## CSC2/458 Parallel and Distributed Systems Parallel Data Structures - III

Sreepathi Pai March 1, 2018

URCS

Some Non-Blocking Data Structures

Some Non-Blocking Data Structures

Handout: Pg 126 of MLS

- Enqueue
  - Prev tail node  $T \rightarrow next$  points to new node N
  - Tail pointer points to node N
- Dequeue (if queue is empty)
  - Returns empty
- Dequeue (if queue is not empty)
  - Returns node *H* pointed to by head
  - New head points to node in H > next

In enqueue:

- CAS1: if CAS(&t.p->next) ...
- CAS2: (void) CAS(&tail, t, <n.p, t.c+1>)
- CAS3: (void) CAS(&tail, t, <w, t.c+1>)

In dequeue

- CAS4: (void) CAS(&tail, t, <n.p, t.c+1>)
- CAS5: (void) if CAS(&head, h, <n.p, h.c+1>)
- Which of these CASes enforce the semantics?
- Which are the linearization points?

```
• new in enqueue
```

- Why the fence(W||W)?
- free\_for\_reuse in dequeue
  - What is this?
  - Could we not simply:

```
rtn := n.p->val.load()
if CAS(&head, h, <n.p, h.c+1>)
    fence(W||W)
    free(h.p)
    break
```

How do we prevent premature reclamation of allocated data?

• while somebody is holding a reference to it?

- No way to theoretically model the performance of these concurrent data structures yet.
  - in advance
- Run microbenchmarks on concurrent data structures
  - measure throughput