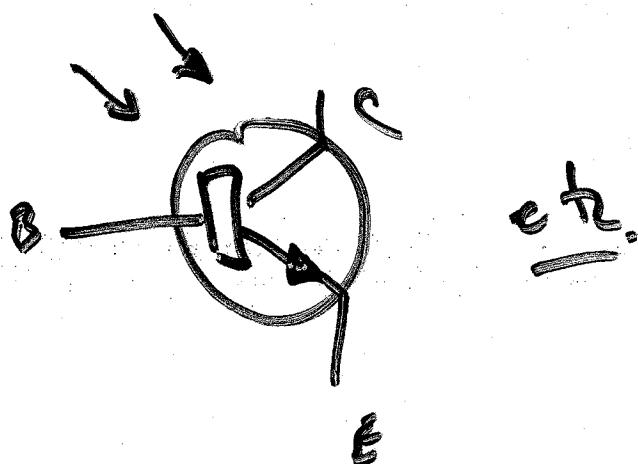
TH

# PHOTO TRANSISTORS

All Transistors are light-sensitive.



LIGHT PHOTONS  
REPLACE THE  
BASE-EMITTER  
CURRENT, SO  
TRANSISTOR IS  
AMPLIFYING  
LIGHT VARIATION



• PHOTO VARYING TUNES

2nd Transistor for

MORE AMPLIFICATION